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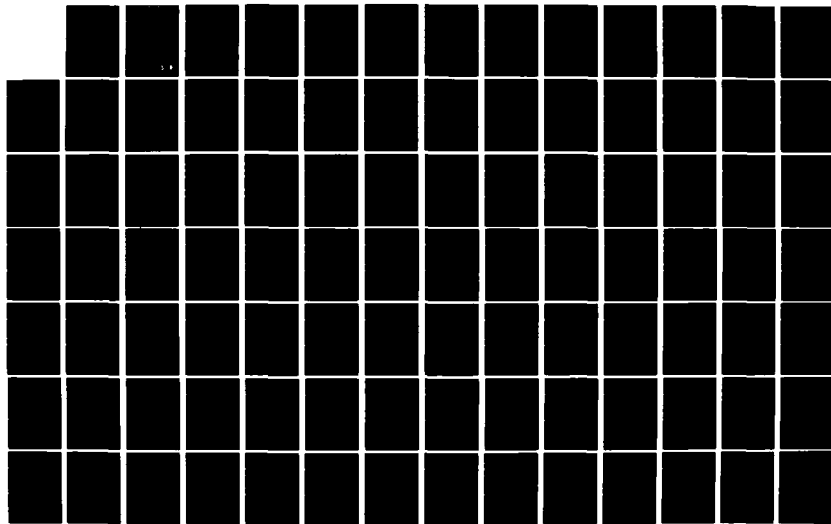
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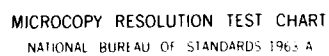
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"EFFICIENT ALGORITHM FOR FUZZY LINEAR PROGRAMMING WITH
MULTIPLE OBJECTIVES".

Final Technical Report

by

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October 1984

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London England

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Abstract

Linear Programming as an aid to solve certain types of decision problems with many decision variables and many constraints has proofed its power already in the military as well as in the civilian area. Efficient algorithms have been developed and are available as computer programs.

In two aspects, however, these algorithms have not yet been advanced satisfactorily :

1. Most of the algorithms can only accomodate one decision criterion (one objective function).
2. Objectives and constraints usually have to be formulated "crisply" i.e. the objective normally is to be maximized or minimized and the constraints divide decision alternatives into feasible and nonfeasible ones without taking into consideration that in human decision making there are "grey zones".

In 1965 L.A. Zadeh (Berkeley/USA) suggested the "Theory of Fuzzy Sets" to cope with vagueness of reality when modelling it as mathematical models. 1972 fuzzy decisions were defined by Bellman and Zadeh as the intersection of fuzzy sets representing not crisply defined objectives and constraints which are not of the yes-no or black-white type.

In the meantime fuzzy linear programming has been introduced and the application of fuzzy linear programming to problems with multiple objectives and fuzzy and crisp constraints was suggested. Here "fuzzy" can either be interpreted as "not crisp" or as "flexibility providing"

To make these promising approaches useful for the solution of large problems of this type the existing models have been advanced in the following directions:

1. Realistic and empirically tested membership functions are integrated into fuzzy programming models.
2. Adequate connectives for human decision making have been included into these models.
3. An interactive decision support system for decisions with multiple (fuzzy) objectives and crisp and fuzzy constraints has been developed which is user-oriented enough to be accepted by decision makers.

Keywords :

Decision Support System, Fuzzy Linear Programming, Multi Criteria Optimization, Interactive Decision Making.

I. Statement of the problem

Linear Programming as an aid to solve certain types of decision problems with many decision variables and many constraints has proofed its power already in the military as well as in the civilian area. Efficient algorithms have been developed and are available as computer programs.

In two aspects, however, these algorithms have not yet been advanced satisfactorily:

1. Most of the algorithms can only accommodate one decision criterion (one objective function).

It has become a generally accepted fact that in many instances many decision criteria need to be considered. Two types of approaches have been suggested so far to cope with this problem: Global Methods (Goal Programming, Utility Models) and Interactive Models.

The former generally demand more information from the decision-maker than he is able to provide, the latter are generally too inefficient computationally to be used for large problems.

2. Objectives and constraints usually have to be formulated "crisply", i.e. the objective normally is to be maximized or minimized and the constraints divide decision alternatives into feasible and nonfeasible ones without taking into consideration that in human decision making there are "grey zones". In other words a model which is based on traditional, dichotomous, two valued logic cannot model human decision problems properly since reality is not dichotomous but rather of the "more or less type". Thus, problems are frequently modelled in a way such that they are computationally solvable but not such that they describe the real problem properly.

In 1965 L.A. Zadeh (Berkeley/USA) suggested the "Theory of Fuzzy Sets" to cope with vagueness of reality when modelling it as mathematical models. 1972 fuzzy decisions were defined by Bellman and Zadeh as the intersection of fuzzy sets representing not crisply defined objectives and constraints which are not of the yes-no or black-white type.

In the meantime fuzzy linear programming has been introduced and the application of fuzzy linear programming to problems with multiple objectives and fuzzy and crisp constraints was suggested.

To make these promising approaches useful for the solution of large problems of this type the existing models have been advanced in the following directions:

1. Realistic and empirically tested membership functions are integrated into fuzzy programming models.
2. Adequate connectives for human decision making have been included into these models.
3. An interactive decision support system for decisions with multiple (fuzzy) objectives and crisp and fuzzy constraints has been developed which is user-oriented enough to be accepted by decision makers.
4. This system has to be programmed and tested such that it can also be used for large decision problems.

The project aims to combine and advance the results which have already been achieved by a team of mathematicians, management scientists, computer scientists, and psychologists in Aachen during the last 4 years for the development of a system including the above mentioned four properties.

II. Basic Theory

1. Historical Background

(Basic Theory of Fuzzy Sets)

The use of mathematical models and methods in order to gain more insight into the functioning of complex systems and in order to find optimal solutions to problems has been steadily increasing in the past. Even though considerable successes could be achieved by this approach certain limitations became more and more obvious when moving into the areas of human systems and decision-making where the systems to be modelled are very complex. Two of the major reasons for this are :

1. A major part of classical mathematics is based on "crisp", two valued logic, i.e. assuming that certain facts or relations are either true or not true. In human life i.e. whenever human value judgements play an important role, situations can often not be reduced to that type of structure.
2. As we try to tackle more and more complex systems we find that an adequately detailed mathematical model of the problem situation cannot be constructed without losing the main advantages of mathematical models.

A person which is faced with a problem of the type described above has essentially 5 possible ways of proceeding:

1. He can request that the poser of the problem formulates his problem in a way suitable for mathematical modelling.
(In most cases the problem poser will not be able or willing to do this!)

2. The model builder can try to design a mathematical model which approximates the real problem. This, however, enhances the danger that the model is too much influenced by existing known mathematical methods and models available to the model builder and too little by the problem itself. Thus the modelled problem might be solved but not the real one.
3. All persons concerned might be content with a model, which by use of a living language describes well the problem situation but which is not suitable for mathematical description or solution. Two consequences might result:
 - (a) Since our day-to-day languages are not unequivocal the model might be ambiguous, and dangerous misinterpretations might be possible.
 - (b) Solutions arrived at from such a model will presumably not be too informative to the decisionmaker or even not helpful at all.
4. Use "subjective probabilities" to express the fuzziness of the respective components of the system i.e. work with an axiomatic system designed for stochastic systems and not for fuzzy systems.
5. The expert might eventually use the terminology of the theory of fuzzy sets to describe the problem situation and fuzzy calculus in order to find optimal solutions to the problem which are more informative than the solutions mentioned under 3..

It is essential to realize the basic difference in vagueness between "Fuzziness" and "Probabilistics". While a statement such as: "The chances of horse A winning the race are .5 and that horse B will win are .4" is probabilistic in nature, the statements: "I like all goodlooking girls" or "We have to achieve satisfactory profits" have a "fuzzy" meaning. The nature of "probabilistic" information is different from the nature of fuzzy information and so are the axiomatic systems for probability theory and the theory of fuzzy sets.

L.A. Zadeh suggested in 1965 (Zadeh 1965) the notion of a fuzzy set and the basic theory of fuzzy sets essentially as the link between vague real phenomena and their adequate mathematical modelling. He defines a fuzzy set as follows :

Definition: If $X = \{x\}$ is a collection of objects denoted generically by x then a fuzzy set A in X is a set of ordered pairs.

$$(1) \quad A = \{(x, \mu_A(x)) , x \in X \}$$

$\mu_A(x)$ is called the membership function or grade of membership¹⁾ of x in A which maps X to the membership-space M . (When M contains only the two points 0 and 1, A is nonfuzzy and $\mu_A(x)$ is identical to the characteristic function of a nonfuzzy set).

$\mu(\cdot)$ is a function the range of which is a subset of the nonnegative real numbers and has the property that the supremum of this set is finite.

Decisions in Fuzzy Environments

In conventional nonfuzzy decisionmaking under certainty we are used to thinking of a decision as consisting of

- (a) a set of possible activities (decision variables),
- (b) a set of constraints limiting the choice between the alternatives (solution space) and
- (c) the objective function which assigns a "value" to each result due to a certain choice of activities according to their "desirability". The optimal decision is then the selection of the activity with the highest "desirability" (for instance the alternative which results in minimum cost, maximum profit etc.).

¹⁾ also degree of compatibility or degree of truth

In a fuzzy environment this picture of a decision has to be revised: The fuzzy objective function is characterized by its membership function, so are the constraints. Since we want to satisfy (optimize) the objective function as well as the constraints, a decision in a fuzzy environment is defined in analogy to nonfuzzy environments as the selection of activities which simultaneously satisfy objective function(s) and constraints.

Bellman and Zadeh (Bellman, Zadeh 1970) assumed the logical "and" to correspond to the intersection of the sets to be "merged" and therefore defined a "fuzzy decision" as the intersection of fuzzy constraints and fuzzy objective function(s). The relationship between constraints and objective functions in a fuzzy environment are therefore fully symmetric, i.e. there is no longer a difference between the former and latter. This can be illustrated by using the following example :

Example 1

Objective Function: "x should be substantially larger than 10", characterized by the membership function

$$\mu_0(x) = \begin{cases} 0, & x < 10 \\ (1+(x-10)^{-2})^{-1}, & x \geq 10 \end{cases}$$

Constraint:

"x should be in the vicinity of 11", characterized by the membership function

$$\mu_c(x) = ((1+(x-11)^4)^{-1})$$

The membership function $\mu_D(x)$ of the decision is then

$$\mu_D(x) = \mu_O(x) \wedge \mu_C(x)$$

$$\mu_D(x) = \begin{cases} \text{Min}((1+(x-10)^{-2})^{-1}, (1+(x-11)^4)^{-1}) & \text{for } x \geq 10 \\ 0 & \text{for } x < 10 \end{cases}$$

This relation is depicted in Figure 1.

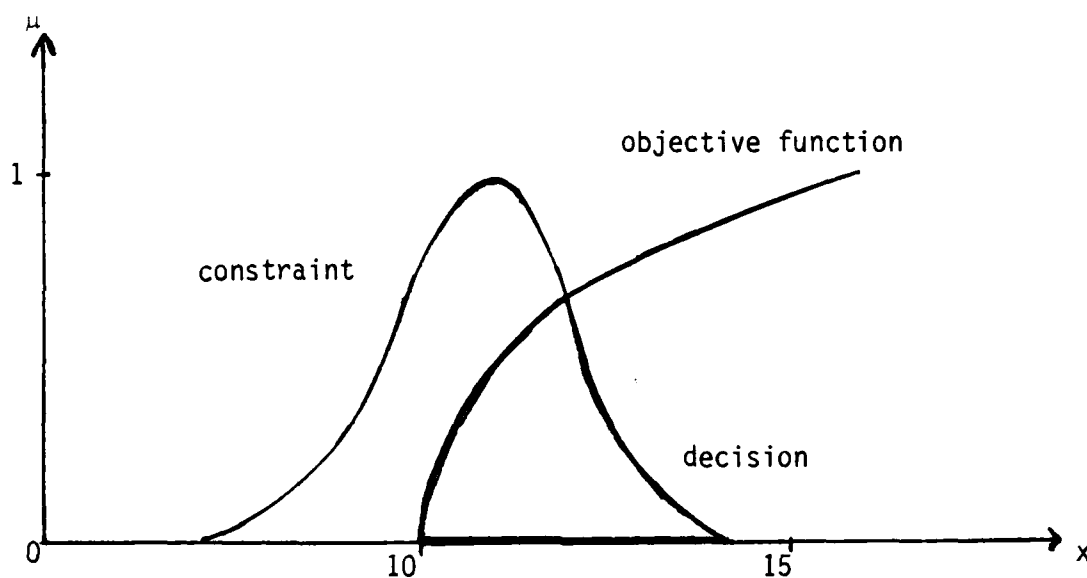


Figure 1

To single out a specific solution from the fuzzy set "decision" it is plausible to select the solution with the highest degree of membership.

Fuzzy Linear Programming

Linear Programming Problems represent a special but very frequently occurring type of decision making.

It was therefore quite natural to apply the notion of a fuzzy decision to linear programming. Zimmermann (Zimmermann 1978) suggested a possible way of doing this which can most easily be illustrated by the following example (which stems from a real application) :

Example 2

A company wanted to decide on the size and structure of its truck fleet. Four differently sized trucks (x_1 through x_4) were considered. The objective was to minimize cost and the constraints were to supply all customers (which had a strong seasonal demand).

That meant: Certain quantities had to be moved (quantity constraint) and a minimum number of customers per day had to be contacted (routing constraint). Because of other reasons at least 6 of the smallest trucks were wanted in the fleet.

The management wanted to use quantitative analysis and agreed to the following suggested LP-approach (simplified):

$$\begin{aligned}
 \text{Min} \quad & 41,400x_1 + 44,300x_2 + 48,100x_3 + 49,100x_4 \\
 \text{s.th.} \quad & 0.84 x_1 + 1.44 x_2 + 2.16 x_3 + 2.40 x_4 \geq 170.00 \\
 & 16 x_1 + 16 x_2 + 16 x_3 + 16 x_4 \geq 1300 \\
 & x_1 \geq 6 \\
 & x_1, \dots, x_4 \geq 0
 \end{aligned}$$

With x_1, \dots, x_4 = number of trucks of sizes one through four the solution was $x_1 = 6$, $x_2 = 17.85$, $x_3 = 0$, $x_4 = 58.64$,

$$\text{Min Cost} = 3,670,850.$$

Since management felt that it was forced into giving precise constraints (because of the model) inspite of the fact that it would rather have given some intervals the following "fuzzy" approach was used:

Starting from the problem

$$\begin{aligned} \text{Min } Z &= cx \\ \text{s.th. } Ax &\leq b \\ x &\geq 0 \end{aligned} \quad (1)$$

the adopted "fuzzy" version was

$$\begin{aligned} cx &\lesssim Z \\ Ax &\lesssim b \\ x &\gtrsim 0. \end{aligned} \quad (2)$$

We now define a function $f: R^{m+1} \rightarrow [0,1]$ such that

$$f(Ax, cx) = \begin{cases} 0 & \text{if } Ax \leq b, cx \leq Z \text{ is strongly violated} \\ & \text{and} \\ 1 & \text{if } Ax \leq b \text{ and } cx \leq Z \text{ is satisfied.} \end{cases} \quad (3)$$

Using the simplest version of the function $f(Ax, cx)$ we assume it to be linear and the intersection of the (fuzzy) constraints and the (fuzzy) objective function.

$$\text{Thus } f(Ax, cx) = f(Bx) = \min_i f_i((Bx)_i), x \geq 0$$

with

$$f_i((Bx)_i) = \begin{cases} 1 & \text{for } (Bx)_i \leq b_i \\ 1 - \frac{Bx_i - b_i}{d_i} & \text{for } b_i < Bx_i \leq b_i + d_i \\ 0 & \text{for } (Bx)_i > b_i + d_i \end{cases} \quad (4)$$

where d_i = subjectively chosen constants of admissible violations of the constraints.

$$\min_i f_i((Bx)_i) \text{ is the membership function of the "fuzzy decision"} \quad (5)$$

$$\text{and } \max_{x \geq 0} \min_i f_i((Bx)_i) \text{ the decision with the highest degree of membership.} \quad (6)$$

$$\begin{aligned} \text{Substituting } b'_i &= \frac{b_i}{d_i} \\ Bx'_i &= \frac{Bx_i}{d_i} \quad \text{componentwise} \end{aligned}$$

and simplifying problem (4) by dropping the "1" (which does not change the problem!) we arrive at the following problem:

$$\max_{x \geq 0} \min_i (b'_i - (Bx)_i) \quad (7)$$

or

$$\max_{x \geq 0} \mu_D(x)$$

As it is wellknown, problem (7) is equivalent to solving the following LP:

$$\begin{aligned} \max \quad & \lambda \\ \text{s.t.} \quad & \lambda \leq b_i - (Bx)_i, \quad i = 0(1)m \\ & x \geq 0 \end{aligned} \quad (8)$$

The optimal solution to (8) is also the optimal solution to (7).

The following assumptions were made

- (1) Total cost should not rise above 4.200,000 (budget limit).
- (2) The "unfuzzy" constraints are minimum requirements and management would feel much better if there was some "leeway".
- (3) The linear approximations of the membership functions are acceptable.
- (4) There are no interdependencies between the constraints.
- (5) Weighting of the constraints is taken care of by defining the d_i .
- (6) The min-operator is the applicable connective.

The theory of fuzzy linear programming has been advanced in the meantime (Hamacher, Leberling, Zimmermann 1978; Rödder, Zimmermann 1980) and fuzzy linear programming has also been applied to a number of problems (for instance Wiedey, Zimmermann 1978; Zimmermann 1980)

Decision Making in Fuzzy Environments and with Multiple Criteria

Even though Kuhn and Tucker mentioned the "Vector Maximum Problem" already in their publication Nonlinear Programming (Kuhn, Tucker 1951) in 1951, practitioners and the scientific community have only become conscious of the importance of decision-making models which take into consideration several decision criteria since the beginning of the 1970's. Since then a very large number of publications in this area has appeared and the problem can still not be considered as satisfactorily solved. (For a good survey of the State-of-the-Art see for instance (Starr, Zeleny 1977)).

The application of fuzzy linear programming to this problem was first suggested by Zimmermann in 1978 (Zimmermann 1978). This approach seems quite efficient and appropriate.

It lacks, however, in two aspects:

1. It is based on some restrictive assumptions such as linear membership functions, use of the minimum operator.
2. It is a "global model" in the sense that it demands all relevant information from the decision maker before the solution of the problems. (I.e. it assumes that the "pessimistic solution" and the "individual optima" determine the aspiration levels of the decision-maker.) (Thole, Zimmermann, Zysno 1979, Zimmermann, Zysno 1980)

With respect to the first aspect empirical research in Aachen

has shown that human decision-makers do not always use the minimum operator but rather operators which allow some degree of compensation. The minimum operator seems to be appropriate for the constraints but not for the combination of the objective functions. The use of other operators (such as suggested in the above references) will result, however, in nonlinear programming models if no appropriate substitutions can be found.

The shape of the membership functions was the subject of an empirical project (financed by the Deutsche Forschungsgemeinschaft) which was completed in 1982.

With respect to the second aspect it seems advisable to develop an interactive model which allows the decision-maker to communicate with the model and to use the "pessimistic" and "optimistic" solutions only as a basis for departure and to approach the "optimal" compromise solution by learning from the model and adapting his aspiration levels accordingly.

2. Decision Processes

In section II.1 a decision was interpreted as "finding an optimal solution".

This, however, is not the only possible interpretation. Some authors (and practitioners) call situations in which "projects" are evaluated and in which "measures of effectiveness" are determined also decisions.

If a number of alternatives (alternative actions or projects) are ranked as to their desirability this is also often called a decision.

Thus a kind of hierarchy of "decisions" can be formulated :

degree of Optimization ↓	solution space $\rightarrow R^n$		Funct. S	
	discrete	cont.		
Evaluation	1	2	3	
Ranking	4		5	
Partial Optimization	6	7		
Optimization	8	9		

All these (crisp) notions of a decision are non-symmetrical in the sense that the "constraints" or "number of feasible solutions" play a different role than the objective- or utility function.

The concept of a "fuzzy decision" (Bellman, Zadeh 1970) is symmetrical.

This concept was used when designing "fuzzy linear programming" such as described in the last section. This notion is static in the sense that it assumes that "a decision" happens at a point in time. Real decisions, however, are processes which occur over time and which correspond to hierarchies rather than to static models.

It is therefore meaningful to extend the Bellman-Zadeh concept to multi-stage decision processes as follows :

Our paradigm assumes that people either learn or generate "evaluative concepts" or "subjective categories". These terms refer to two sides of one coin : The first refers to the intensional aspects of a set which can be described by a list of attributes and the second stresses the accumulation of objects (extensional aspect of a set). We assume that human beings have such concepts or categories at their disposition and that they can relate them to each other.

Attributes constituting a concept may be interpreted other than psychologically. They can be replaced by any mental information unit, for instance, the status of neutral elements or the adjectives of a language. The relationships may actually be modelled by operators, connectives, rules, or others.

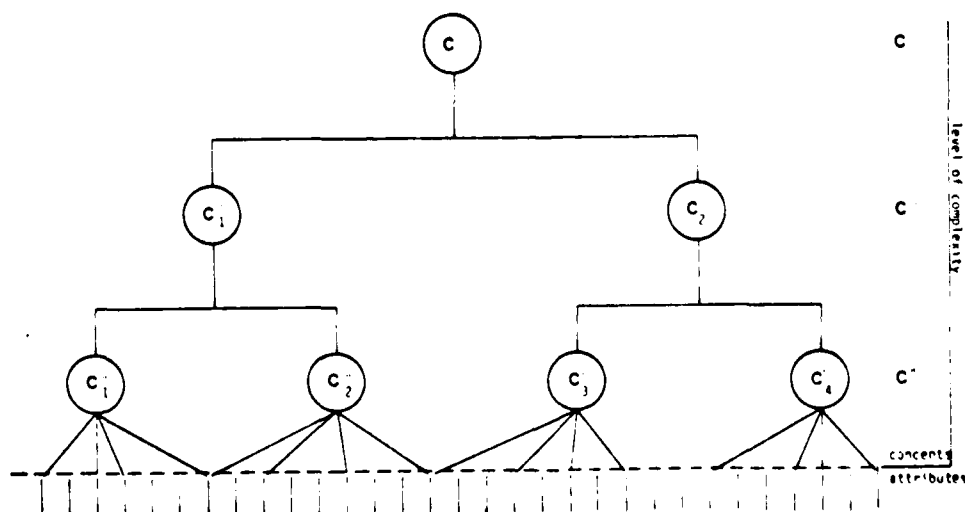


Fig 2 Hierarchy of concepts/categories

For our purposes we will limit considerations to a specific type of amalgamation : We assume a hierarchy of concepts in which there are several levels of complexity. (Fig. 2)

The bottom level contains basic concepts which can stepwise be aggregated until the top concept of the hierarchy is attained. (A more detailed description is given in (Zimmermann, Zysno 1983)).

For reasons of practical relevance of the model we shall allow that

- (a) the subcategories are of unequal importance for the respective super category.
- (b) the description of categories of each level may partly contain the same attributes.

III. Developments, Results and Conclusions

III.1 Membership Functions

Types of functions

Different types of functions can be chosen to express the membership values of elements to a fuzzy set. They mainly differ with respect to their mathematical properties and their empirical fit. We shall first discuss some membership functions introduced in fuzzy sets literature.

The membership function proposed first in connection with mathematical modeling is the linear one (e.g. Zimmermann, 1978). It is uniquely defined by the two values \underline{c} and \bar{c} which have to be provided by a decision maker :

$$\mu(x) = \begin{cases} 0 & x \leq \underline{c} \\ \frac{x - \underline{c}}{\bar{c} - \underline{c}} & \underline{c} < x \leq \bar{c} \\ 1 & x \geq \bar{c} \end{cases} \quad (9)$$

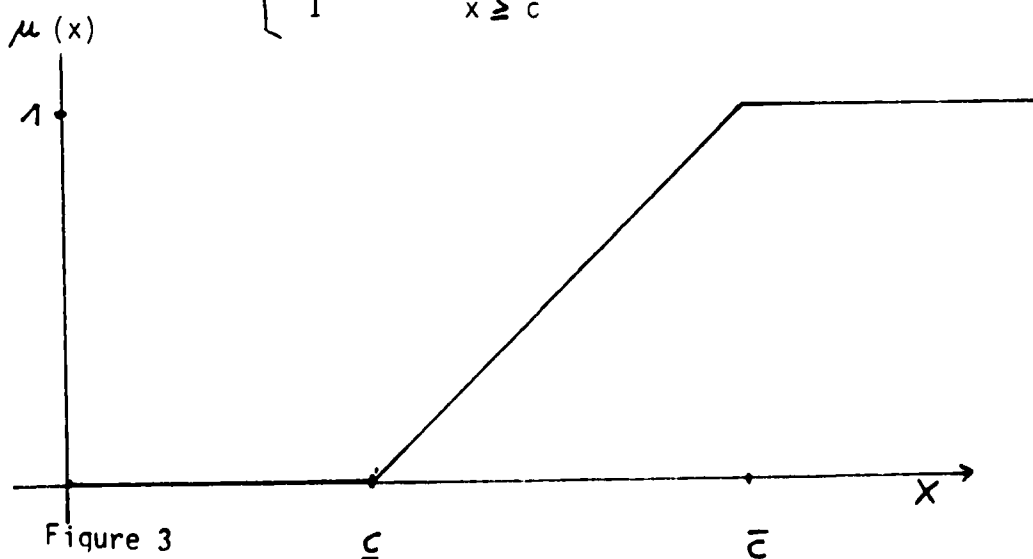


Figure 3

The advantage of the linear function is its good behaviour in linear models. Each function can more or less be approximated by a linear or a piecewise linear function.

Empirical research (e.g. Hersh, Caramazza 1976), however, shows that s-shaped functions model human behaviour much better. Hence mathematical models of such functions are introduced in fuzzy set literature. For example the logistic function proposed by Zimmermann, Zysno (1984).

$$\mu(x) = \frac{1}{1 + e^{-a(x-b)}} \quad (10)$$

This function is uniquely defined by the slope a and the inflection point b .

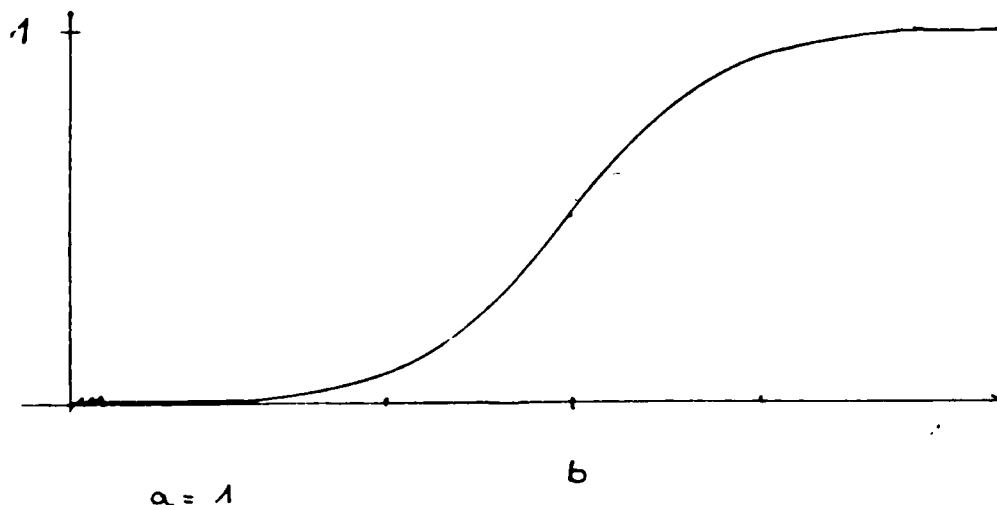


Figure 4

A hyperbolic membership function is proposed by Leberling (1981)

$$\mu_H(x) = \frac{1}{2} \frac{e^{(x-(\bar{c} + \underline{c})/2)\alpha} - e^{-(x-(\bar{c} + \underline{c})/2)\alpha}}{e^{(x-(\bar{c} + \underline{c})/2)\alpha} + e^{-(x-(\bar{c} + \underline{c})/2)\alpha}} \quad (11)$$

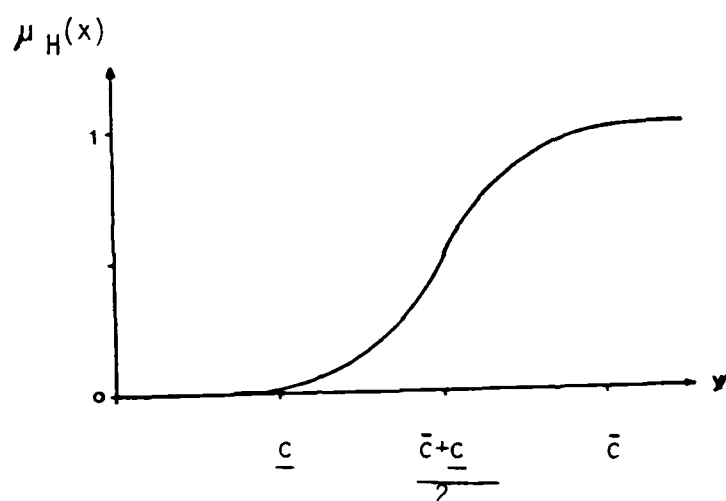


Figure 5

A cubic spline function is deduced by Schwab (1983), here in a cut version :

$$\mu_S(x) = \begin{cases} 1 & \text{für } x \leq x_m \\ ax^3 + bx^2 + cx + d & \text{für } x_m \leq x \leq x_D \\ ex^3 + fx^2 + gx + h & \text{für } x_D \leq x \leq x_0 \\ 0 & \text{für } x_0 \leq x \end{cases} \quad (12)$$

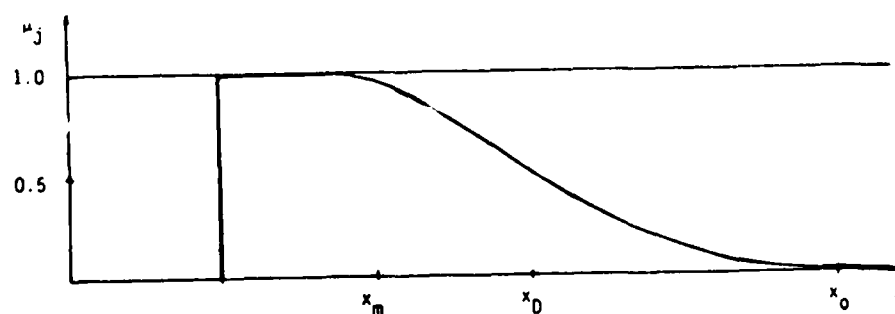


Figure 6

It can be shown that hyperbolic membership function and logistic membership function are isomorphic mathematical models. By choosing appropriate parameters a , b , and \bar{c} , \underline{c} , α respectively the resulting membership functions are equal.

Determining a cubic spline function many different values, a , b , c , e , f , g , h have to be provided by the decision maker or to be observed empirically. Hence the two most promising membership functions in mathematical modeling are the linear and logistic one which are considered in the following. The linear can be determined easily and can be handled efficiently. The logistic function can also be determined easily and its fit to human behaviour is better. Some empirical investigations have been performed to further improve the fit.

Measurement

Measurement means assigning numbers to objects, such that certain relations between numbers reflect analogous relations between objects (Campbell 1938). With other words measurement is the mapping of object relations into numerical relations of the same type.

If it is possible to prove that there is a homomorphic mapping $f : E \rightarrow A$ from an empirical relational structure $\langle E, P_1, \dots, P_n \rangle$ with a set of objects E and n -tuple of relations P_i into a numerical relational structure $\langle N, Q_1, \dots, Q_n \rangle$ with a set of numbers N and relations Q_i , then a scale $\langle\langle E, N, f \rangle\rangle$ exists. By specifying the admissible transformations the grade of uniqueness is determined.

Therefore, measurement starts by formulating the properties of the empirical structure; implicitly the intended object space is modelled

on a non-numerical level. Strictly speaking at the very beginning there should be a semantic definition of the central concepts, which would considerably facilitate the consistent use of the relevant principles. This has not yet been possible for the concept of membership. Membership has a clear cut formal definition. However, apart from first steps by Norwich and Turksen (1984) genuine measurement structures have not yet been developed.

Under these circumstances one could wait and see, until a satisfactory definition is available. However, one should remember that up to the beginning of the 20th century even in the "hard sciences" measures were used without being equipped with adequate measurement theories. Usually measurement tools were used, which were based on not much more but plausible reasons. Nevertheless, the success of the natural sciences is undoubted. Hence, for the purpose of empirical research it may be tolerable to use plausible techniques.

As the base variable provides a good deal of control with respect to judgmental errors of the subjects we used direct scaling methods. This involves less effort in data collection. In order to express this possibly lower level of aspiration we call this scale an "evaluative" scale.

Model

The judgment (valuation) of membership can be regarded as the comparison of object x with a standard (ideal) which results in a distance $d(x)$. If the object has all the features of the standard the distance shall be zero, if no similarity between standard and object exists, the distance shall be " ∞ ". If the evaluation concept is represented formally by a fuzzy set $\tilde{P} \subseteq X$, then a certain degree of membership $\mu_{\tilde{P}}(x)$ is assigned to each element x . In the following as a matter of convenience we will denote the degree of membership, $\mu_{\tilde{P}}(x)$, simply by μ .

$$\mu = \frac{1}{1+d(x)} \quad (13)$$

Membership is defined as a function of the distance $d(x)$ between a given object x and a standard (ideal). Hence :

$d(x) = 0 \rightarrow \mu = 1$; $d(1) = \infty \rightarrow \mu = 0$. Equation (13) is only a transformation rule from one numerical relative into another : real numbers R are mapped into the interval $[0,1]$.

The distance function now has to be specified. A specific monotonic function of the similarity with the ideal could as a first approximation be $d'(x) = 1/x$.

Experience shows, however, that ideals are very rarely ever fully realized. As an aid to determine the relative position very often a context dependent standard b is created. It facilitates a fast and rough preevaluation such as "rather positive", "rather negative" etc. As another context dependent parameter we can use the evaluation unit a , similar to unit of length such as feet, meters, yards etc. If one realizes furthermore that the relationship between physical unit and perceptions is generally exponential (Helson 1964), then the following distance function seems appropriate :

$$d(x) = \frac{1}{e^{a(x-b)}} \quad (14)$$

Substituting (14) into (13) yields the logistic function

$$\mu = \frac{1}{1+e^{-a(x-b)}} \quad (15)$$

It is S-shaped such as demanded by several authors (Goguen 1969; Zadeh 1971). Formally b is the inflexion point and a is the slope of the function.

From the point of view of linear programming (15) has the additional advantage, that it can easily be linearized by the following transformation :

$$-\ln \frac{1-\mu}{\mu} = \ln \frac{\mu}{1-\mu} = a(x-b). \quad (16)$$

The parameters a and b will have to be interpreted differently depending on the situation which is modelled. From a linguistic point of view a and b can be considered as semantic parameters.

Since concepts or categories, which are formally represented by sets, are normally linguistically described, the membership function is the formal representation of meaning. The vagueness of the concept is operationalized by the slope a and the identification threshold by b . For managerial terms such as "appropriate dividend" or "good utilization of capacities" a models the slope of the membership function in the tolerance interval and b represents the turning point from rather positive onto rather negative tolerance.

Model (15), however, is still too general to fit subjective models of different persons. Frequently only a certain part of the logistic function is needed to represent a perceived situation. This is also true for measuring devices such as scales, thermometers etc. which are designed for specific measuring areas only.

In order to allow for such a calibration of our model we assume that only a certain interval of the physical scale is mapped into the open interval $(0,1)$ (see figure 7). Whenever stimuli are smaller or equal to the lower bound or larger or equal to the upper bound the grade of membership of 0 or 1 respectively is assigned to them. This is achieved by changing the range by legitimate scale transformations such that the desired interval is mapped into $(0,1)$.

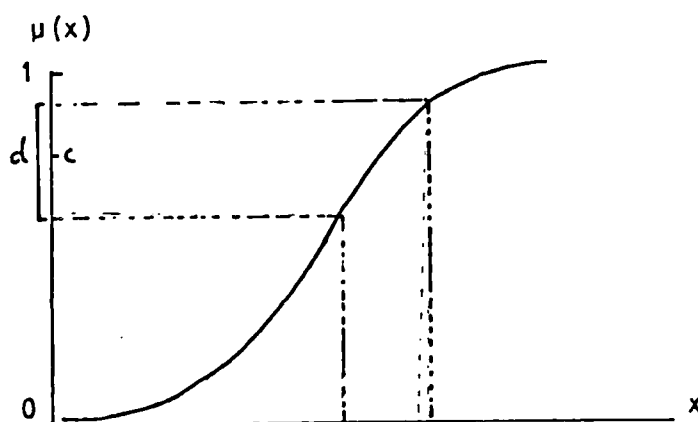


Figure 7 : Calibration of the interval for measurement

The general model of membership (15) is specific by the two parameters of calibration c and d , c representing the "neutral point" and d the actually used interval.

$$\mu_i = \left[\frac{1}{1 + e^{-a(x - b)}} - c \right] \frac{1}{d} + \frac{1}{2} \quad (17)$$

$\left[\right]$ indicates that values outside of the interval $(0,1)$ have no real meaning. The measurement instrument does not differentiate there.

Hence

$$x < \underline{x} \rightarrow \mu(x) = 0 \quad (18)$$

$$x > \bar{x} \rightarrow \mu(x) = 1 \quad (19)$$

The determination of the parameters from an empirical data base does not pose any difficulties in the general model (15).

On the basis of (16) the original membership values are transformed into y-valued :

$$y_i = \ln \frac{\mu}{1-\mu_i} \quad (20)$$

Between x and y there exists a linear relationship. The straight line of the model is then defined by the least squares of deviations.

The estimation of the parameters c and d in the extended model still poses some problems. We cannot yet suggest a direct way for a numerically optimal estimation. We can, however, suggest an iterative procedure. We assume that a set of stimuli which is equally spread over the physical continuum was chosen such that the distance between any two of the neighbouring stimuli is constant

$$x_{i+1} - x_i = s \quad (21)$$

This condition serves as a criterion for precision. If c and d are correctly estimated then those scale values x_i' are reproducible which are invariant with respect to x_i with the exception of the additive and multiplicative constant. This becomes obvious when rewriting (19) as follows :

$$\ln \frac{a(\mu_i - 1/2) + c}{1 - (d(\mu_i - 1/2) + c)} = a(x_i - b) = x_j' \quad (22)$$

Let s' be the distance between the pairs x_i' and x_{i+1}' and M' their mean value. If the estimated values \hat{d} and \hat{c} are equal to their true values then the estimated distance \hat{s}' and the mean \hat{M}' are equal to their respective true values and vice versa :

$$\hat{d} = d \wedge \hat{c} = c \iff \hat{s}' = s \wedge \hat{M}' = M. \quad (23)$$

Our aim is therefore to reach the equivalence of \hat{s}' and s and \hat{M}' and M respectively.

Using appropriate starting values c_1 and d_1 one can now determine the x_i' which corresponds to the empirically determined μ_i .
Hence

$$\hat{M}' = \frac{1}{n} \sum x_i \quad (24)$$

$$\hat{s}' = \frac{1}{n-1} \sum_{i=1}^{n-1} (x_{i+1}' - x_i') \quad (25)$$

$$= \frac{x_n - x_1}{n-1}$$

If the sums of the deviations do not exceed a certain ϵ , then the estimate is accepted as sufficiently exact :

$$|\hat{M}'' - \hat{M}'| \leq \epsilon_M \quad (26)$$

$$|\hat{s}'' - \hat{s}'| \leq \epsilon_s \quad (27)$$

If this is not the case the interval of the base variable is estimated which corresponds to the (0,1) interval of the membership values. To this end an upper bound \bar{x}' and a lower bound \underline{x}' is determined.

$$\bar{x}' = \hat{M}' + \frac{n\hat{s}'}{2} \quad (28)$$

$$\underline{x}' = \hat{M}' - \frac{n\hat{s}'}{2} \quad (29)$$

Now the corresponding \bar{u}' and \underline{u}' , respectively, are computed and new parameters \hat{c} and \hat{d} are estimated. Experience has shown that it takes usually less than 10 iterations to reproduce the values of the base variable up to an accuracy of three units behind the decimal point. As starting points we used

$$c_1 = \frac{1}{n} \sum \mu_i \quad (30)$$

$$d_1 = \min(1 - \frac{1}{k}, 2(1-c), 2c) \quad (31)$$

Where n is the number of stimuli and k is the number of different degrees of membership. If only the values 0 and 1 occur $d_1 = 1/2$.

Only the "linear" interval in the middle of the logistic function is used. With increasing k , d converges to 1, i.e. $\lim_{k \rightarrow \infty} d = 1$. The entire range of the function is used. Finally it should be mentioned that not only monotonic functions, such as discussed so far, can be described but also unimodal functions by representing them by an increasing (S_I) and a decreasing (S_D) part. Formally they can be represented as the minimum or maximum, respectively, of two monotonic membership functions each :

$$\mu_{S_I S_D}(x) = \min \left[\mu_{S_I}(x), \mu_{S_D}(x) \right] \quad (32)$$

$$\mu_{S_I S_D}(x) = \max \left[\mu_{S_I}(x), \mu_{S_D}(x) \right] \quad (33)$$

A computer program was written to process the observed data.

Empirical Evidence

64 subjects (16 for each set) from 21 to 25 years of age individually rated 52 different statements of age concerning one of the four fuzzy sets "very young man" (vym), "young man" (ym), "old man" (om) and "very" old man" (vom).

The evaluation of the data showed a good fit of the model. Figures 8 -13 show the membership functions given by six different persons. As can be seen, the concepts "vym" and "ym" are realized in the monotonic type as well as in the unimodal.

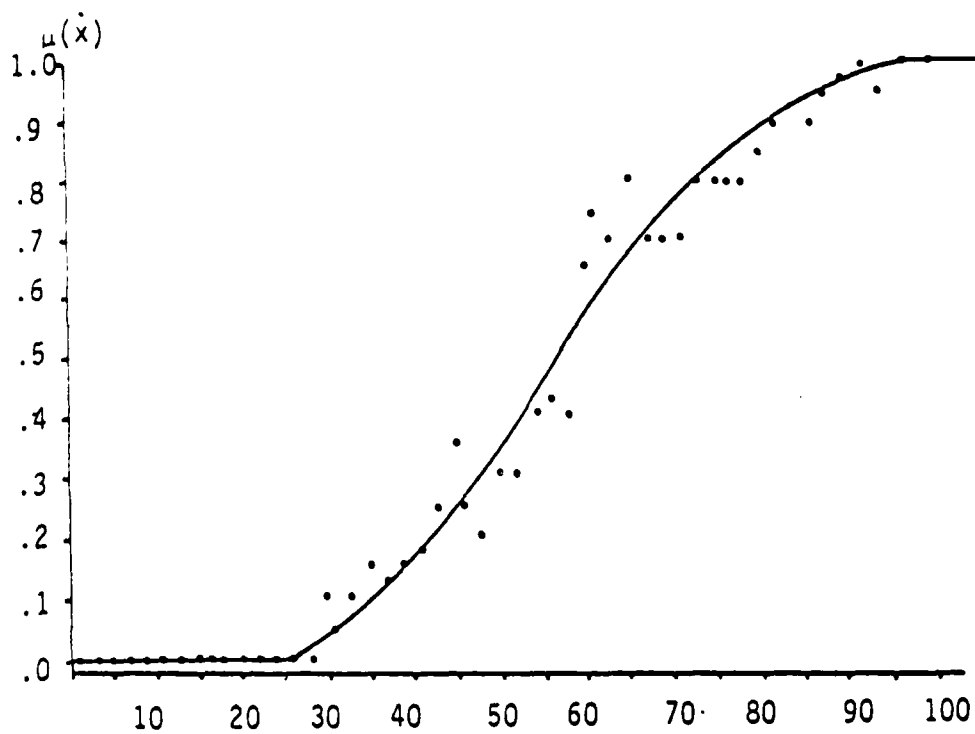


Fig. 8 : Subject 34, "old man"

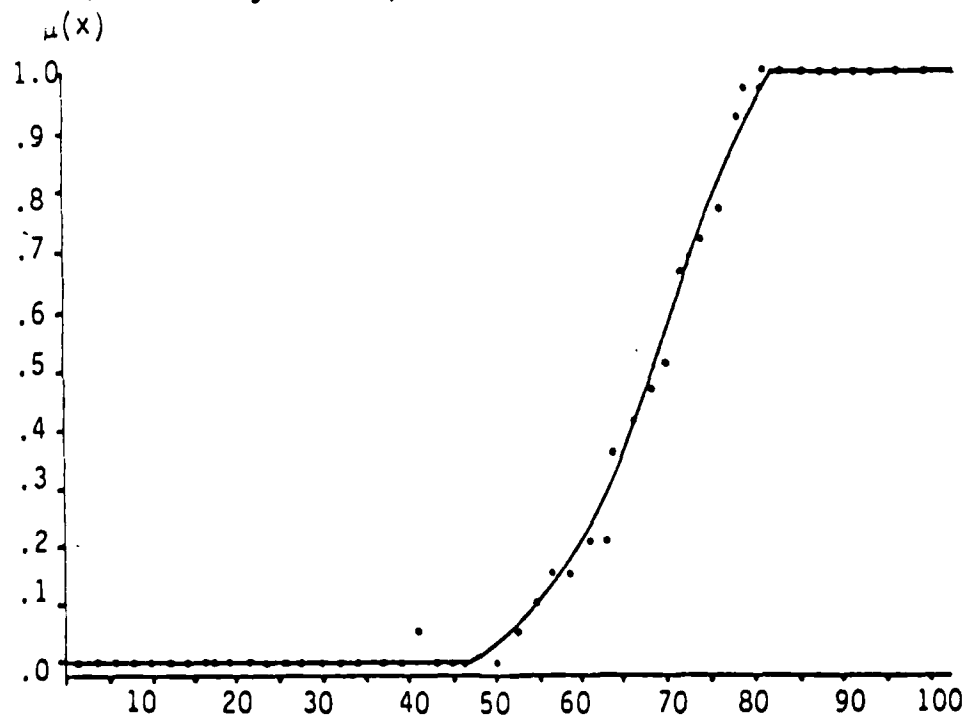


Fig. 9 : Subject 58, "very old man"

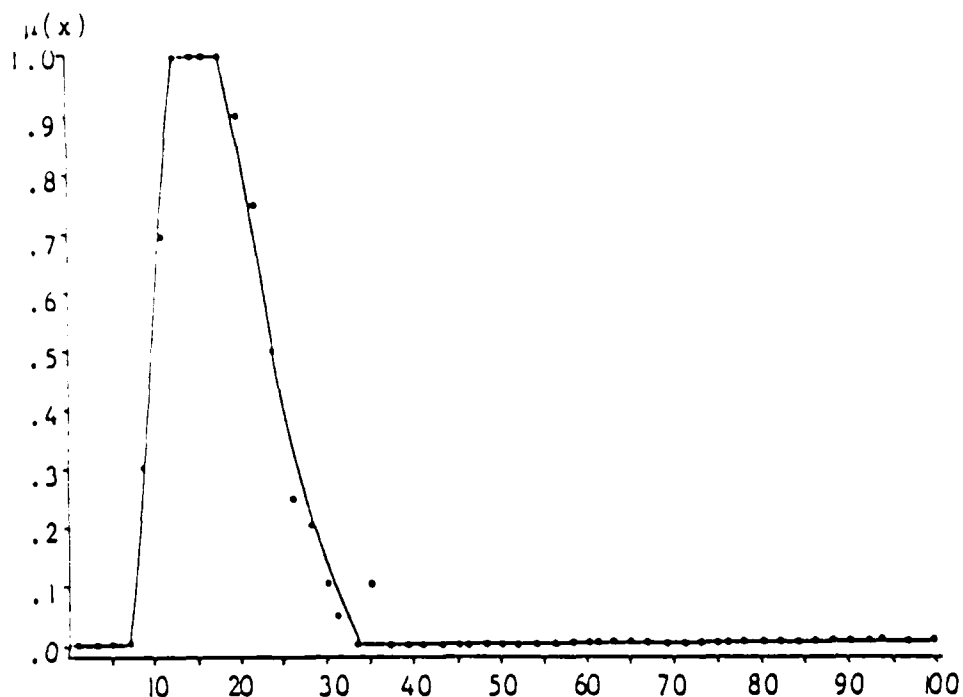


Fig. 10 : Subject 5, "very young man"

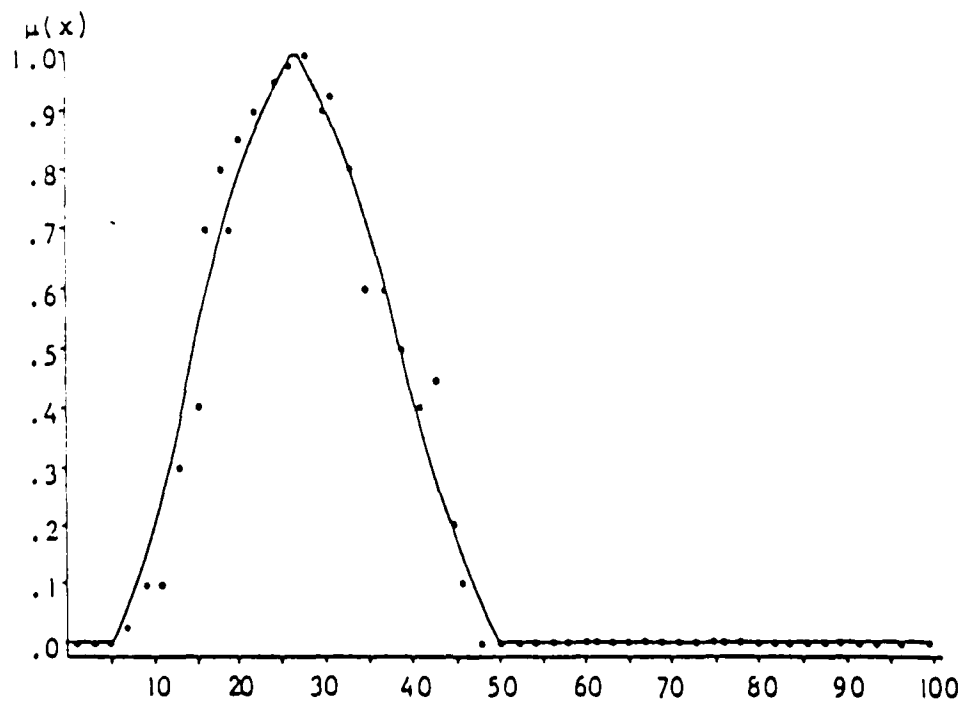


Fig. 11: Subject 17, "young man"

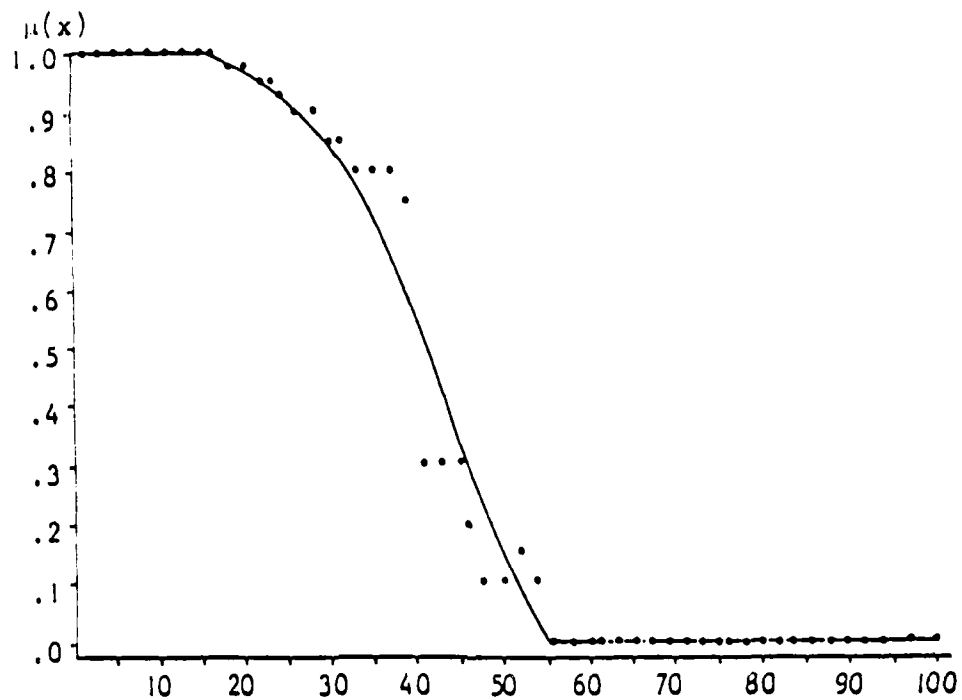


Fig. 12: Subject 15, "very young man"

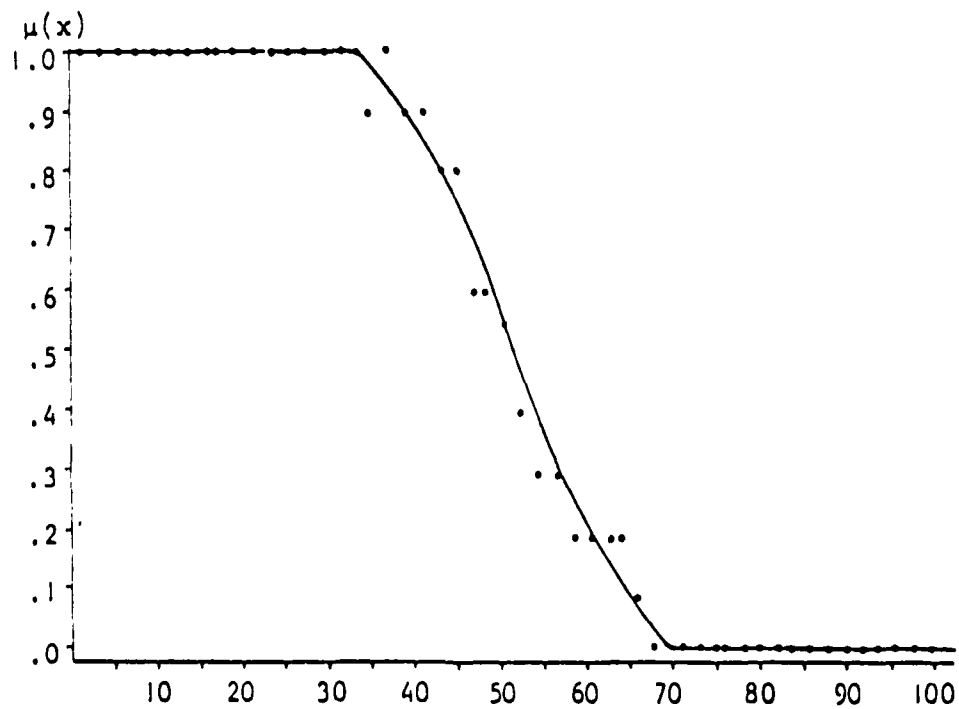


Fig. 13 : Subject 32, "young man"

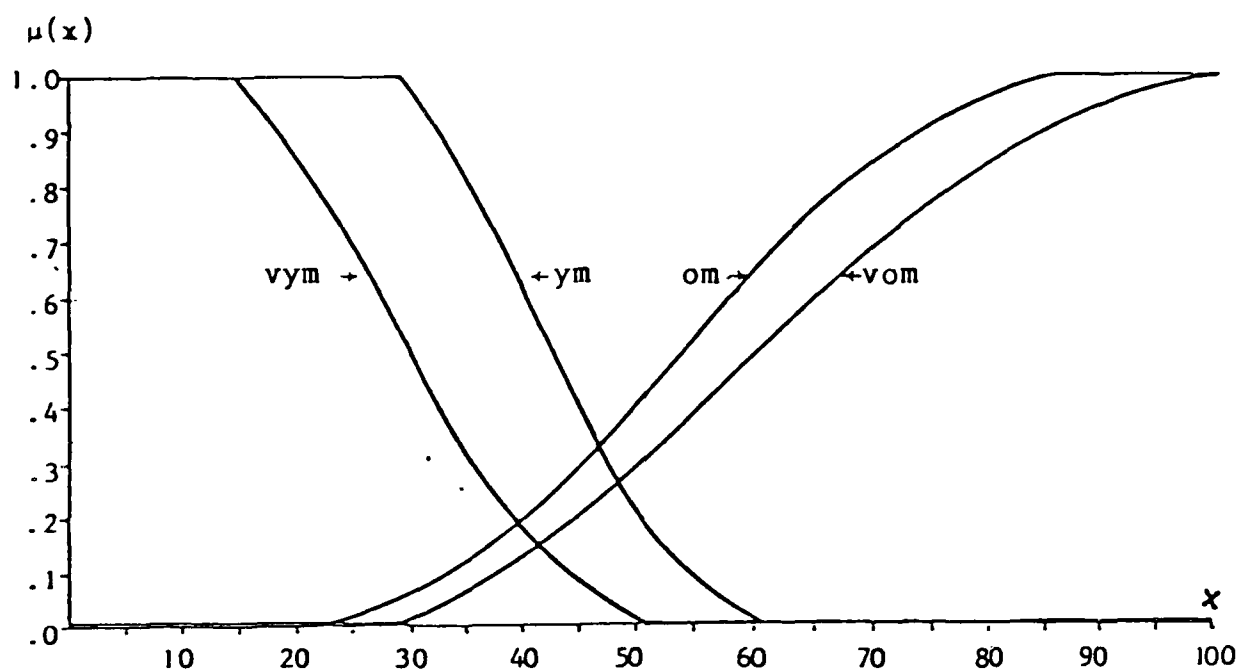


Fig. 14 : Generalized membership function (monotonic type)
 "very young man" (vym), "young man" (ym), "old man"
 (om) and "very old man" (vom)

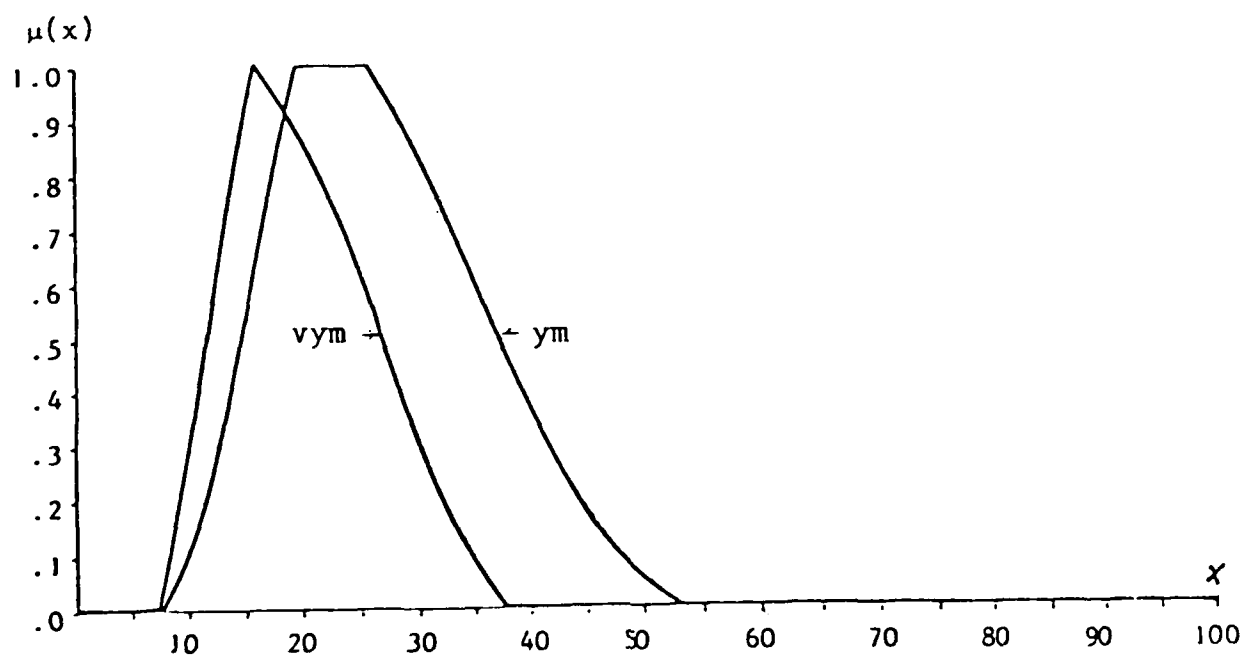


Fig. 15 : Generalized membership function (unimodal type) for
 "very young man" (vym) and "young man" (ym)

One may ask whether a general membership function for each of the four sets can be established. Even though the variety of conceptual comprehension is rather remarkable, there should be an overall membership function at least in order to have a standard of comparison for the individuals. This is achieved by determining the common parameter values a , b , d and d for each set. Obviously the general membership functions of "old man" and "very old man" (Fig. 14) are rather similar. They practically differ only with respect to their inflection points, indicating a difference of about five years between "old man". The same holds for the monotonic type (Fig. 14) of "very young man" and "young man"; Their inflection points differ by nearly 15 years. It is interesting to note that the modifier "very" has a greater effect on "young" than on "old", but in both cases it can be formally represented by a constant. Several subjects provided the unimodel type in connection with "very young" and "young". Again the functions show a striking congruency (Fig. 15).

Of the slope is an indicator for vagueness (Kochen & Badre 1973) then the meaning of "young" is less vague than that of "old". On the other hand, the variability of membership functions may be regarded as an indicator of ambiguity. Thus, though being less vague, "young" seems to be more ambiguous.

III.2. Aggregation Operators

As already mentioned in section II.1 a decision in a "fuzzy envirement" has been defined as the intersection of fuzzy sets representing either objectives or constraints. The grade of membership of an object in the intersection of two fuzzy sets, i.e. the fuzzy set "decision", was determined by use of either the min-operator or the product operator. The following example is an illustration of this :

Example 3 : The board of directors is trying to find the "optimal" dividend to be paid to the shareholders. For financial reasons it ought to be attractive and for reasons of wage negotiations it should be modest (Fig. 16).

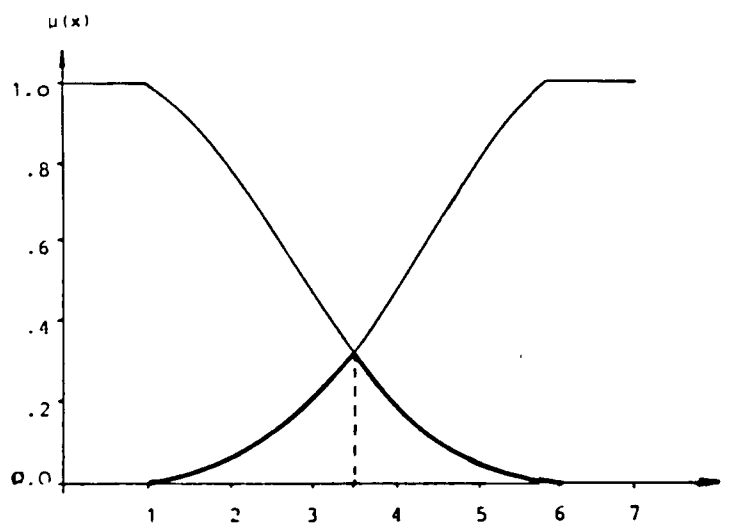


Figure 16 : fuzzy decision; x = dividend (%)

The optimal dividend to be paid to the shareholders would be 3.5%, considering the dividend with the highest degree of membership in the fuzzy set "decision" as the "most desirable".

Rather than viewing a decision as the intersection of several fuzzy sets (Thole, Zimmermann, Zysno 1979) one could describe it also as the union of all relevant fuzzy sets, using the maximum operator for aggregation :

Example 4 : An instructor at a university has to decide how to grade written test papers. Let us assume that the problem to be solved in the test was a linear programming problem and that the student was free to solve it either graphically or using the simplex method. The student has done both. The student's performance is expressed - for graphical solution as well as for the algebraic solution - as the achieved degree of membership in the fuzzy sets "good graphical solution" (G) and "good simplex solution" (S), respectively. Let us assume that he reaches

$$\mu_G = 0.9 \quad \text{and} \quad \mu_S = 0.7.$$

If the grade to be awarded by the instructor corresponds to the degree of membership of the fuzzy set "good solutions of linear programming problems" it would be quite conceivable that this grade μ_{LP} could be determined by

$$\mu_{LP} = \text{Max}(\mu_G, \mu_S) = \text{Max}(0.9, 0.7) = 0.9$$

The two definitions of decisions - as the intersection or the union of fuzzy sets - imply essentially the following :

The interpretation of a decision as the intersection of fuzzy sets implies no positive compensation (trade-off) between the degrees of membership of the fuzzy sets in question, if either the minimum or the product is used as an operator. Each of them yields degrees of membership of the resulting fuzzy set (decision) which are on or below the lowest degree of membership of all intersecting fuzzy sets (see Example 3).

The interpretation of a decision as the union of fuzzy sets, using the maxoperator, leads to the maximum degree of membership achieved by any of the fuzzy sets representing objectives or constraints. This amounts to a full compensation of lower degrees of membership by the maximum degree of membership (see Example 4).

Observing managerial decisions one finds that there are hardly any decisions with no compensation between either different degrees of goal achievement or the degrees to which restrictions are limiting the scope of decisions. The compensation, however, rarely ever seems to be "complete" such as would be assumed using the max-operator. It may be argued that compensatory tendencies in human aggregation are responsible for the failure of some classical operators (min, product, max) in empirical investigations (Hersh & Caramazza 1976; Thole, Zimmermann & Zysno 1979).

Neither the non-compensatory "and" represented by operators which map between zero and the minimum degree of membership nor the fully compensatory "or" represented by operators which map between the maximum degree of membership and 1 are appropriate to model the aggregation of fuzzy sets representing managerial decisions.

New additional operators will have to be defined which imply some degree of compensation, i.e. which map also between the minimum degree of membership and the maximum degree of membership of the aggregated sets. By contrast to modelling the non-compensatory "and" or the fully-compensatory "or" they should represent types of aggregation which we shall call "compensatory and".

It is possible that human beings use many non-verbal connectives in their thinking and reasoning. Being forced to verbalize them men possibly map the set of "merging connectives" into the set of the corresponding language connectives ("and", "or"). Hence, when talking, they use the verbal connective which they feel closest to their "real" non-verbal connective.

In analogy to the verbal connectives, the logicians defined the connectives " \wedge " and " \vee ", assigning certain properties to each of them. By this, compound sentences can be examined for their truth values. In contrary to this constructive process, the empirical researcher has to analyze a given structure.

For the generation of promising and testable models we considered the relationships between different levels of the hierarchies mentioned in Section II 2.

Intensionally, in set theory higher level concepts are defined by the union of the attributes of lower level concepts. Extensionally, however, higher level concepts equal the intersection of corresponding lower level concepts (Zysno 1980). The most popular algebraic representation of this type of aggregation is the Minimum :

$$\mu_{\theta} = \text{Min}(\mu_i) \quad (34)$$

where $\mu_i(x)$ is the grade of membership of element x to set A_i (for convenience, x and A are dropped in the formulas); $x \in X$ = Universe of realized entities; θ is the fuzzy set representing an empirical supercategory : $A_1, A_2, \dots, A_i, \dots, A_m \subset \theta \subset X$.

However, operators like this yield acceptable predictions only in very special situations. This probably is due to the tendency of man to compensate attribute deficiencies of one aspect by stressing certain attributes of another aspect.

In extremal situations complete compensation is possible; in this case the maximum operator would seem appropriate.

$$\mu_{\theta} = \text{Max}(\mu_i). \quad (35)$$

In order to model human evaluative behavior the pool of candidates to be tested should comprise such operators which work between minimum and maximum. Of course, they should also satisfy the desirable mathematical requirements of continuity, strict monotonicity, injectivity in each argument (which is implied by the presence of continuity and monotonicity), commutativity (which is implied by the presence of continuity, injectivity, and associativity (Ačzel 1961)).

Unfortunately, it is hard to find an averaging operator meeting all these requirements. Therefore, we should abandon at least one of them. Most critical seems to be the associativity as it is fulfilled by the median (Fung & Fu 1975) only. Hence we will be flexible with respect to this property.

Simple and well known operators regarding the remaining mathematical requirements are the geometric mean

$$\mu_0 = \left(\prod_{i=1}^m \mu_i \right)^{-m} \quad (36)$$

and arithmetic mean :

$$\mu_0 = \frac{1}{m} \sum_{i=1}^m \mu_i \quad (37)$$

An example aggregating two membership functions by each of the four operators is given in Figure 17.

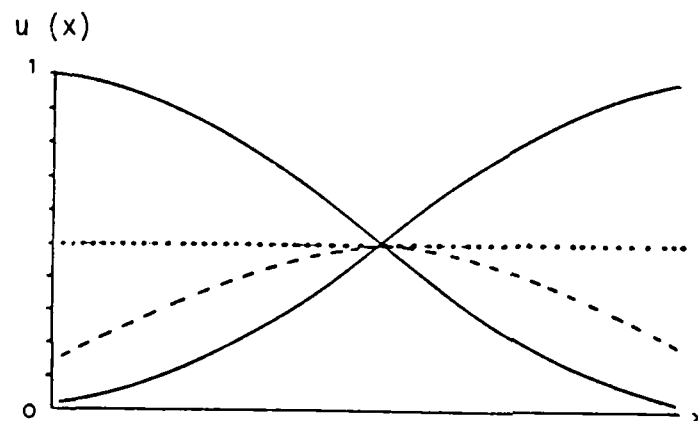


Fig. 17 : Aggregation of two membership functions by geometric (arithmetic) means as depicted by the dashed (dotted) line.

Experiments (Zimmermann & Zysno 1979, 1980, 1983) conducted in order to get empirical evidence on this problem lead to the following conclusions :

- (1) People use averaging operations when making judgments or evaluations resulting in membership values between minimum and maximum.
- (2) The geometric mean and to some extent the arithmetic mean are adequate models for human aggregation of fuzzy sets when special compensatory effects exist.
- (3) Men use still other connectives than "and" and "or".

Quite naturally, if several operators are necessary in order to describe a variety of phenomena, the question arises, how many operators are needed, as each important situation in practice would then call for an adequate model. Moreover, one would be forced to assume that man has a decision rule enabling him to choose the right connective for each situation. The pursuit of this train of thought and especially its application implies a lot of difficulties. We feel that one way to bypass these difficulties is to generalize the classical concept of connectives by introducing a parameter which may be interpreted as "grade of compensation". Each point on the continuum between "and" and "or" represents a different operator.

One way to formalize this idea is to find an algebraic representation for a weighted combination of the non-compensatory "and" and the fully compensatory "or" : The more there is a tendency for compensation the more the "or" becomes effective and vice versa.

Let X be the universe of discourse with the elements x .
 A , B and Γ are fuzzy sets in X . Then, the convex combination
of A , B and Γ can be denoted by $(A, B; \Gamma)$ and is defined either
by the relation

$$(A, B; \Gamma) = \bar{\Gamma}A + \Gamma B \quad (38a)$$

or

$$(A, B; \Gamma) = A\bar{\Gamma} \cdot B\Gamma \quad (38b)$$

where $\bar{\Gamma}$ is the complement of Γ . Written in terms of membership
functions, (38) reads

$$f_{(A,B;\Gamma)} = (1-f_{\Gamma}(x)) \cdot f_A(x) + f_{\Gamma}(x) \cdot f_B(x) \quad (39a)$$

and

$$f_{(A,B;\Gamma)} = f_A(x)^{1-f_{\Gamma}(x)} f_B(x)^{f_{\Gamma}(x)} \quad (39b)$$

A basic property of the above-defined convex combination is expressed
by :

$$A \cap B \subset (A, B; \Gamma) \subset A \cup B$$

Obviously, the convex combination is a fuzzy set between the inter-
section and the union of two fuzzy sets A and B .

one model, fulfilling the above mentioned properties and having performed as the best balanced representation so far in several experiments including practical decision situations is the so called γ - operator

$$\mu_{\theta} = \left(\prod_{i=1}^m \mu_i^{\delta_i} \right)^{1-\gamma} \left(1 - \prod_{i=1}^m (1 - \mu_i)^{\delta_i} \right)^{\gamma} \quad (40)$$

This model is a convex combination of the product and the algebraic sum, which are known as algebraic representations of the intersection and the union, respectively.

The γ - operator seems rather complicated especially for use in linear models. Thus additional compensatory operators have been considered. The convex combination of minimum and maximum operator

$$\mu_{\theta} = (1-\gamma) \min_{i=1}^m \{\mu_i\} + \gamma \max_{i=1}^m \{\mu_i\} \quad \gamma \in [0,1] \quad (41)$$

is a special case of relation in which the min-operator stands for "and" the max-operator for "or". γ again is the parameter of compensation. Using the empirical data of Zimmermann, Zysno (1983) this operator gives a rather good model for aggregation although the γ -model is better. One of its advantages is its computational simplicity. A slight disadvantage could be seen in the fact that extreme values get a higher weight and that dominated solutions cannot be recognized after aggregation.

Example :

Consider three alternatives x_1, x_2, x_3 each with membership values of

μ_1 , μ_2 and μ_3 :

	x_1	x_2	x_3
μ_1	0.7	0.8	0.8
μ_2	0.3	0.7	0.4
μ_3	0.1	0.4	0.4

	x_1	x_2	x_3
min	0.1	0.4	0.4
max	0.7	0.8	0.8

Although x_3 is strictly dominated by x_2 the aggregation $\gamma \min + (1-\gamma) \max$ gives the same result for both and so both are elements of the optimal decision. Additional considerations are necessary in such a case to exclude those results. This fact is the consequence of minimum and maximum being not strictly monotonous and so the convex combination is not either. The following figure shows the compensatory effect of this operator for different values of γ .

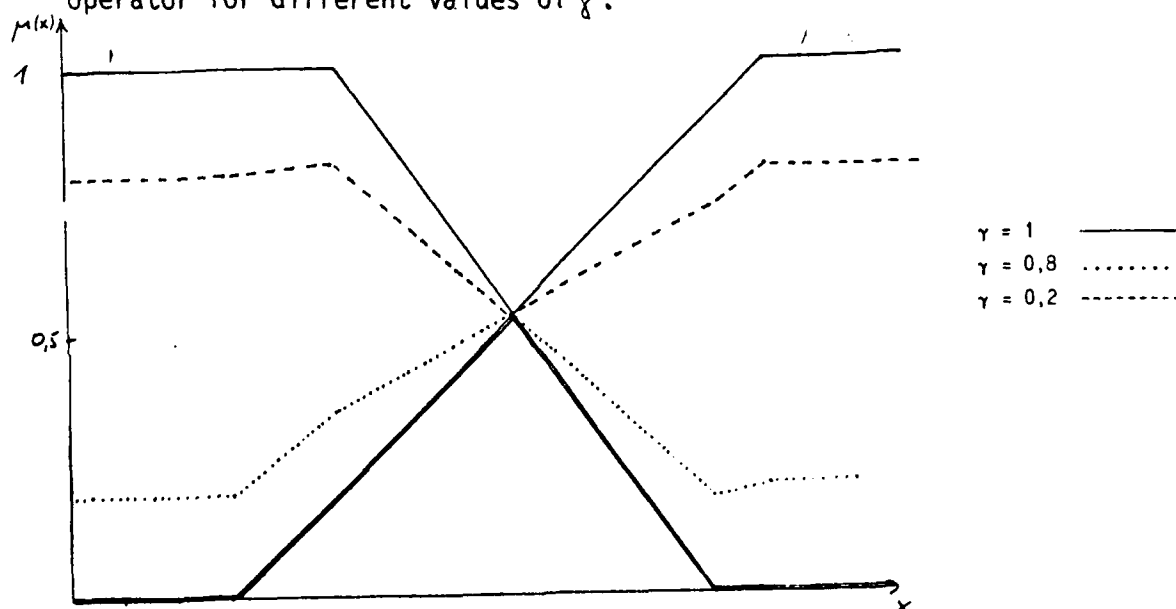


Fig. 18

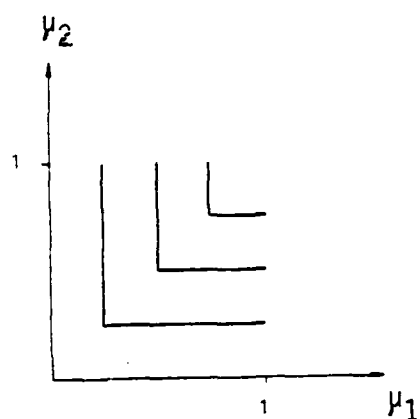
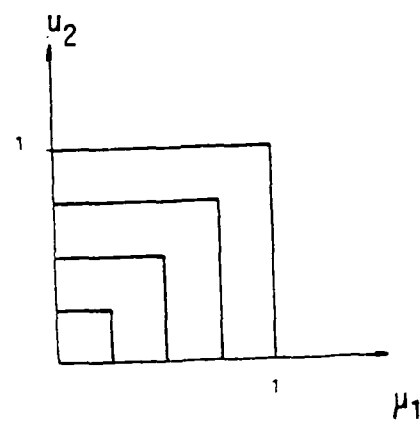
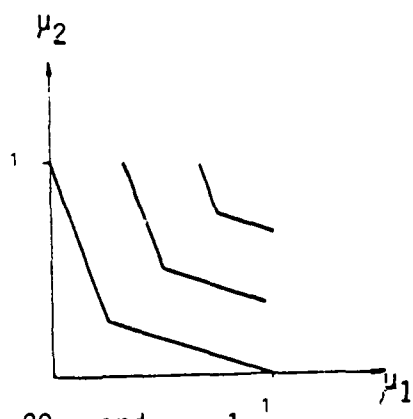
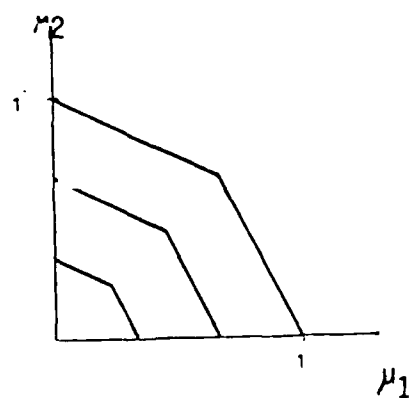
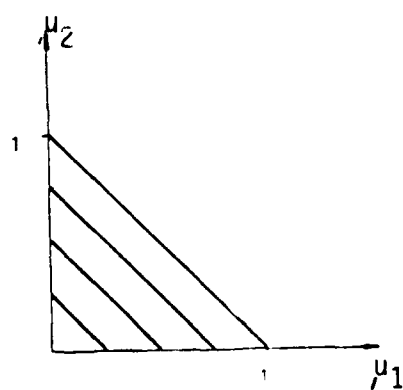
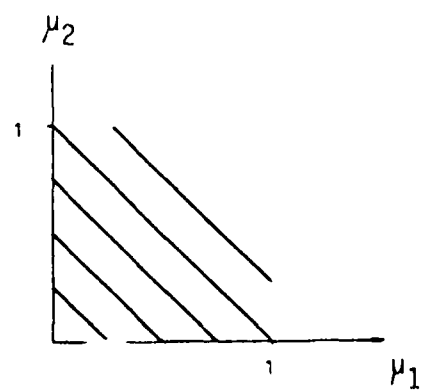
Aggregation of two membership functions by a convex combination of
min - max

To avoid this effect and to give higher weight to middle values new operators are proposed by Werners (1984). The idea is to differentiate between the terms "and" and "or", to allow compensation and to get the minimum when expressing the logical "and" and maximum when intending the logical "or" :

$$\mu_{\text{and}} = \gamma \min_{i=1}^m \mu_i + (1-\gamma) \frac{1}{m} \sum_{i=1}^m \mu_i \quad \gamma \in [0,1] \quad (42)$$

$$\mu_{\text{or}} = \gamma \max_{i=1}^m \mu_i + (1-\gamma) \frac{1}{m} \sum_{i=1}^m \mu_i \quad \gamma \in [0,1] \quad (43)$$

Here γ is the degree of approximating the logical meaning of "and" and "or", respectively. The arithmetic mean gives a compensatory effect. $\gamma=1$ yields $\mu_{\text{and}} = \min$ and $\mu_{\text{or}} = \max$. The combination of these two operators leads to very good results with respect to the empirical data of Zimmermann, Zysno (1983). The mathematical structure seems to be rather easy and efficiently to be handled. Both operators are commutative, idempotent, monotonous, continuous, compensatory and generalisations of the logic "and" and "or", respectively (Werners 1984). The following figures illustrate these operators :

Fig. 19: and, $\gamma = 1$ Fig. 22 : or, $\gamma = 1$ Fig. 20 : and, $\gamma = \frac{1}{2}$ Fig. 23 : or, $\gamma = \frac{1}{2}$ Fig. 21 : and, $\gamma = 0$ Fig. 24 : or, $\gamma = 0$

III.3 Mathematical Programming Model

III.3.1 Combination : Operator and Membership Function

Considering different types of membership functions, possible aggregation operators and feasible algorithms 10 model types can be characterized in terms of the results. The numbers of the columns refer to the "hierarchy of decisions" as shown on page 15

	1	2	3	4	5	6	7	8	9a	9b
<u>Solution:</u>										
Skalar	x	x				x	x	x	x	x
Vektor						x	x	x	x	x
Sorting				x	x					
μ -Function			x							
<u>Necessary</u> <u>M-E</u>										
I	x			x		x	x	x		
II		x	x		x		x		Lin x	N-Lin x
<u>Possible</u> <u>Aggregator</u>										
γ	x	x	x							
Min/Max	x	x	x						x	
Min	x	x	x							x
others	x	x	x							
Algorithm	Aggr	Aggr	Aggr	sorting	FM sort.	?	?	?	MILP	LP

This project focusses on mathematical programming models which can be solved efficiently. The computational effort depends essentially on the mathematical character of the "equivalent crisp model"

(last row in above table). The basic type of fuzzy model gives only one "degree of freedom".

The type of equivalent model depends much more on the type of membership function assumed and the type of operators used.

The "derived" models ought to be either linear programs or mixed integer linear programs, otherwise computations can become excessively long.

APEX, for instance, is an efficient tool for solution. Hence, our attention is directed towards models of type 9a and 9b.

Principally several combinations of membership functions and operators as proposed in III.1 and III.2 are possible. But the following discussion will show that only few of them can be solved efficiently.

The γ -operator, though empirically the most satisfying connective, leads to crisp equivalents which are extremely hard to solve. They are convex in some ranges, concave in other ranges and there do not seem to be efficient numerical algorithms available which could be used in the framework of an interactive decision support system to find optimal solutions efficiently. The following picture gives an impression of the unpleasant structure of these types of problems.

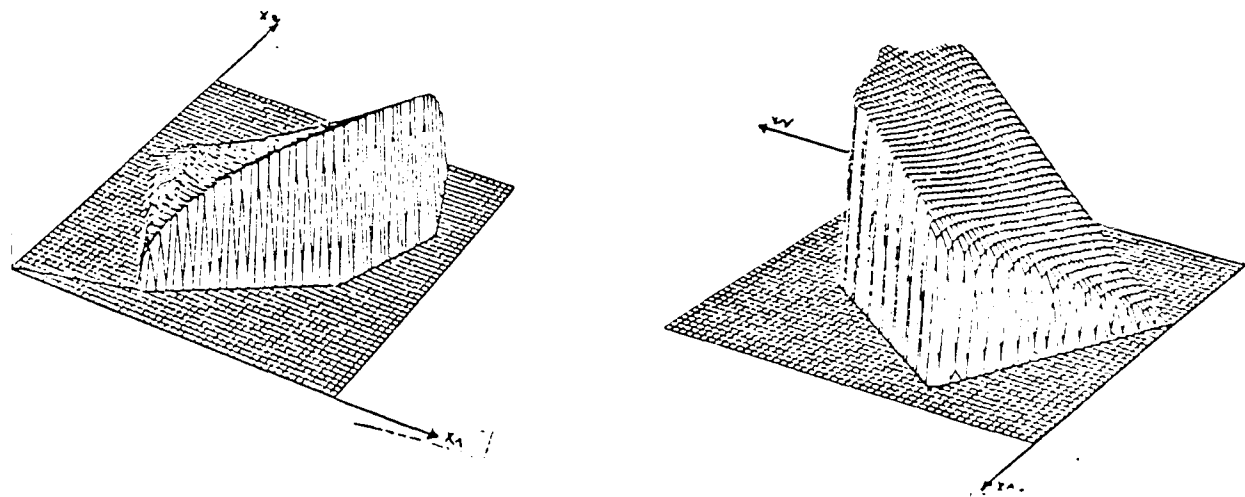


Fig. 25

The spline function as membership function together with the algebraic mean as a connective leads to crisp equivalent which are also non-linear but which could be solved by using gradient methods. These, however, do not seem to be well-suited for interactive approaches.

The improved logistic function with four parameters is too complicated to be used in mathematical programming models, especially no equivalent linear model can be found in general.

The logistic function, however, can be transformed such that a linear function results (using logarithms). Therefore we concentrate on linear original or transformed membership functions.

The feasibility of computations does not only depend on the type of membership function but rather on the chosen combination of membership function and operator. With respect to operators we found that all those basing on product-type models lead to very nasty equivalent models.

So we concentrate on the operators minimum and the convex maximum and the new operators and and or.

Let us consider linear functions $c_i^t x$, on which membership functions μ_i are defined, $i = 1, \dots, m$. Using the minimum operator an optimal decision x can be determined by solving

$$\max_{x \in X} \min_{i=1}^m \mu_i(c_i^t x) \quad (44)$$

This is equivalent to the mathematical programming model

$$\begin{aligned} \max \alpha \\ \alpha \leq \mu_i(c_i^t x) \quad i = 1, \dots, m \\ x \in X \end{aligned} \quad (45)$$

If μ_i is linear for all i , then (45) is a linear programming model and can be solved by an efficient linear programming code.

If the membership functions are nonlinear under certain conditions equivalent linear models can be derived. For the logistic membership function

$$\mu_{Li} = \frac{1}{1 + e^{-a(x-b)}}$$

(45) becomes

$$\begin{aligned} \max \alpha \\ \text{s.t. } \alpha \leq \frac{1}{1 + e^{-a_i(c_i^t x - b_i)}} \\ x \in X \end{aligned} \quad \forall i = 1, \dots, m \quad (46)$$

If (x^0, α^0) is an optimal solution of (46) then α^0 is the degree of membership of x^0 to the fuzzy set decision. But in this form the model

can hardly be solved. An equivalent formulation with

$$\alpha' = \ln \left(\frac{1}{1-x} \right)$$

is given by

$$\begin{aligned} \max \alpha' \\ \text{s.t. } \alpha' &\leq a_i (c_i^t x - b_i) \quad \forall i = 1, \dots, m \\ x &\in X \end{aligned}$$

$$\Rightarrow \begin{aligned} \max \alpha' \\ \text{s.t. } \frac{1}{a_i} \alpha' - c_i^t x &\leq -b_i \quad \forall i = 1, \dots, m \\ x &\in X \end{aligned} \quad (47)$$

After solving (47) which is a normal LP the optimal solution of this model, (α'^0, x^0) has to be transformed to find the optimal solution to (46) by $\left(\frac{e^{-\alpha'^0}}{1+e^{-\alpha'^0}}, x^0 \right)$.

Because the minimum operator does not allow any compensation a number of compensatory operators are considered in the following :

Using the convex combination of minimum and maximum the problem of finding an optimal alternative reads :

$$\max_{x \in X} \left(\gamma \min_{i=1}^m [\mu_i(x)] + (1-\gamma) \max_{i=1}^m [\mu_i(x)] \right) \quad (48)$$

$$\gamma \in [0, 1] \quad \text{degree of compensation}$$

respectively for linear goals and constraints :

$$\max_{x \in X} \left(\min_{i=1}^m \{u_i(c_i^t x)\} + (1-\alpha) \max_{i=1}^m \{u_i(c_i^t x)\} \right) \quad (49)$$

Equivalent to (49) is

$$\max \alpha_1 + (1-\alpha) \alpha_2 \quad (50)$$

$$\text{s.t. } \alpha_1 \leq u_i(c_i^t x) \quad \forall i=1, \dots, m$$

$$\alpha_2 \leq u_i(c_i^t x) \quad \text{for at least one } i \in \{1, \dots, m\}$$

$$x \in X$$

In this mathematical programming model the second group of constraints can be substituted by

$$\alpha_2 \leq u_i(c_i^t x) + M y_i \quad \forall i=1, \dots, m \quad (51)$$

$$\sum_{i=1}^m y_i \leq m-1$$

y_i binary variable,

M very large (dependent on the computer used)

Thus (50) can be modelled by a mixed-integer programming model. If all membership functions u_i are linear in $c_i^t x$ then the resulting model is a mixed integer linear programming model (MILP) which can efficiently be solved by standard software, for instance APEX.

The same does not necessarily hold for non-linear membership functions, as can be shown for logistic functions. Then an equivalent model to (50)

is :

$$\max \left(\frac{1}{1+e^{-\alpha_1}} + (1-\gamma) \frac{1}{1+e^{-\alpha_2}} \right) \quad (52)$$

$$\text{s.th. } \alpha_1' \leq a_i (c_i^t x - b_i) \quad \forall i=1, \dots, m$$

$$\alpha_2' \leq a_i (c_i^t x - b_i) \quad \text{for at least one } i=1, \dots, m$$

$$x \in X$$

which is non-linear.

Considering the new operator "fuzzy and" with

$$\max_{x \in X} \left(\min_{i=1}^m \mu_i(c_i^t x) + (1-\gamma) \frac{1}{m} \sum_{i=1}^m \mu_i(c_i^t x) \right) \quad (53)$$

an equivalent programming model can be formulated :

$$\max \quad \alpha + (1-\gamma) \frac{1}{m} \sum_{i=1}^m \alpha_i \quad (54)$$

$$\text{s.th. } \alpha + \alpha_i \leq \mu_i(c_i^t x) \quad \forall i=1, \dots, m$$

$$x \in X$$

$$\alpha + \alpha_i \leq 1 \quad \forall i=1, \dots, m$$

$$\alpha, \alpha_i \geq 0$$

If $\mu_i(c_i^t x)$ are linear for $i=1, \dots, m$ then (54) is a crisp LP.

$$\text{With } \mu_i(x) = \mu_{L_i}(x) = \frac{1}{1 + e^{-a_i(c_i^t x - b_i)}} : \quad (55)$$

$$\begin{aligned} \max \quad & \alpha + (1-\gamma) \frac{1}{m} \sum_{i=1}^m \alpha_i \\ \text{s.th.} \quad & \alpha + \alpha_i \leq \frac{1}{1 + e^{-a_i(c_i^t x - b_i)}} \\ & x \in X \\ & \alpha + \alpha_i \leq 1 \\ & \alpha, \alpha_i \geq 0 \end{aligned}$$

A substitution leads to the following crisp mathematical programming model with linear constraints and nonlinear objective function.

$$\begin{aligned} \max \quad & \frac{1}{1 + e^{\alpha'}} + (1+\gamma) \frac{1}{m} \sum_{i=1}^m \frac{e^{\alpha'_i}(1 - e^{\alpha'_i})}{1 + e^{\alpha'}(1 + e^{\alpha'} + e^{\alpha'_i} + \alpha'_i)} \\ \text{s. th.} \quad & \alpha' + \alpha'_i \leq a_i(c_i^t x - b_i) \quad \forall_i = 1, \dots, m \\ & x \in X \\ & \alpha', \alpha'_i \geq 0 \end{aligned} \quad (56)$$

$\alpha + \alpha_1 \leq 1$ in (55) $\forall_i = 1, \dots, m$ follows from

$$\alpha + \alpha_i = \frac{1}{1 + e^{\alpha' + \alpha'_i}} \leq 1 \quad \text{for } e^{\alpha' + \alpha'_i} \geq 0 \quad \forall \alpha', \alpha'_i$$

The following table presents those combinations of membership functions and aggregation operators which lead to efficiently solvable models and can be introduced into a decision support system :

	Min	Min/Max	A.M.	And	γ -Oper.
Linear Model	L.P.	Mix.Int.	L.P.	L.P.	
Logistic Model	L.P.				
Ext.Log. Model					

III.3.2 Interactive Model

Using the decision support system first the decision maker has to give his goals and constraints for a fuzzy programming model. Goals and constraints are not treated equally as in the fuzzy decision model of Zadeh mentioned earlier. Instead we consider as the main difference between a fuzzy goal and a fuzzy constraint that the decision maker is able to give more information about a constraint than about a goal. Similar to crisp programming models where he only distinguishes between 0 and 1 degree of membership for satisfying a constraint the decision maker a priori gives a membership function for each constraint. The membership function of a fuzzy maximization goal cannot be given in advance but depends on what is possible when satisfying the constraints. So additional information has to be attained about the dependencies of the model. This can be done by the system. Here extreme solutions are determined optimizing one goal over two crisps feasible regions : one with degree of membership of one, the other with positive degree of membership until zero. The results are used to determine membership functions of the goals.

Solving a crisp vector maximum model Zimmermann (1978) proposed to deduce membership functions dependent on the ideal and the pessimistic solutions. The concept used here to propose membership functions for the goals is a generalization which is necessary to handle fuzzy goals under crisp and fuzzy constraints. Aggregating all membership values i.e. of goals and constraints a compromise solution is determined. Interactively the decision maker can now change the proposed membership functions until he is satisfied with the compromise solution.

The interactive fuzzy programming system supports a decision maker, especially in two different ways :

- first, it determines extreme solutions and proposes membership functions describing the goals.
- second, it evaluates efficient compromise solutions with additional local informations.

After each presented compromise the decision-maker gets more and more insight into the model and can articulate further preference information :

- local, by modifying membership functions,
- global, by modifying the model.

The following rough flow chart sketches how the DSS works :

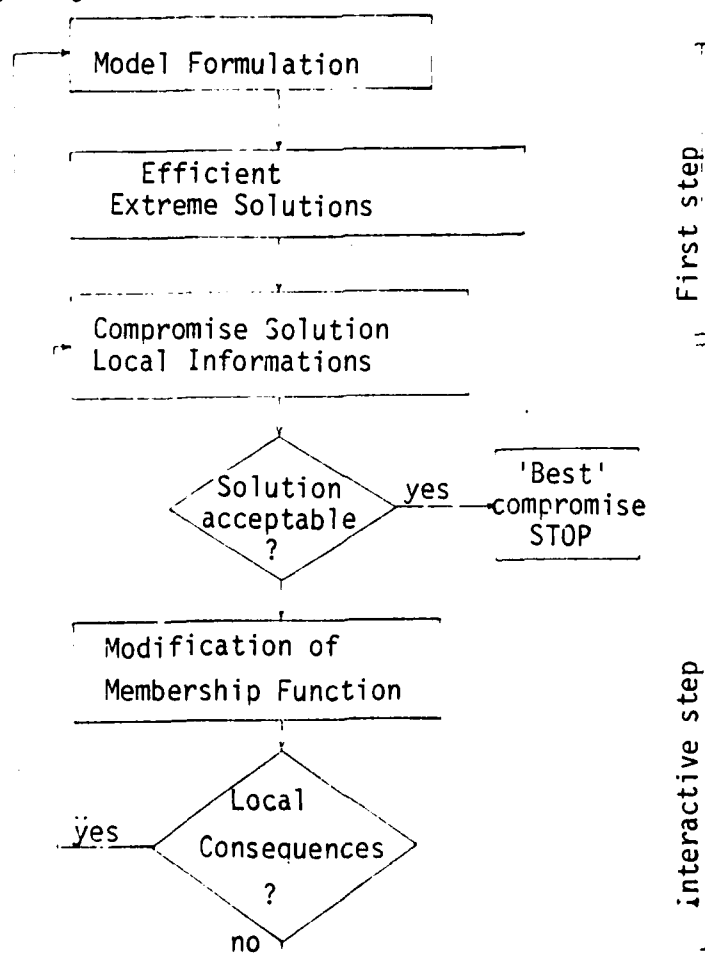


Figure 26 :
Rough flow
chart DSS

The consequences of an interactive variation of a linear membership function can be seen in figs. 27a, 27b. Here μ_1 is fixed whereas μ_2 is modified by changing \underline{c} to \underline{c}' . The resulting compromise solution $x^{0'}$ after modification has a higher value $c^t x^{0'} > c^t x^0$, but the degree of membership has decreased. This is the result of the higher aspiration level formulated by the decision maker.

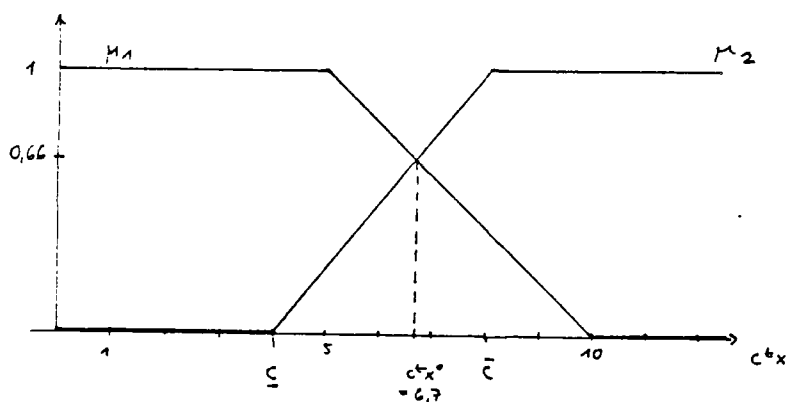


Fig. 27a

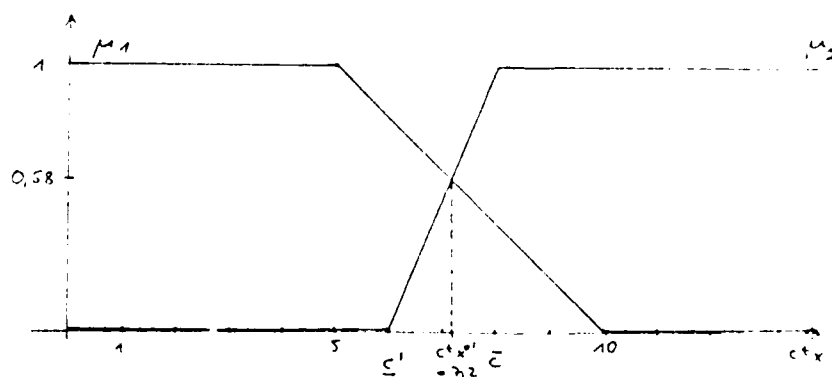


Fig. 27b

	c_1	c_2	\dots	c_k
x^{o1}	$\sum_j c_{1j} x_j^{o1}$	$\sum_j c_{2j} x_j^{o1}$	\dots	$\sum_j c_{kj} x_j^{o1}$
\vdots				
x^{ok}	$\sum_j c_{1j} x_j^{ok}$	$\sum_j c_{2j} x_j^{ok}$	\dots	$\sum_j c_{kj} x_j^{ok}$
x^{11}	$\sum_j c_{1j} x_j^{11}$	$\sum_j c_{2j} x_j^{11}$	\dots	$\sum_j c_{kj} x_j^{11}$
\vdots				
x^{1k}	$\sum_j c_{1j} x_j^{1k}$	$\sum_j c_{2j} x_j^{1k}$	\dots	$\sum_j c_{kj} x_j^{1k}$

Fig. 28 : Extreme solutions

x^{o1}, \dots, x^{ok} and x^{11}, \dots, x^{1k} are extreme solutions of a fuzzy maximization model with membership value to the constraints of 0 or 1 respectively.

Afterwards a compromise solution x^0 is determined by the system and is proposed to the decision maker including the degrees of membership to the different goals and constraints

Using the DSS the decision maker has to give his data for the following fuzzy linear programming model :

$$\begin{aligned}
 k_1 \quad & \max \quad C_1 x \\
 k_2 \quad & \min \quad C_2 x \\
 m_1 \quad & \text{s.th. } A_1 x \lesseqgtr \underline{b}_1, \bar{b}_1 \\
 m_2 \quad & A_2 x \gtrless \underline{b}_2, \bar{b}_2 \\
 m_3 \quad & A_3 x \approx \underline{b}_3, b_3, \bar{b}_3 \\
 & D_1 x \leq e_1 \\
 & D_2 x \geq e_2 \\
 & D_3 x = e_3 \\
 & x \geq 0
 \end{aligned} \quad x \in X \quad (57)$$

Assumption : $\underline{b}_i < b_i < \bar{b}_i \quad \forall i$

For each goal an efficient individual optimum is determined considering the constraints satisfied with membership degree one or zero respectively. The extrem solutions are presented to the decision maker in a table and are used to determine the membership functions of the different goals (theoretical evaluation to this point can be found in (Werners, 1984)).

	\max		\min	\leq	\geq	\approx
	\bar{c}_1	\bar{c}_2	\bar{c}_k	$\bar{b}_1^1 \dots$	$\underline{b}_1^2 \dots$	$b_1^3 \dots$
x^0	$c_1^t x^0$	$c_2^t x^0$	$c_k^t x^0$	$a_1^1 t x^0$	$a_1^2 t x^0$	$a_1^3 t x^0$
	\underline{c}_1	\underline{c}_2	\underline{c}_k	$\bar{b}_1^2 \dots$	\underline{b}_1^2	$\underline{b}_1^3, \bar{b}_1^3$
z^0	$\alpha^0 + \alpha_{01}^0$	$\alpha + \alpha_{02}^0$	$\alpha + \alpha_{0h}^0$	$\alpha + \alpha_{11}^0$	$\alpha + \alpha_{21}^0$	$\alpha + \alpha_{31}^0$

Fig. 29 : Compromise solution

Now the decision maker can decide whether he agrees with one of the proposed solutions or whether he wants to change one of the membership functions or the degree of compensation of the aggregation operator.

III.4 Empirical Investigation : Portfolio Analysis

The DSS should be tested in real military or civilian decision situations. Besides the methodological restrictions mentioned in the previous chapter restrictions concerning reality and computation time had to be taken into account.

Thus the empirical decision situation had to be chosen such that

1. the substantial concepts have to be understood as fuzzy subjective categories and as fuzzy goals/restrictions,
2. the membership function is linear or logistic in first approximation,
3. the aggregation of the subjective categories and the fuzzy goals/restrictions respectively can be represented satisfactorily by simple operators such as minimum and maximum convex combinations of both, or convex combinations of min and alg. mean.
4. the decision situation can be described by few categories so that it remains comprehensible,
5. the hierarchy of criteria (for the use in the LP) has the same depth in all branches,
6. the data can be collected with acceptable effort.

No military problem situation could be made available to us. We, therefore, turned the above mentioned non-military cases.

Requirements seemed to be fulfilled in the decision situation when buying bonds. After having collected information concerning the quality of the alternatives from brokers or other sources the

decision maker generally selects relevant aspects like maximizing the profit or minimizing the risk. His goals and/or restrictions can be formulated in a fuzzy way formalized by membership functions.

Often the investor has to rely on brokers because of the complexity of the problem. Anyway the goals of the investor, his individual economic situation and the restrictions resulting from individual preferences should be clear.

Most of the investors want to maximize the annual profit no matter whether it results from raising stock prices or from dividends. Those who use the profit for subsistence prefer safe monetary returns and raise the portion of shares with high dividends or of bonds with fixed interests. A third group prefers an increase of the value of the portfolio and therefore tends to shares with growing values.

The economic situation of the investor restricts the budget. It also determines the portfolio-condition which is formalized by a single investment. For example the budget can be DM 100.000.- and the maximum for a single investment 10 per cent or DM 10.000.-

Restrictions concerning the individual preferences are normally stated in terms such as "more defensive/more aggressive" or "risk avoiding/speculative". They should be explicitly formulated, for example, as lower bounds for the increase in price and dividend,

"tolerable" fall in price or dividend. This yields substantial restrictions for the alternatives. So the investor learns about how realistic his expectations are and can correct them if there is no bond satisfying all his wishes.

III.4.1 Models

When modelling the goals and restrictions of the investor on the one hand and the evaluation of the brokers on the other hand one needs a common formulation which can serve as a basis for the interface.

III.4.1.1 The descriptive model

First we have to create a simple system which is acceptable both for the investor and the broker. Within this system the process of valuation should be clearly structured so that the investor can at least partly understand the propositions of the broker in order to correct his goals if necessary. So the system should satisfy the following conditions :

1. Simplicity : An investor with normal education should be able to understand the system.
2. Substance : The system should contain the substantial aspects of evaluation.
3. Symmetry : The criteria of evaluation should be chosen such that both the structure of the expectations of the investor and the aspects of evaluation by the broker are represented.

The main goal of the evaluation is to reach a "good investment". This consists of an increase in prices and of an attractive dividend. For each of these aspects one can expect a more or less satisfactory development (supposing fixed environmental factors) which can be described by the price after an agreed period for one year. The development itself and so its forecast is uncertain which yields fluctuations in the stock-exchange prices. The analogous holds for the dividend which is not guaranteed to be stable.

The crucial problem of investment is the risk. The normal goal of the investor is a profit as high and as safe as possible. But there is hardly any bond with these qualities. The owners of such papers would have no interest to sell causing the prices to raise because of the great demand.

Papers with an uncertain development often have better opportunities of good profit combined however with a rather high risk. Now the above mentioned preference (concerning the risk) of the investor becomes decisive. Often a mixture of bonds with different opportunities of profit is recommended according to the principle of diversification.

The analogous holds for the dividend which rarely is guaranteed to be stable. In the worst case, however, it can fall to 0 per cent which amounts to a loss when taking into consideration inflation.

The above described criteria can be ordered into a simple hierarchical structure as to their dependencies (Fig. 30). The rate of interest is supposed to be stable in order to facilitate the scheme.

(The corresponding lines in the hierarchy are therefore dashed).

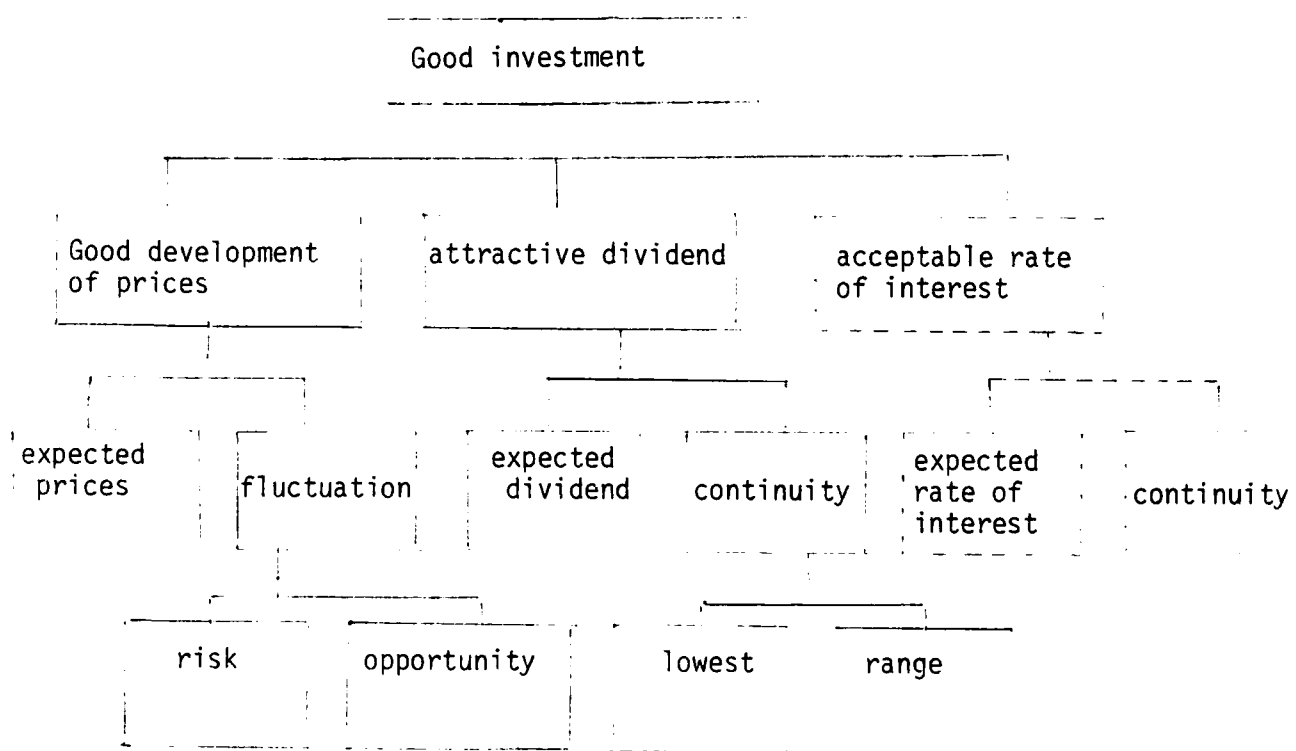


Fig. 39 : Hierarchy of criteria for evaluations bonds

For evaluating a bond the base informations are combined in a systematic process of aggregation according to the paradigm of the hierarchy of subjective categories. Naturally this hierarchy can be expanded easily. For simplicity of the model it is supposed that the broker or the experienced investor solve this task in an internal process of evaluation and by means of coefficients, scoring and graphical methods. (Chart analysis).

This more or less qualified process of evaluation finally yields the expected changes of price and dividends.

Such prognosis have two advantages for the investor. First he is able to control the performance based on the hierarchy of categories. Secondly he gets the opportunity to manifest his structure of expectations in a normal process. Hence he becomes aware of it and he can control and correct it.

Before we can express the method numerically we have to operationalize the criteria. They have to coincide concerning their dimensionality and have to have at least the quality of an interval scale because additions have to be performed so that they can serve as the base of an LP. So we chose monetary units for prices and dividends as these are used on the stock exchange too.

The categories are symbolized as follows :

i	index denoting the bond
E^{K_i}	expected price
R^{K_i}	risk
C^{K_i}	opportunity
E^{D_i}	expected dividend
R^{D_i}	risk of dividend (lowest)
C^{D_i}	opportunity of dividend (range)

Symbols for informations concerning the prices and dividends :

k_i	price at the beginning of the actual period
\bar{k}_i	estimated price at the end of the period
\underline{k}_i	estimated lowest price during the period
\bar{k}_i	estimated highest price during the period
d_i	last dividend
\bar{d}_i	next dividend
\underline{d}_i	estimated lowest dividend
\bar{d}_i	estimated highest dividend

The period is fixed to one year because in Germany the dividend is paid once a year. Then the expected price is estimate :

$$(58) \quad E^{K_i} = \bar{k}_i$$

Next the two aspects of uncertainty, risk and opportunity, are considered. An investor with a high preference for certainty tries to enlarge the capital with the essential restriction, that the possible rate of loss is as small as possible. He would prefer a small but certain profit to a large but uncertain one. The risk of loss is formalized by the estimated lowest price during the period

$$(59) \quad {}_R K_i = k_i - \underline{k}_i$$

The opposite of the risk of loss is the opportunity of profit. The aggressive investor will try to gain a considerable profit. If the expected risk of loss is less or equal to the possible profit, he won't buy. But the more favorable a paper is concerning the opportunity of profit the more attractive becomes the paper. The opportunity of profit is expressed as the difference between the estimated highest price and the estimated lowest price :

$$\begin{aligned} (50) \quad {}_c K_i &= (\bar{k}_i - k_i) - (k_i - \underline{k}_i) \\ &= \bar{k}_i + \underline{k}_i - 2k_i \end{aligned}$$

Similar operationalizations are possible for the aspects of an acceptable dividend. The expected dividend is equal to the estimated one (as was assumed for the price):

$$(61) \quad {}_E D_i = \bar{d}_i$$

The risk of the dividends can be described by the difference between the estimated lowest dividend and the rate of inflation (converted into DM) :

$$(62) \quad R_i^D = \underline{d}_i - I$$

Because the rate of inflation is constant for all possible investments it can be omitted without loss of adequacy of the model. So the risk of the dividends can be represented by the estimated lowest dividends.

$$(63) \quad R_i^D = \underline{d}_i$$

The opportunity could be operationalized analogously taken the rate of inflation into account :

$$(64) \quad C_i^D = \bar{d}_i + \underline{d}_i - 2 I$$

The rate of inflation again is a global constant. The lowest dividend is bounded from below by zero and therefore has a smaller range than the highest dividend. So it will correlate with the opportunity of the price. Thus it makes more sense to represent the opportunity of the dividend by the difference between the estimated highest and lowest dividend :

$$(65) \quad C_i^D = \bar{d}_i - \underline{d}_i$$

This is a measure of uncertainty. A defensive investor will favour a lowest price as high as possible together with a small uncertainty; a speculative investor will prefer a low probability of the lowest price together with a great range above. To compare the criteria for different bonds we use a percentage scale referring to the price K_i .

For each share the values of the criteria are multiplied by a weight g_i :

$$(66) \quad g_i = 100/K_i$$

This percentage transformation is useful in order to make the criteria better comprehensible to the investor. It would be hard to ask for the expectations for each bond. So the expectation can be generally expressed for a category. If the interest of a bond is lower than, for instance, the rate of inflation, it is of no interest to the investor. Also the acceptable risk and the lower bounds for the opportunity can be inquired more easily if the price is supposed to be 100. The transformation to a share i is obtained by dividing by g_i .

The expectations of investors may be dichotomous, i.e. a share with a dividend of more than 8% is considered attractive while shares with 8% or less are not. Usually, however, this transition from "attractive" to "not attractive" is gradual. If the "rate of acceptability" is represented by values between 0 and 1, the acceptability of a share with a dividend equal to the rate of inflation might be 0 and that of a share with a dividend (in percent) twice as high as the rate of inflation is 1.

In between there is a continuum of gradual acceptance.
In between there is a continuum of gradual acceptance.

Returning to the above described paradigm of the hierarchy of subjective categories the numerical relationships between the value of the base variables and the individual acceptance are thus modelled by membership functions. For the subjective category "risk" it describes the degree of membership $\mu_R(i)$ of the alternative i to the set R of risky investments.

The individual "model" for the structure of expectance of an investor need not to be totally isomorphic to the system of categories, but it should be possible to project it into the formulated system such that the investor sees his interests represented well enough.

III.4.1.2 The normative model

The classical formulation of decision theory distinguishes

1. a set of possible activities (decision variables),
2. a set of restrictions to bound the space of alternatives (elements within the solution space have a degree of membership equal to 1, else equal to 0),
3. a goal function which associates a degree of desirability with each feasible solution.

If the variables are additive this yields the following formal structure :

$$\begin{aligned}
 (57) \quad & \max c^T x = z \\
 & \text{s.t. } Ax \leq b \\
 & \quad x \geq 0
 \end{aligned}$$

Here x is the decision variable, in the above described problem the quantity of each bond. The matrix A contains the information of the brokers, the vectors c and b represent the goals and restrictions of the investor respectively.

In the classical LP (Problem depicted in ()) there is only one goal function. The different conceptions of the investors concerning the weights of the raise in price and the dividend cannot be formulated as a goal but only as restrictions. The two components of profit (price, dividend) are used as the objective function:

$$(68) \quad \max \sum_j (\bar{k}_j - k_j + d_j) x_j$$

The restrictions can be derived from the operationalization of the criteria :

1. raise in price :

$$(69a) \quad \sum_j (\bar{k}_j - k_j) x_j \geq b_1$$

2. risk of price :

$$(69b) \quad \sum_j (k_{i1} - k_j) x_j \geq b_2$$

3. opportunity of price :

$$(69c) \quad \sum_j (\bar{k}_j + \underline{k}_j - 2k_j) x_j \geq b_3$$

4. profit of dividend :

$$(69d) \quad \sum_j \bar{d}_j x_j \geq b_4$$

5. risk of dividend (lowest) :

$$(69e) \quad \sum_j \underline{d}_j x_j \geq b_5$$

6. opportunity of dividend (range) :

$$(69f) \quad \sum_j (\bar{d}_j - \underline{d}_j) x_j \leq b_6$$

7. total budget :

$$(69g) \quad \sum_j k_j x_j \leq b_7$$

8. portfolio condition :

$$(69h) \quad 0 \leq x_j \leq b_8 \cdot \underline{k}_j / k_j^2$$

aggregation of $k_j x_j \leq b_8 \cdot \underline{k}_j / k_j$ and non-negativity $x_j \geq 0$

Different preferences of the investors are expressed by different numerical values of b_i . Basically the type of inequalities can also vary. Here we have formulated the most plausible model which can be modified if necessary when the experimental restrictions are available.

III.4.1.3 The prescriptive model

Using the approach of Fuzzy Sets (FS) the elements of the space of alternatives are no longer associated with a degree of membership of the set $\{0,1\}$ but of the interval $[0,1]$. The rule of association is formalized by the membership function.

The same holds for the goal function because the FS-approach does not distinguish between goal function and restrictions. (Bellman & Zadeh 1970). Hence the problem has to be reformulated, such that we are looking for an alternative which is optimal according to the membership function (including goal function and restrictions). It is normally structured as follows:

$$(70) \quad \begin{aligned} c^T x &\leq z \\ Ax &\leq B \\ x &\geq 0 \end{aligned}$$

Matrix A is to be interpreted as a list of rowvectors which are not structurally different from c^T . Extending matrix A by c^T we obtain the matrix A^t and the vector b^t . Thus problem (70) can be expressed as:

$$(71) \quad \begin{aligned} A^t x &\leq b^t \\ x &\geq 0 \end{aligned}$$

(A^t is an $m+1 \times n$ - matrix, b^t an $m+1$ - vector.) The i -th fuzzy restriction/goal function can be transformed to an equivalent crisp problem using the following evaluation function :

$$(72) \quad \mu_i(x) = \begin{cases} 1 & \Leftrightarrow (Bx)_i \leq b_i \\ \frac{b_i + \varepsilon_i - (Bx)_i}{\varepsilon_i} & \Leftrightarrow b_i < (Bx)_i \leq b_i + \varepsilon_i \\ 0 & \Leftrightarrow (Bx)_i > b_i + \varepsilon_i \end{cases}$$

The meaning can be explained by the following figure:

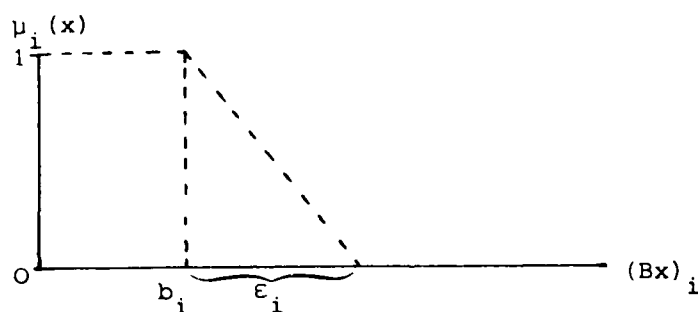


Fig. 30a : Meaning of the variables in equation (72)

The main difference to the classical LP is the variable ε_i which replaces the crisp bound b_i by an interval $[b_i, b_i + \varepsilon_i]$. For each row (restriction or objective function) (72) has to be defined on the bases of the collected data. A "fuzzy decision" with the degree of membership $\mu_g(x)$ finally is a function of the aggregation of the membership functions $\mu_i(x)$. The optimal decision x is the one which maximizes the degree of membership $\mu_g(x)$.

This yields the optimizing problem :

$$(73) \quad \begin{aligned} \max \quad & u_{\theta}(x) \\ \text{s.t.} \quad & x \geq 0 \end{aligned}$$

Using the minimum as aggregation operator as proposed by Bellman & Zadeh (1970) (73) is equivalent to

$$(74) \quad \begin{aligned} \text{Max} \quad & \lambda \\ \text{s.t.} \quad & \lambda \leq \frac{1}{\epsilon_i} (b_i - (Bx)_i) \\ & x \geq 0 \end{aligned} \quad \left| \begin{array}{l} 0 \leq \lambda \leq 1 \\ i = 1(1)m+1 \end{array} \right.$$

The model of the portfolio problem as an FLP resembles the normal LP structurally. It aims to maximize the raise in price and the dividend :

$$(75a) \quad \text{Max} \quad \sum_j (\bar{k}_j - k_j) x_j$$

$$(75b) \quad \text{Max} \quad \sum_i \bar{d}_j x_j$$

Here x_j is the decision variable which denotes the quantity of bond j . The crisp bounds b_i are abandoned in favour of intervals of

acceptance with lower and upper bounds ($B_i, B_i/i = 1, 2, \dots, 6$), which are specified by the respective membership function.

Beside these individual categorial levels of aspirations there are two more general restrictions. First the available total budget (B_7) must not be exceeded. Secondly there is a maximum value (B_8) allowed for a single investment (portfolio condition). Here one can assume that the investor tends to allow higher investment for safer bonds. A plausible weight is the ratio of the expected lowest price to the actual price. The maximum investment for a bond can be computed as the product of the upper bound

B_8 with \underline{k}_j/k_j .

This yields the following restrictions :

1. profit in price :

$$(75a) \quad \sum_j (\bar{k}_j - k_j) x_j \quad \geq B_1, \bar{B}_1$$

2. risk of price :

$$(75b) \quad \sum_j (\underline{k}_j - k_j) x_j \quad \geq B_2, \bar{B}_2$$

3. opportunity of price :

$$(76c) \quad \sum_j (\bar{k}_j + k_j - 2k_j) x_j \quad \geq B_3, \bar{B}_3$$

4. profit in dividend :

$$(76d) \quad \sum_j \bar{d}_j x_j \quad \geq B_4, \bar{B}_4$$

5. risk of dividend (lowest) :

$$(76e) \quad \sum_j \underline{d}_j x_j \quad \leq \underline{B}_5, \quad \bar{B}_5$$

6. opportunity of dividend (range) :

$$(76f) \quad \sum_j (\bar{d}_j - \underline{d}_j) x_j \quad \leq \underline{B}_6, \quad \bar{B}_6$$

7. total budget :

$$(76g) \quad \sum_j k_j x_j \quad \leq B_7$$

8. portfolio condition :

$$(76h) \quad 0 \leq x_j \quad \leq B_8 \cdot \underline{k}_j / k_j^2$$

(aggregation of $k_j x_j \leq B_8 \cdot \underline{k}_j / k_j$ and $x_j \geq 0$)

Now we can determine an aggregate membership function and find the combination of alternatives which maximizes this function.

Remember that the minimum operator has been chosen to model the intersection. Verbally this means that an investment is good if the increase in price and the risk of price and the opportunity of price and the increase in dividend and the risk of dividend and the opportunity of dividend are good, or more precise if the minimum over all criteria

is at a maximum.

Probably some of the investors are indifferent as to whether profit results from raise in price or from dividend. They would aggregate the subjective categories "good development of prices" and "attractive dividend by," or "which can be represented by the maximum operator for the membership functions.

Continuing our paradigm partial degrees γ are possible between the "a" "and" and "or" aggregation. This results from the fact that some aspects of raise in price and dividend are similar while others are divergent. Thus it does not matter whether the profit results from a raise in price or from the dividend. But usually the dividend is associated with a higher certainty than the predicted raise in price which can not be timed exactly. In section 3.2 we proposed the convex combination of the intersection and the union for the aggregation in order to be able to model the individual preferences. This convex combination is formally represented in the LP by the minimum and maximum because of the better numerical tractability :

$$(77) \quad (\bar{C}_1 - \underline{C}_1) \text{ Min } - \sum_j (\bar{k}_j - k_j) x_j \leq \underline{C}_1$$

If the investor defines lower and upper levels of aspiration for the two goals (75) , i.e. $\underline{C}_1, \bar{D}_1, \underline{C}_2, \bar{C}_2$ the following model can be formulated :

Goal :

$$(78) \quad \text{Max} \quad (1-\gamma) \cdot \text{Min} + \gamma \cdot \text{Max}$$

restrictions :

1. "goal I" :

$$(79a) \quad \mu_0(x) = (1-\gamma) \text{Min} [\mu_i(x)] + \gamma \text{Max} [\mu_i(x)]$$

2. "goal II" :

$$(79b) \quad (\bar{C}_2 - \underline{C}_2) \text{Min} -\sum_j \bar{d}_j \cdot x_j \leq -\underline{C}_2$$

3. profit in price :

$$(79c) \quad (\bar{B}_1 - \underline{B}_1) \text{Min} -\sum_j (\bar{k}_j - k_j) x_j \leq -\underline{B}_1$$

4. risk of price :

$$(79d) \quad (\bar{B}_2 - \underline{B}_2) \text{Min} -\sum_j (k_j - \underline{k}_j) x_j \leq -\underline{B}_2$$

5. opportunity of price :

$$(79e) \quad (\bar{B}_3 - \underline{B}_3) \text{Min} -\sum_j (\bar{k}_j + \underline{k}_j - 2k_j) x_j \leq -\underline{B}_3$$

6. profit of dividend :

$$(79f) \quad (\bar{B}_4 - \underline{B}_4) \text{Min} -\sum_j \bar{d}_j x_j \leq -\underline{B}_4$$

7. risk of dividend (lowest) :

$$(79g) \quad (\bar{B}_5 - \underline{B}_5) \text{Min} -\sum_j \underline{d}_j x_j \leq -\underline{B}_5$$

8. opportunity of dividend (ranges) :

$$(79h) \quad (\bar{B}_6 - B_6) \text{ Min} + \sum_j (\bar{d}_j - \underline{d}_j) x_j \leq \bar{B}_6$$

9. "goal I" :

$$(80a) \quad (\bar{C}_1 - \underline{C}_1) \text{ Max} - \sum_j (\bar{k}_j - k_j) x_j - MY_1 \leq \underline{C}_1$$

10. "goal II" :

$$(80b) \quad (\bar{C}_2 - \underline{C}_2) \text{ Max} - \sum_j \bar{d}_j \cdot x_j - MY_2 \leq \underline{C}_2$$

11. profit in price :

$$(80c) \quad (\bar{B}_1 - \underline{B}_1) \text{ Max} - \sum_j (\bar{k}_j - k_j) x_j - MY_3 \leq \underline{B}_1$$

12. risk of price :

$$(80d) \quad (\bar{B}_2 - \underline{B}_2) \text{ Max} - \sum_j (\underline{k}_j - k_j) x_j - MY_4 \leq \underline{B}_2$$

13. opportunity of price :

$$(80e) \quad (\bar{B}_3 - \underline{B}_3) \text{ Max} - \sum_j (\bar{k}_j + \underline{k}_j - 2k_j) x_j - MY_5 \leq -\underline{B}_3$$

14. profit of dividend :

$$(80f) \quad (\bar{B}_4 - \underline{B}_4) \text{ Max} - \sum_j \bar{d}_j x_j - MY_6 \leq -\underline{B}_4$$

15. risk of dividend (lowest) :

$$(80g) \quad (\bar{B}_5 - \underline{B}_5) \text{ Max} - \sum_j \underline{d}_j x_j - MY_7 \leq -\underline{B}_5$$

16. opportunity of dividend :

$$(80h) \quad (\bar{B}_6 - \underline{B}_6) \text{ Max} + \sum_j (\bar{d}_j - \underline{d}_j) x_j - MY_8 \leq \bar{B}_6$$

17. exclusion

$$(30i) \quad Y_1, Y_2, Y_3, Y_4, Y_5, Y_6, Y_7, Y_8 \in \{0,1\}$$

$$(80i') \quad \text{Min } (Y_i) = 0$$

18. artificial variable :

$$(30j) \quad M = \infty$$

19. total budget :

$$(81a) \quad \sum_j k_j x_j \leq B_7$$

20. portfolio condition :

$$(81b) \quad 0 \leq x_j \leq B_8 \cdot \frac{k_j}{k_j^2}$$

Restriction (79) concerns the minimum and restriction (80) the maximum. The budget restriction and the portfolio restriction are generally valid.

The γ -values for the degree of compensation of categories should be kept variable both within the hierarchy and between the individuals in order to obtain an adequate representation of the human decision. At the present state of knowledge this is only possible in the descriptive model. In the long run progress can be expected for the prescriptive model also.

III.4.2 Preliminary study : Membership function of the investor

To get an idea about the shape of the membership function (type B), which represents the investor's attitude concerning the categories of the hierarchy of evaluation, 10 persons were interviewed, who possessed a depot of bonds. This procedure was not intended to obtain a representative random sample of all possible individual membership functions, but to

- a) show, that the goals and restrictions of investors can be represented by membership functions,
- b) select characteristic constellations of membership functions which can serve the brokers as an indication of the expectations of investors in the main study.

The membership functions of subject 4 are given in the following figures.

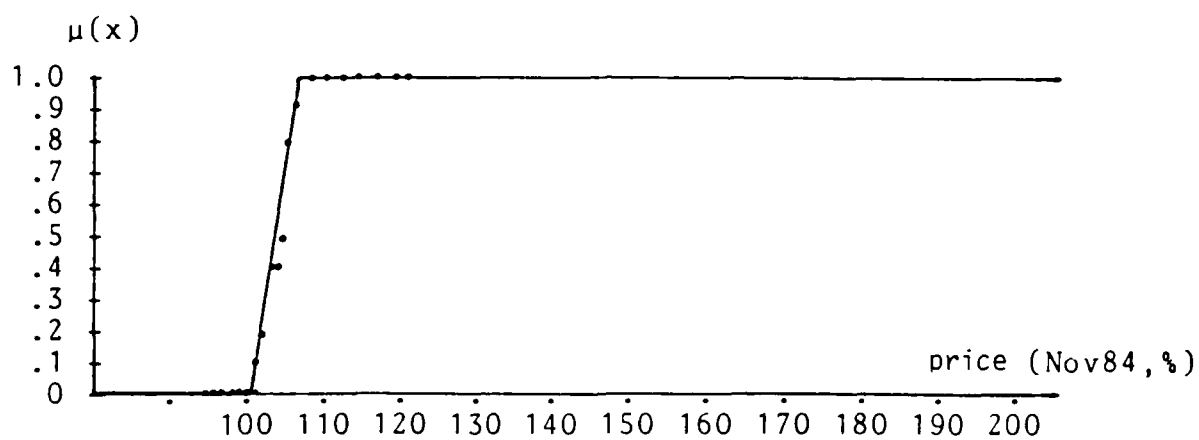


Fig. 31 investor 4, expected price

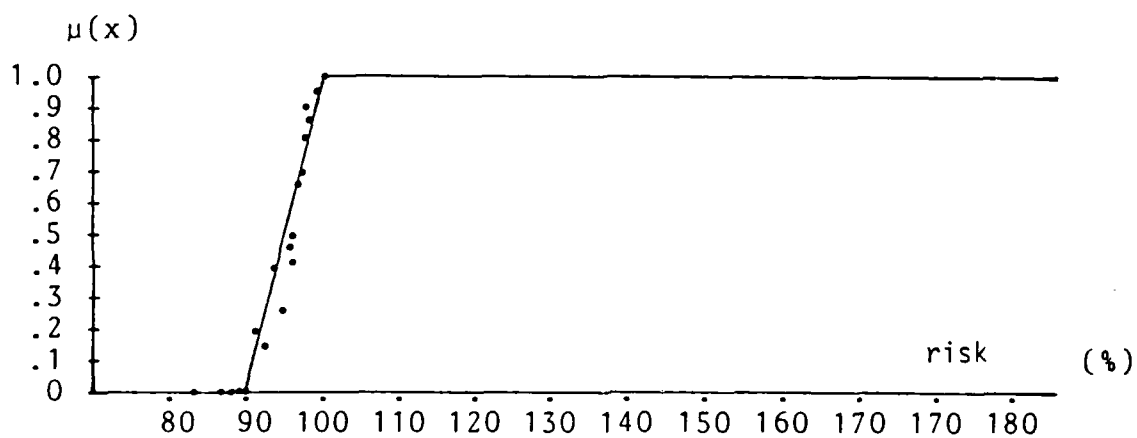


Fig. 32 investor 4, risk

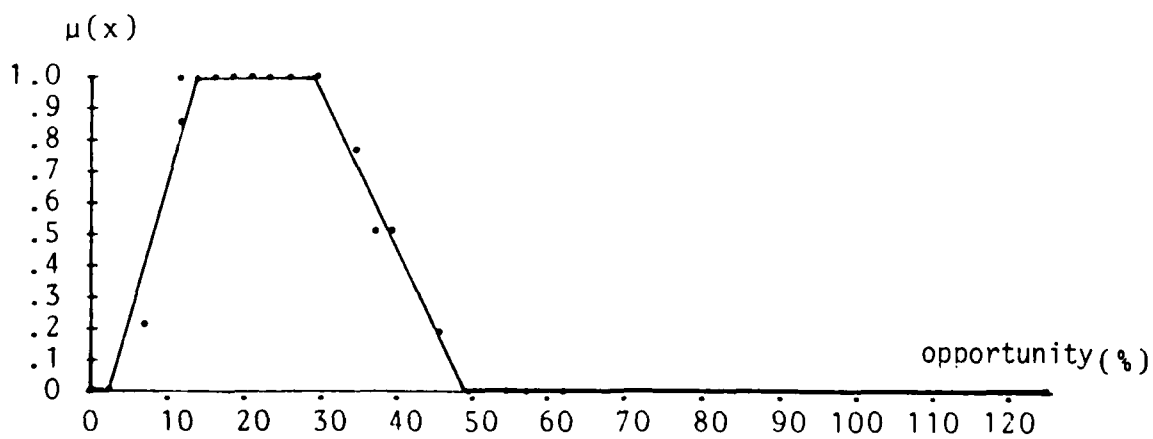


Fig. 33 Investor 4, opportunity

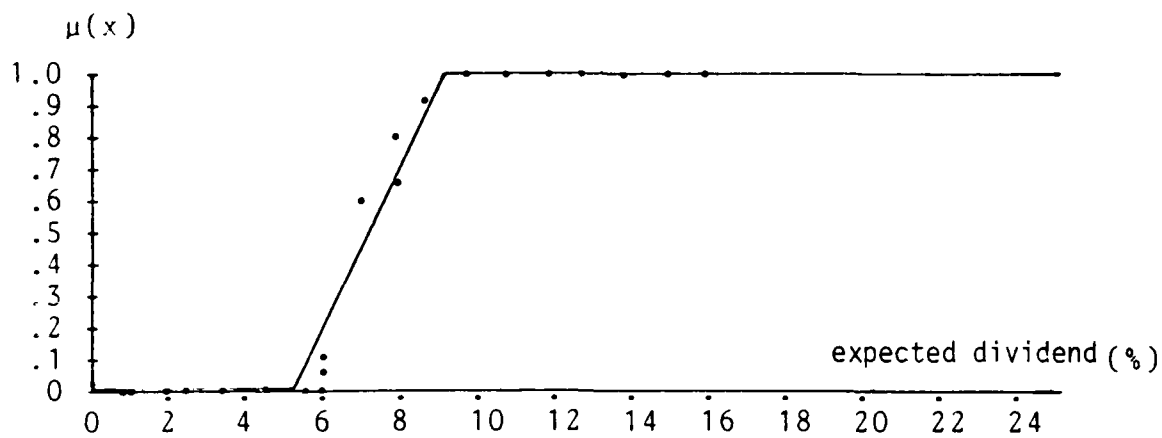


Fig. 34 investor 4, next dividend

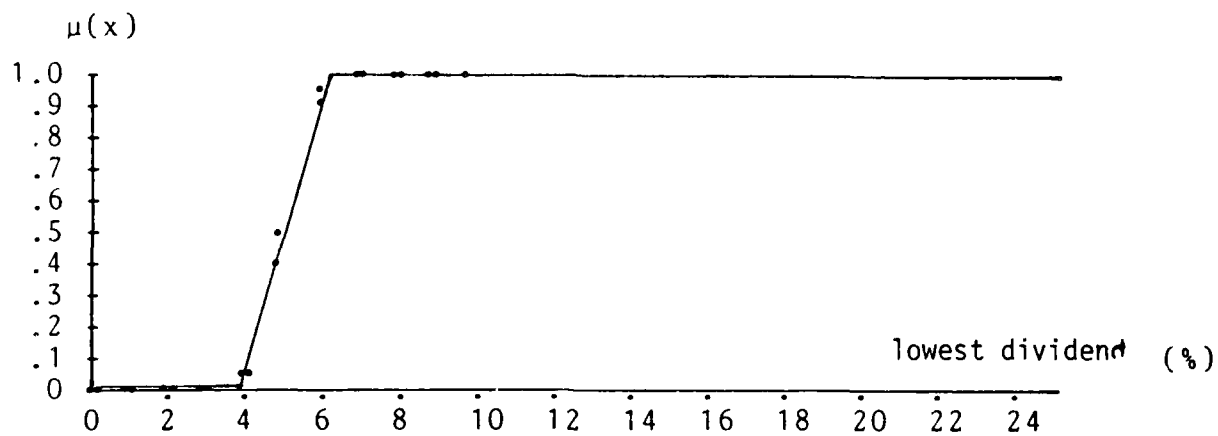


Fig. 35 investor 4, lowest

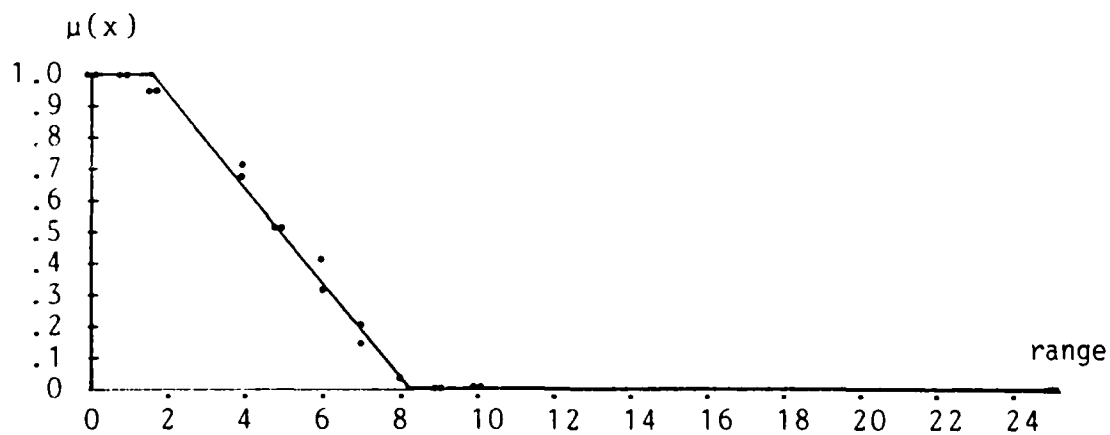


Fig. 36 investor 4, range

III.4.3 Main study : comparison of performances.

After the model had been formulated and the empirical conditions (structure of the goals and restrictions of the investors) been ensured the final and most important phase of empirical testing could be started. Based on the forecasts of the brokers concerning the development of prices and dividends of a representative selection of bonds portfolios could be determined by means of LP and FLP. These portfolios had to be compared with the propositions given by the brokers.

On the basis of the model it could be expected, that the FLP supplies "better" results than the LP because more information is considered via the membership function. Such a comparison, however, yields a relative judgement only; nothing can be said about whether the available informations have been used advantageously. For this purpose we would need a level of comparison which represents the general development of the stock exchange.

As a simple and plausible orientation the percentage of profit obtained by a random selection one may use :

$$\begin{aligned}
 (82) \quad v_{zuf} &= 100 \frac{\Sigma \bar{k}_z - \Sigma k_z}{\Sigma k_z} \\
 &= 100 (\Sigma \bar{k}_z / \Sigma k_z - 1)
 \end{aligned}$$

Here k_z is the price at time t and \bar{k}_t the price at a later time t' . Index z indicates that the prices are a random representations of all bonds.

This value can be compared with the percentage of profit obtained from the bonds i of portfolio proposed by the brokers j

$$(83) \quad v_{w(j)} = 100 \frac{\sum \bar{k}_i - B}{B}$$

$$= 100 (\sum \bar{k}_i / B - 1)$$

B denotes the total budget at time t . If $v_{WP(j)}$ is greater than v_{Zuf} the broker has provided a good forecast. The analogous holds for the forecast based on LP and FLP.

III.4.3.1 Hypothesis

If the models contain relevant information then it can be expected that the LP yields a better portfolio than pure chance and FLP yields better results than LP : $v_{LP} < v_{FLP}$. If non-linear membership functions ($\wedge P$) could also be intergrated the appropriate solution would probably dominate the above mentioned solutions.

Naturally the current project can only make statements about some of these relationships. The zero hypothesis assumes that neither the formal models nor the brokers contain relevant informations beyond the actual prices. It was assumed that the rates of change are all equivalent :

$$H_0 : \quad v_{Zuf} = v_{WP(j)} = v_{LP(j)} = v_{FLP(j)}$$

The alternative hypothesis has to make a statement about the order of the performance of the model compared to that of the brokers. It can be expected, however, that at least some of the experts have not sufficiently considered the restrictions given by the investors (defensive, speculative), so that they may produce an infeasible solution.

If the brokers j has been conscious about the preferences of the investor when selecting his portfolio the alternative hypothesis reads as follows :

$$H_1: V_{Zuf} < V_{WP(j)} < V_{LP(j)} < V_{FLP(j)}$$

III.4.3.2 Experimental design

The empirical part of the research aimed at obtaining from the brokers firstly estimates about the development of some selected German bonds and secondly a portfolio for the defensive and speculative investor described in the above chapter. In order to keep the experimental and financial effort within reasonable limits the two following restrictions were made :

- 1) The budget is fixed at DM 100.000.-
- 2) 30 bonds which are traded on German stock exchanges have been selected such that

- the different lines of trade are represented equally,
- the papers are approximately normally distributed with respect to opportunities of prices and dividends,
- the main shares (18), federal loans with fixed interests (4), real estate funds (4) and precious metals (4) are represented.

Each participant obtained a booklet of 20 pages which stated the aims of the research and which made the brokers familiar with their tasks. The completed questionnaires were returned to us by a fixed date so that we could guarantee the anonymity as well of the participants as the financial institutions.

III.4.3.3 Evaluation and results

The test data were evaluated in the sequence of the hypotheses. The results of the four stages are summerized in figure 37 for the devensive and in figure 38 for the speculative investors. The four columns represent the results of the decision models "random", "broker" (WP), "Linear Programming" (LP) and "Fuzzy Linear Programming" (FLP). The presentation has exemplarily been limited to three brokers.

20 brokers of different financial institutions were interviewed concerning the evaluation of different German shares, real estate funds, bonds with fixed interests and precious metals. The evaluation expresses the forecasts of the expected mean, highest and

lowest prices and dividends. Based on his own forecast each participant proposed a portfolio with the budget of DM 100.000.- for the above selected defensive and speculative investors, respectively.

Our hypotheses have proved valid in all respects. Brokers are generally able to select a portfolio which yields a better expected profit than pure chance. By increasing the number of preferences and demands of the investor and the number of possible investments the probability of a feasible and even an optimal solution diminishes. By using Linear Programming both can still be obtained. Fuzzy Linear Programming enables one to find a compromise between divergent goals (high increase of prices, high dividend) in the interval between two restriction spaces and thus to enlarge the satisfaction of the user. For $\gamma = .5$ the compromise between the two goals "maximal increase in prices" and "maximal dividend" yields solutions with higher weight on the dividends. Changes to $\gamma = 1$ and $\gamma = 0$ respectively yields a higher weight for the associated components.

One condition is, however, that the investor is able to articulate himself sufficiently or, even better, that a verbal interface can be defined which allows the freeflow of informations between the human being and the model. The proposed hierarchy of criteria, formalized using fuzzy sets, proved very useful in this respect. It does not only allow to receive informations systematically but also a to the investor. His reactions, f.i. relaxation of restrictions or specifications of certain areas of investment, could be useful for a repeated and promising analysis.

Fig. 3/: Expected profits for the defensive investor resulting from the 19 portfolios based on the forecasts of the respective broker

w_j	random		broker		LP		FLP(1-5)		
	profit i.price	profit i.dividend Σ	profit i.price	profit i.dividend Σ	profit i.price	profit i.dividend Σ	profit i.price	profit i.dividend Σ	
7	7553	3444	12800	5020	26974	6000	32974	7600	29204
10	13823	3177	13340	1277	40817	5996	46813	7542	37214
15	15908	2935	7480	5450	28453	5998	34450	6286	29636

Fig. 38: Expected profits for the speculative investor resulting from the 19 portfolios based on the forecasts of the respective broker

w _j	random		broker		LP		LP($\gamma = .5$)						
	profit i.price	profit* in dividend Σ	profit i.price	profit i.dividend Σ	profit i.price	profit i.dividend Σ	profit i.price	profit i.dividend Σ					
7	7653	3444	11097		18437	2700	21137	30696	4296	34956	21604	7599	29203
10	13823	3177	17000		12245	3560	15805	44515	3498	48013	35234	3630	37864
15	15908	2935	18843		35438	2600	38038	51160	1215	52375	38758	3392	42150

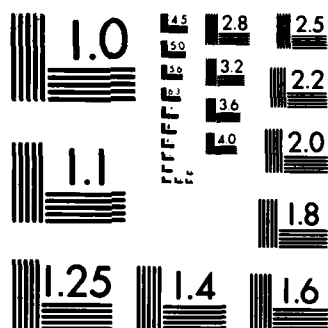
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MICROCOPY RESOLUTION TEST CHART
NATIONAL BUREAU OF STANDARDS-1963-A

III.5 EDP - Implementation

1) Introduction

The system "DSS" supports the decision maker solving multi-criteria problems with crisp and flexible restrictions.

The system is composed of three components :

a) Man/Machine communication

This part has the following tasks :

- to guide the decision maker through the system directed by a menu,
- to present the processed data to the decision maker and
- to allow the input and change of the data and the decision variables by the decision maker

b) Data management

This section contains the activities

- data processing and
- data update

c) System/Machine communication

This part is the interface to other software systems, which are used by "DSS". In detail this section

- generates the interface files and
- supervises and controls the execution of the software system in use.

From the above description of the components of the system it becomes obvious that the second part, "data management", depends only on the chosen programming language and therefore is unrestricted portable. Section a) "Man/Machine communication" depends on the available hard-

ware; section c) "System/Machine communication" depends on the software used.

In detail the dependance on the hardware means that communication is possible between a Hazeltine Esprit III terminal and a Cyber 175 via a synchronous line. The dependence on the software makes the application of the LP-system APEX III under NOS 1.4 necessary.

The programs of the system are coded in PASCAL and FORTRAN. The application of FORTRAN as a second language has been necessary due to the fact that on the Cyber 175 of the RWTH Aachen APEX and PASCAL are working with non-compatible data management systems.

In detail the system "DSS" processes the modules 1, 3 to 5,8 and 9 (of figure38). For this purpose two permanent libraries can be used which contain

- a) all system programs as relocatable binary decks
and
- b) all data of the problem known by the system.

After starting the system the following libraries are generated depending on the needs of the user :

- libraries for intermediate results and
- storage of control procedures which are selfstarting.

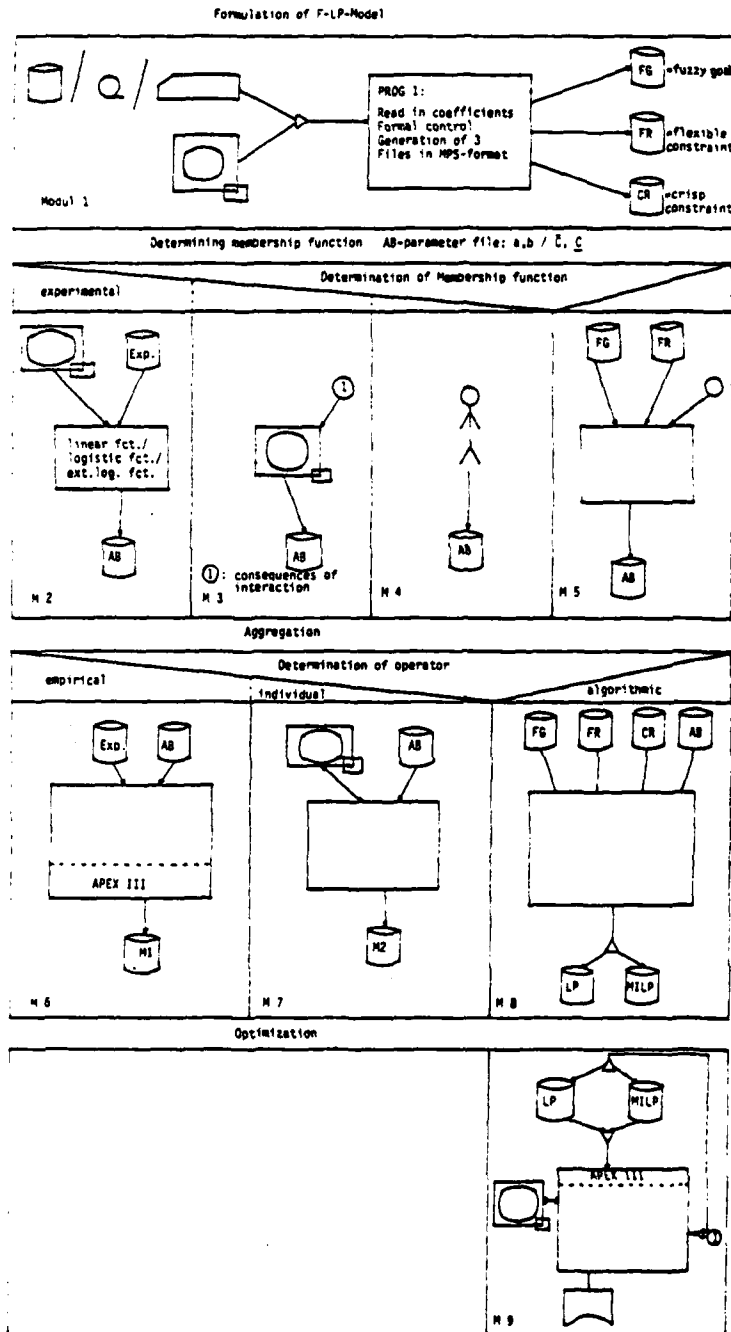


Fig. 38: Formulation of F-LP-Model

III.6 Conclusions and Recommendations

The goals of the project as stated in the original application have been achieved: A decision support system has been designed, programmed, implemented and tested which supports decisions of the following very general kind:

1. They have to be of the "mathematical programming type", i.e. decisions have to be made which have to optimize one or more "criteria" and which are constrained by restrictions such as budgetary constraints, limited firepower, limited availability of capacities, resources or times.
2. The criteria or goals can be of different character:
 - they can be criteria which are to be strictly minimized or maximized,
 - they can represent aspiration levels which have to be achieved,
 - they can be criteria which have to be "achieved" in a more approximate way, i.e. "if possible", "as good as possible", "close to" etc.
3. The constraints can either be
 - crisp, i.e. restrictions representing well defined borders such as "at most 1 mio dollars", "at least 1000 men", etc.
 - flexible in the sense "not much more than", "basically not less than", "approximately". The reason for the constraints can be that either the data are not exactly known, the requirements are not known to the last digit, or that flexibility is desired with respect to the constraints.

For those problems the system supports the decision maker by a fuzzy multi criteria programming model interactively. The applicability of the types of membership functions and operators used in the models have been tested empirically and shown to be acceptable.

The work had to be done subject to a number of constraints:

1. Military problems could not be obtained for real testing.
2. The hardware configuration in Aachen is essentially a double Cyber 175, i.e. a very fast mainframe computer with, however, a not very comfortable and user oriented periphery. To that computer the terminals are connected via a "concentrator".
3. To solve the LP or MILP models the program APEX III was used.
4. Two years were available for all modelling, programming and testing.

Primarily due to those four constraints some improvements could not be made, which can be considered as worthwhile extensions of this project:

Empirical:

Membership functions: So far linear or transformable 2-parameter logistic membership functions have been used in the DSS. Outside the project it has been shown, however, that the 4-parameter logistic function (see fig. 7 on page 25) shows a better empirical fit, i.e. is better context adaptable. The transformation of the 2-parameter logistic function into a linear function is optimally possible via known methods. For the 4-parameter function this can only be done iteratively. It would be desirable to find ways to either determine the two parameters c and d directly or to design methods to obtain optimal linear approximations as functions of a , b , c and d .

Operators: So far the min-operator, linear combinations of min and max and the "fuzzy and", represented by a linear combination of min and the algebraic mean, have been included in the DSS. It would be desirable to explore empirically how distinctions can be made between the "fuzzy and" and the "fuzzy or" when modelling a problem.

User-interface: Because of the lack of military problems the appropriateness of the model-user-interface could only be tested and improved for the portfolio problem. It would be desirable to test and possibly improve the interface in other contexts.

Modelling:

The simultaneous use of the "fuzzy and" and the "fuzzy or" or the sole use of the latter leads to integer derived models and to some other complications. One way out would be to use "hierarchical aggregation [see Werners 1984, pp. 207-213]. This would also allow the decision maker to develop his model in successive steps. To integrate this into the DSS would require more theoretical, programming and testing effort.

So far we have assumed, that the original problems did not have any integer requirements. To widen the scope of application of the DSS it would be desirable to include new approaches [f.i. Zimmermann, Pollatscheck 1984] to this end. The integration of the 4-parameter logistic function would also require additional modelling effort.

Coding:

Two improvements with respect to turn around times (i.e. waiting time of the user) could be envisaged:

In Aachen a new operating system will be installed in the near future which allows parallel processing. Then a number of processing activities could be performed in parallel rather than successively, which would reduce the waiting time of the user.

It could also be conceived a configuration in which an intelligent terminal and a mainframe share the work thus arriving at a multi-stage system which would probably provide similar improvements.

It was already mentioned that the hardware available in Aachen lacks some of the user orientation which, for instance, IBM or DEC computers do provide.

Hence a modification of the DSS for other computer periphery could considerably improve the user orientation and the portability of the system.

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IV Documentation of the System

"DSS" is a program system for supporting the decision maker solving problems with several objectives and crisp and fuzzy (flexible) restrictions

The system fulfills the following tasks:

- storage and maintenance of different data of the problem
- determination of membership functions and extremal solutions
- aggregation of membership functions and computation of compromise alternatives
- presentation of further local information and processing of interactive modifications.

This documentation aims at making the reader familiar with the way the system is working. Therefore first a dialog with the system will be presented exemplarily. Then the existing data files and programs will be documented. Finally a complete representation of error messages and screen masks will be given.

The documentation is structured as follows:

1. Structure of the system
2. Description of the data files
 - 2.1 Survey
 - 2.2 Detailed descriptions
 - 2.2.1 PROBES
 - 2.2.2 PROBDA
 - 2.2.3 PROBL
 - 2.2.4 APEX-1 data files
 - 2.2.5 TAPE4

- 3. Documentation of the programs
 - 3.1 MAINTEN1
 - 3.2 CREAT
 - 3.3 DELET
 - 3.4 DESCR
 - 3.5 UPDTE
 - 3.6 EXT
 - 3.7 PROBSOL
 - 3.8 BINGLP
 - 3.9 INDVLP
 - 3.10 COMPL
 - 3.11 SOLUT
 - 3.12 MAINCCL
- 4. Error Messages
- 5. Masks for Dialog

IV.1 Structure of the system

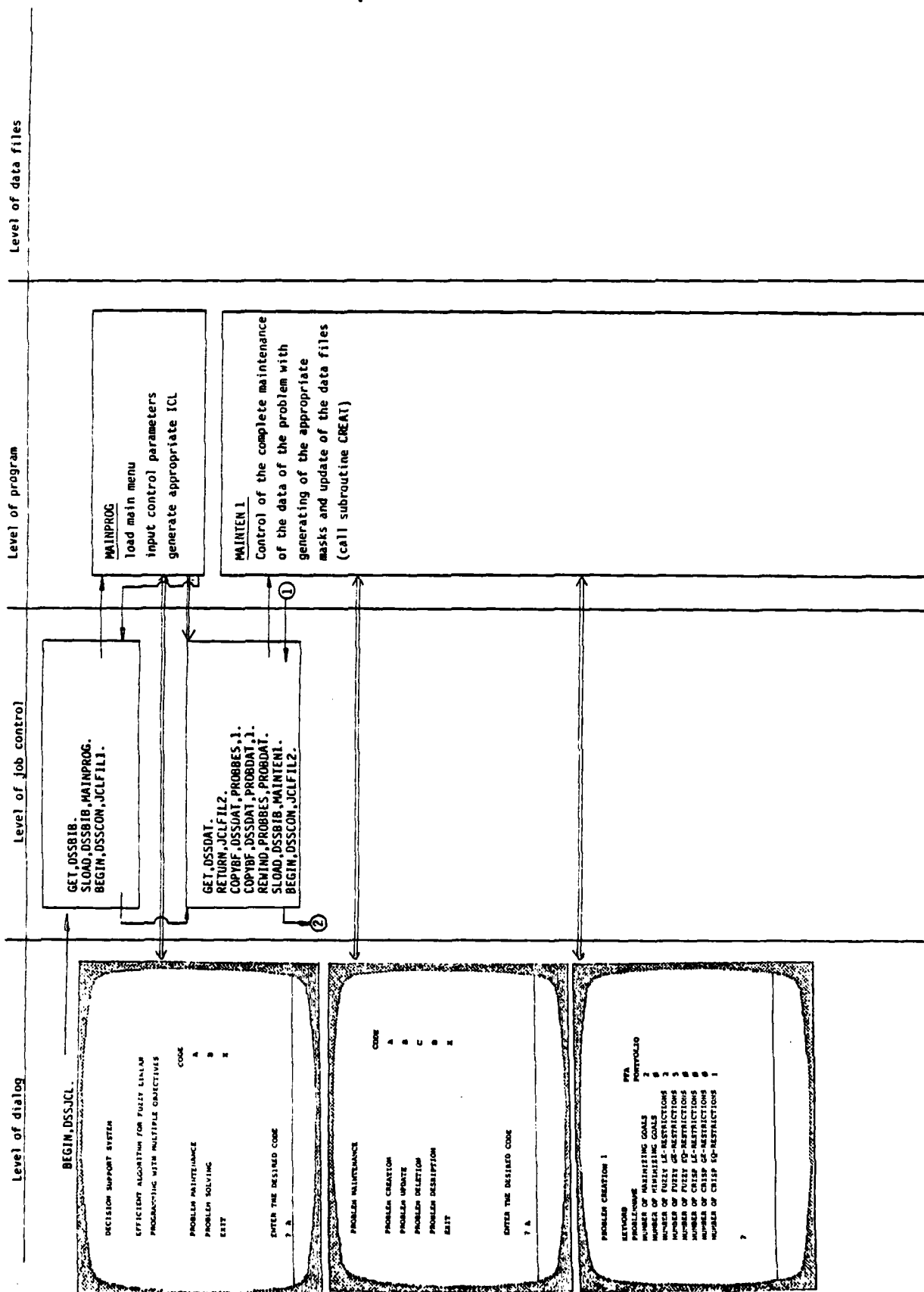
The system "DSS" is a menu-oriented dialog system for solving multi-criteria problems with crisp and fuzzy restrictions. A static description of the structure shall be omitted, because the structure of the system is highly dependent of the wishes of the decision maker. Instead we shall try to clarify the structure by describing a terminal session exemplarily.

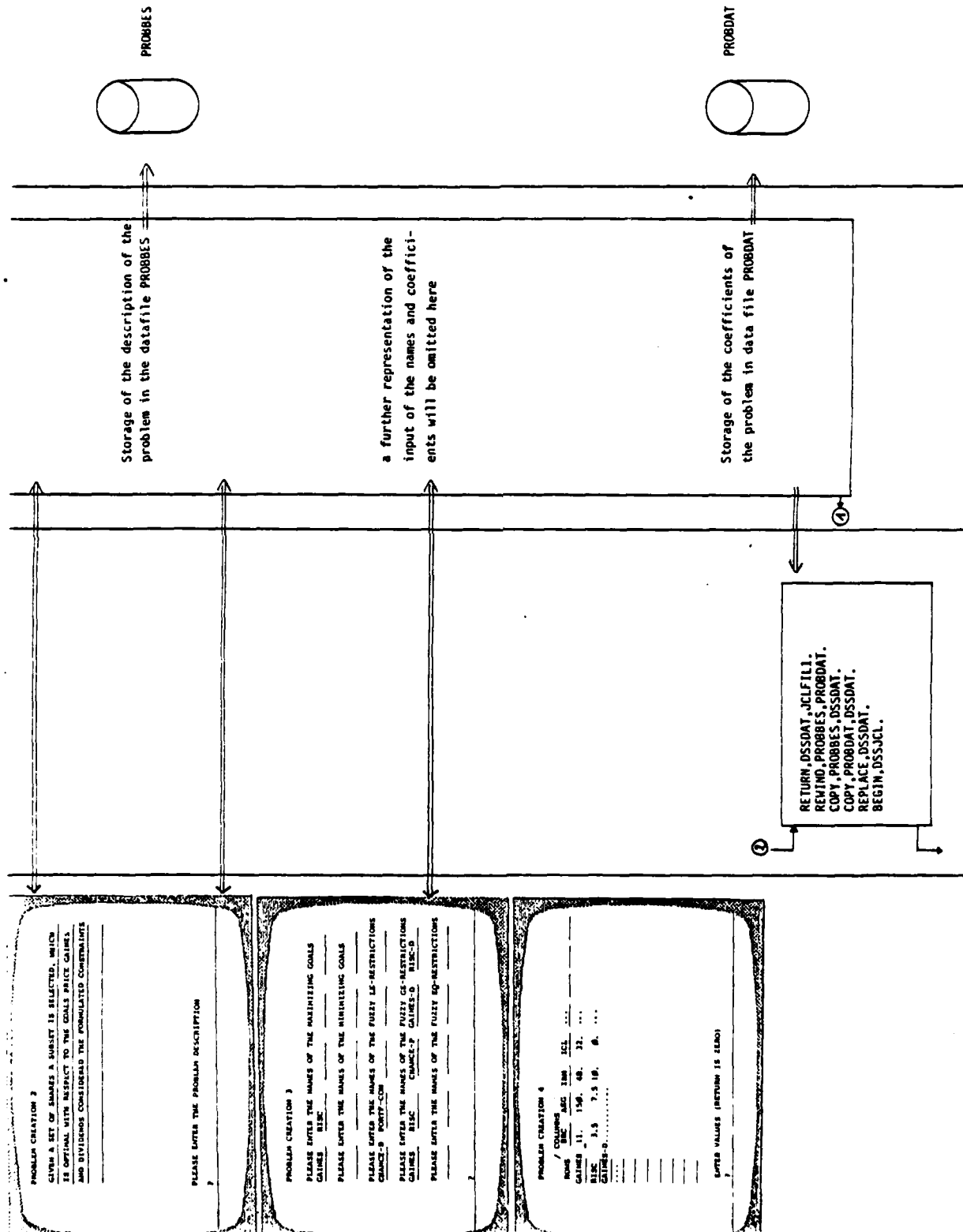
The session will be represented on four levels:

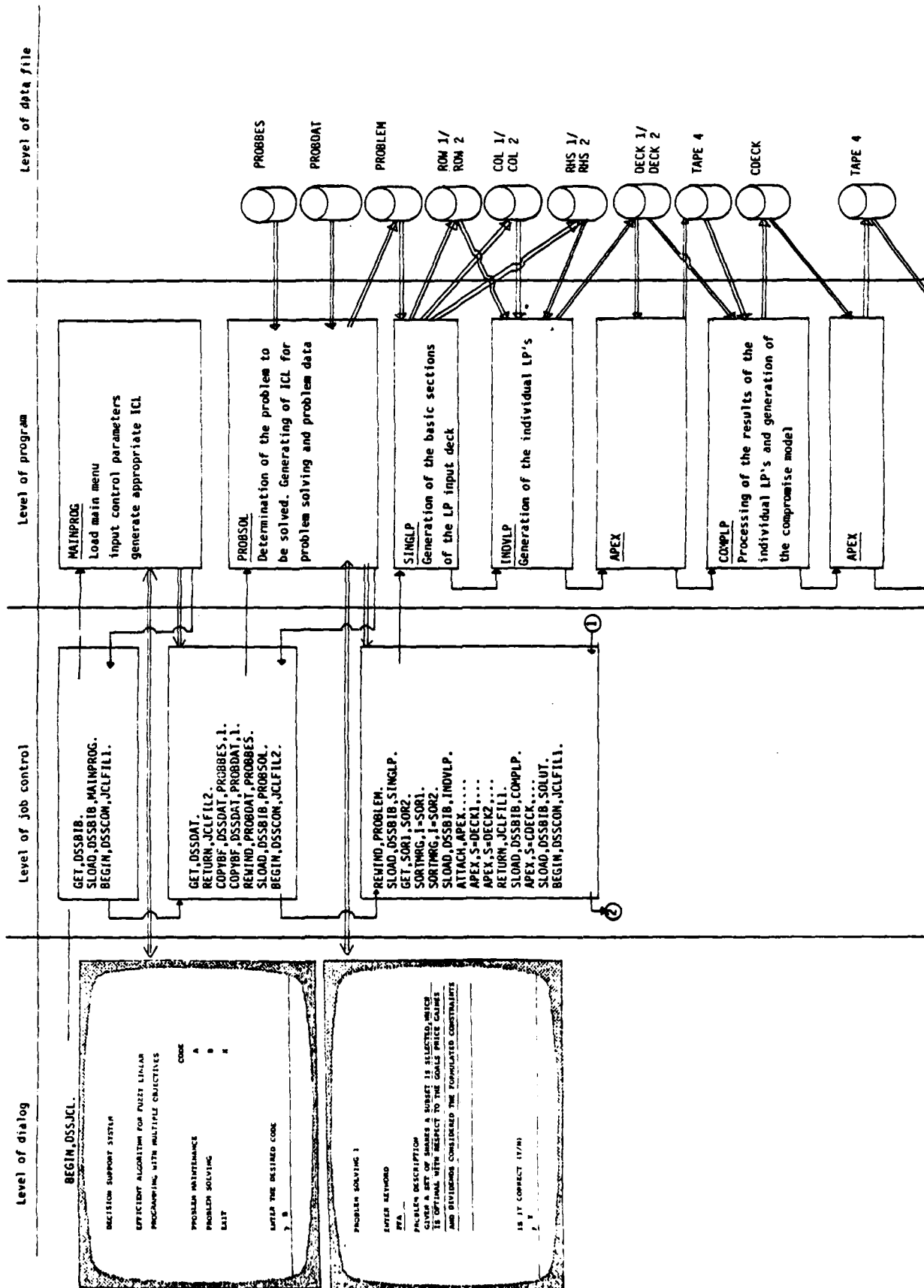
- level of dialog
- level of job control
- level of data files
- level of programs.

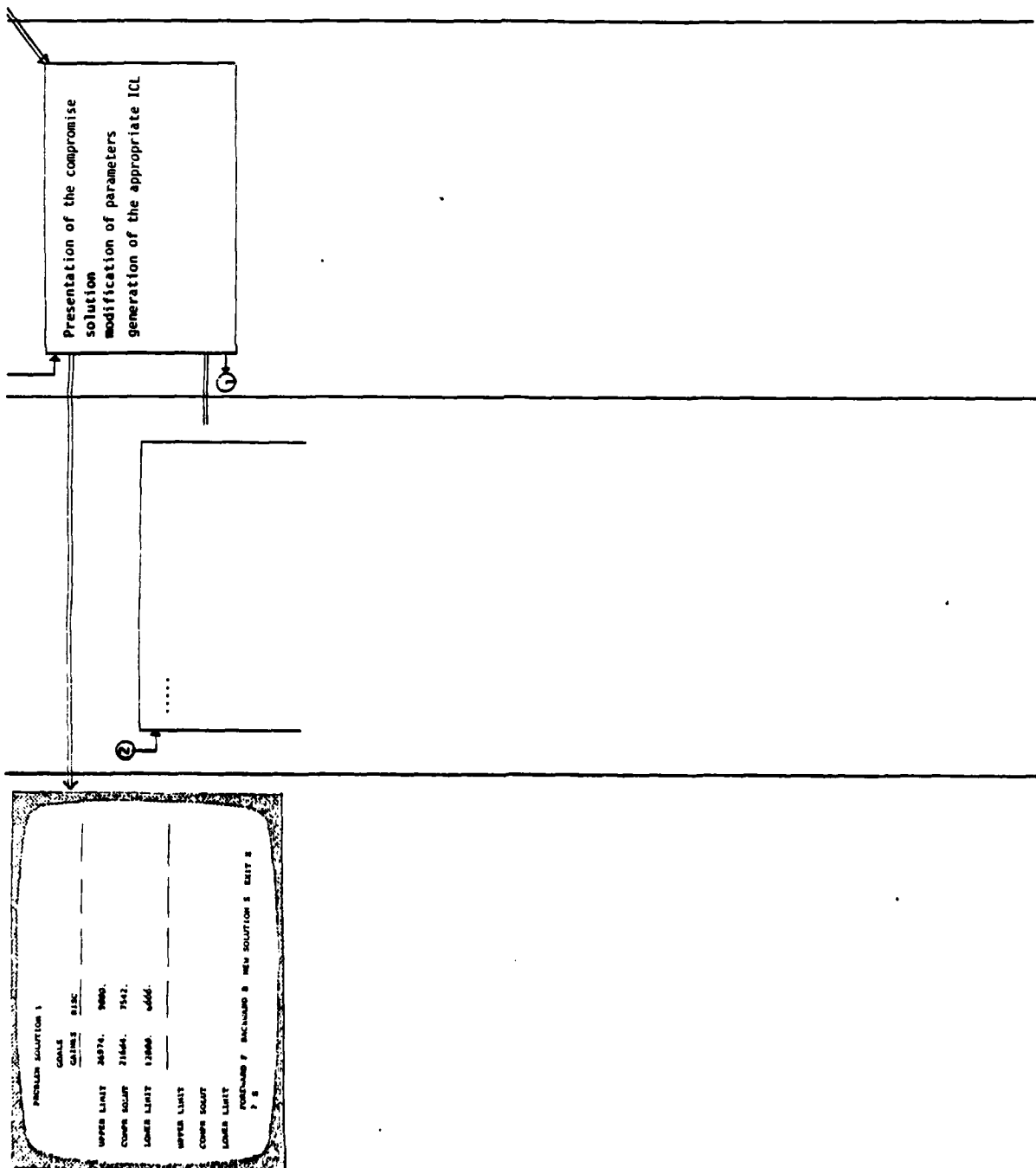
We shall represent, for instance, the input of a new problem and the solution of this problem. We will omit the complete representation of all masks for reasons of space.

In the following a single arrow denotes a flow of control, a double one a flow of data.









IV.2 Description of the data files

IV.2.1 Survey

data file	modul	MAINPROG	MAINTEN1	PROBSOL	SINGLP	INDVLP	COMPLP	APEX	SOLUT
PROBBES		PU							
PROBDAT		PU		PR			PR		
PROBLEM				WW	WR				PR
ROW1/2					WW	WR			
COL1/2					WW	WR			
RHS1/2					WW	WR			
DECK1/2						WW	WR	WR	
TAPE4							WR	WW	WR
CDECK							WW	WR	WU

Legend:

PR - } library file { reading
 PW - } writing
 PU - } modifying

WR - } working file { reading
 WW - } writing
 WU - } modifying

IV.2.2 Detailed descriptions

IV.2.2.1 PROBES

General informations

Name of the file: PROBES
Organization: sequential
Type of file: permanent library modul
Record length: ≤ 364 characters
Max. number of records: according to the stored problem descriptions
which have come in during the processing
Short description: File contains a global short description of the
present problems.

structure of record

format of record

creation in

use in

modification in

ISUCH	PROBNAME	MAX	MIN	FILE
A(3)	A(20)	I2	I2	I2
CREAT	CREAT	CREAT	CREAT	CREAT
MAINTEN 1	MAINTEN 1	MAINTEN 1	MAINTEN 1	MAINTEN 1
UPDTE	UPDTE	UPDTE	UPDTE	UPDTE

FGE	FEQ	CLE	CGE	CEQ	LAENGE
I2	I2	I2	I2	I2	I(5)
CREAT	CREAT	CREAT	CREAT	CREAT	CREAT
MAINTEN 1	MAINTEN 1	MAINTEN 1	MAINTEN 1	MAINTEN 1	MAINTEN 1
UPDTE	UPDTE	UPDTE	UPDTE	UPDTE	UPDTE

BESCH				
A(320)				
CREAT				
MAINTEN 1				
UPDTE				

ISUCH - 3 digit alphanumerical searching key for determination of the
 problem to be processed
 PROBNAME - 20 digit alphanumerical name of the problem
 MAX - 2 digit numerical number of maximizing objectives
 MIN - " " " " " minimizing objectives
 FLE - " " " " " fuzzy \leq - restrictions
 FGE - " " " " " fuzzy \geq - restrictions
 FEQ - " " " " " fuzzy - restrictions
 CLE - " " " " " crisp \leq - restrictions
 CGE - " " " " " crisp \geq - restrictions
 CEQ - " " " " " crisp - restrictions
 LAENGE - 5 digit numerical description of the length of problem data
 in records
 BESCH - contains a short formulation of the actual problem (up to
 320 alphanumerical signs)

IV.2.2.2 PROBDAT

General information:

Name of the file: PROBDAT
 Organization: sequential
 Type of file: permanent multiframe library modul
 Record length: ≤ 34 characters
 Max. number of records: summation of the contents of the array LAENGE in
 the file "PROBES"
 Short description: file contains the initial data of all stored
 problems

RCTYP	RCNAME	RCNAMI	RANBON	
I2	A(20)	A(10)	I1	
CREAT	CREAT	CREAT	CREAT	
MAINTEN1/PROBSOL				
UPDTE	UPDTE	UPDTE	UPDTE	

structure of record
format of record
creation in
use in
Modification in

Redefinition

RCTYP	VARANZ	BLO	B	BUP	
I2	I2	F10.4	F10.4	F10.4	
CREAT	CREAT	CREAT	CREAT	CREAT	
UPDTE	UPDTE	UPDTE	UPDTE	UPDTE	

Redefinition

RCTYP	VARNO	VWERT			
I2	I2	F10.4			
CREAT	CREAT	CREAT			
UPDTE	UPDTE	UPDTE			

```

RCTYP  - type of the following records
        1 - maximizing objective
        2 - minimizing objective
        3 - fuzzy  $\leq/\geq$  - restriction
        4 - fuzzy = - restriction
        5 - crisp  $\leq/\geq$  - restriction
        6 - crisp = - restrictions
        7 - variable without bounds
        8 - variable with bounds
        10 - row description
        20 - input of coefficients
RCNAME - user name of rows and columns
RCNAMEI - internal name of rows and columns
RANBON - characterization whether variable is bounded
VARANZ - number of NNE in a row
BLO    - values of the right hand side  $BLO \leq B \leq BUP$  for fuzzy restrictions;
  B    - for fixed restrictions only B is given
BUP    -
VARNO  - number of a variable in a row
VWERT  - value of coefficient

```

IV.2.2.3 Problem

General information:

Name of the file:	PROBLEM
Organization:	index-sequential
Type of file:	working
Record length:	variable
Max. number of records:	according to the number of functions of the problem to be solved
Short description:	File contains processed initial problem for generating the single LP/MIP model formulations

Structure of data record

words:	1	2	3	...	n
	Integer	Integer	variable section		
	type of record	record length			

Type of record: 1 characterization of the problem

2 max - objective

3 min - objective

4 fuzzy objective \leq

5 fuzzy objective \geq

6 fuzzy objective $=$

7 crisp objective \leq

8 crisp objective \geq

9 crisp objective $=$

Type 1:

* max OF	* min OF	* FR \leq	* FR \geq	* FR $=$	* CR \leq	* CR \geq	* CR $=$
----------	----------	-------------	-------------	----------	-------------	-------------	----------

Type 2 + 3:

column index	value
--------------	-------

Type 4 + 5:

<u>b</u>	\bar{b}	column index	value	...
----------	-----------	--------------	-------	-----

Type 6:

<u>b</u>	b	\bar{b}	column index	value	...
----------	---	-----------	--------------	-------	-----

Type 7 - 9:

RHS	column index	value	...
-----	--------------	-------	-----

IV.2.2.4 APEX input data files

General information

Name of the file: ROW1 / ROW2, COL1 / COL2, RHS1 / RHS2, DECK1 / DECK2,
CDECK
Organization: sequential
Type of file: working
Record length: ≤ 72 characters
Max. number of records: $\leq 2 * \text{number of functions} + \text{number NNE of the}$
coefficient matrix + 10
Short description: data files contains APEX input structures
(For further informations see APEX III, Reference Manual, CDC,
Publ.-No. 76070000, 1976)

IV.2.2.5 TAPE 4

General information:

Name of the file: TAPE 4
Organization: sequential
Type of file: working
Record length: 70 characters
Max. number of records: number of functions + number of variables + 3
Short description: file contains special APEX output which can be
processed by FORTRAN programs

Each solution file contains two header records, with each record being seven 60-bit words in length. The first header contains the following information:

<u>Word</u>	<u>CR Cell</u>	<u>Type</u>	<u>Description</u>
1	KNPROB	Alpha	Name of problem
2	KNOBJ	Alpha	Name of objective function
3	KNRHS	Alpha	Name of right-hand side
4	KNBND	Alpha	Name of bounds set or blank
5	RPSOBJ	Real	Multiplier of objective, usually +1. or -1.
6	RPSRHS	Real	Multiplier of right-hand side, usually +1.
7	RDOBJFN	Real	Current value of objective function

The second header contains the following information:

<u>Word</u>	<u>CR Cell</u>	<u>Type</u>	<u>Description</u>
1	KNCHOBJ	Alpha	Name of change objective function or blank
2	KNCHRHS	Alpha	Name of change right-hand side or blank
3	KNRNG	Alpha	Name of ranges set or blank
4	RPCHOBJ	Real	Multiplier of change objective function or zero
5	RPCHRHS	Real	Multiplier of change right-hand side or zero
6	LJROWS	Integer	Number of rows in the problem
7	LJCOLS- LKRHS	Integer	Number of columns in the problem, excluding right-hand sides

A seven-word record (60 bits per word) is written for each row and column (excluding right-hand sides) in the problem. All row records are described first, followed by column records.

The row detail record includes the following information:

<u>Word</u>	<u>Type</u>	<u>Description</u>
1	Alpha	Name of the row
2	Real	Row activity level
3†	Real	Slack activity
4†	Real	Right-hand side lower limit
5†	Real	Right-hand side upper limit
6†	Real	Marginal value (dual)
7†	Octal	Special packed word

Similarly, the column detail record contains:

<u>Word</u>	<u>Type</u>	<u>Description</u>
1	Alpha	Name of the column
2	Real	Activity level of the column
3	Real	Original cost (objective coefficient)
4†	Real	Column lower bound
5†	Real	Column upper bound
6	Real	Marginal value (d_j or reduced cost)
7†	Octal	Special packed word

As indicated, word 7 is a special word. Its information is packed in the following form:

<u>Bits</u>	<u>Value</u>	<u>Description</u>
59-58	00	Variable is okay
	01	Reserved for future use
	10	Variable is nonoptimal
	11	Variable is infeasible
		NOTE: A sign test specifies whether the variable is nonoptimal or infeasible
57-30	0	Reserved for future use
29-12	—	Variable number according to input order
11-10	—	Basis status, including the following four types of status:
	00	• Nonbasic status
	01	• Nonbasic at upper bound status
	10	• Basic status
	11	• Reserved for future use
9-8		Variable type, including the following four types of variables:
		COLUMN TYPE (ROW TYPE)
	00	• Fixed (E = EQUALITY)
	01	• Plus (L = LESS THAN OR EQUAL)
	10	• Minus (G = GREATER THAN OR EQUAL)
	11	• Free (N = FREE (NONCONSTRAINING))
7	—	Upper bound indicator specifying one of the following two conditions: (The U bit) [†]
	0	• No upper bound
	1	• Upper bound exists
6	—	Lower bound indicator (columns only) specifying either: (The L bit) [†]
	0	• No lower bound (lower is zero)
	1	• Lower bound exists
5-0	—	Variable type, including one of the following types of variable:
	00	• Row variable
	01	• Column variable
	02	• Binary variable
	04	• Integer variable
	05	• Type 1 SOS variable
	06	• Type 2 SOS variable

A final seven-word record is written to indicate the end of the special file. It takes the following form:

<u>Word</u>	<u>Type</u>	<u>Description</u>
1	Alpha	\$\$END\$\$bbb (where b = blank)
2-7	—	zero

IV.3 Description of the program

IV.3.1 MAINTEN 1

Name: MAINTEN 1

Task: processing of all maintenance activities for the data of the appropriate CCL procedures

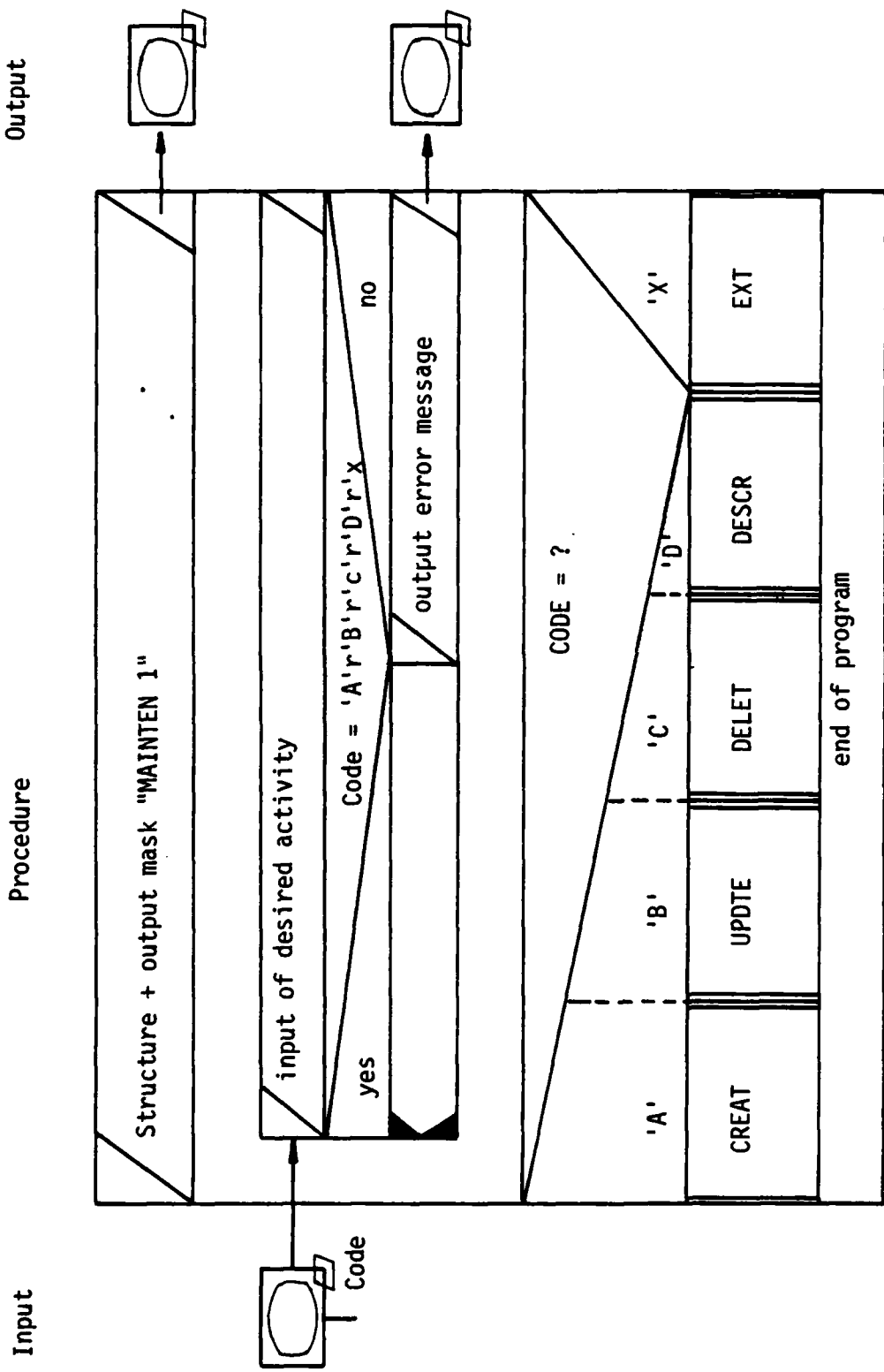
Language: FORTRAN

Status: - calling programs: MAINCCL

- called programs: CREAT, DELET, DESCR, UPDTE, EXT
control procedure
main program
subroutine

- mode: dialog

Data
files: PROBDAT, PROBBES



IV.3.2 CREAT

Name:

Task: input of data for problem description and problem, formal check
of these data storage in the data files PROBDAT and PROBBES

Language: FORTRAN

Status: - calling programs: MAINTEN 1

- called programs: --

control procedure

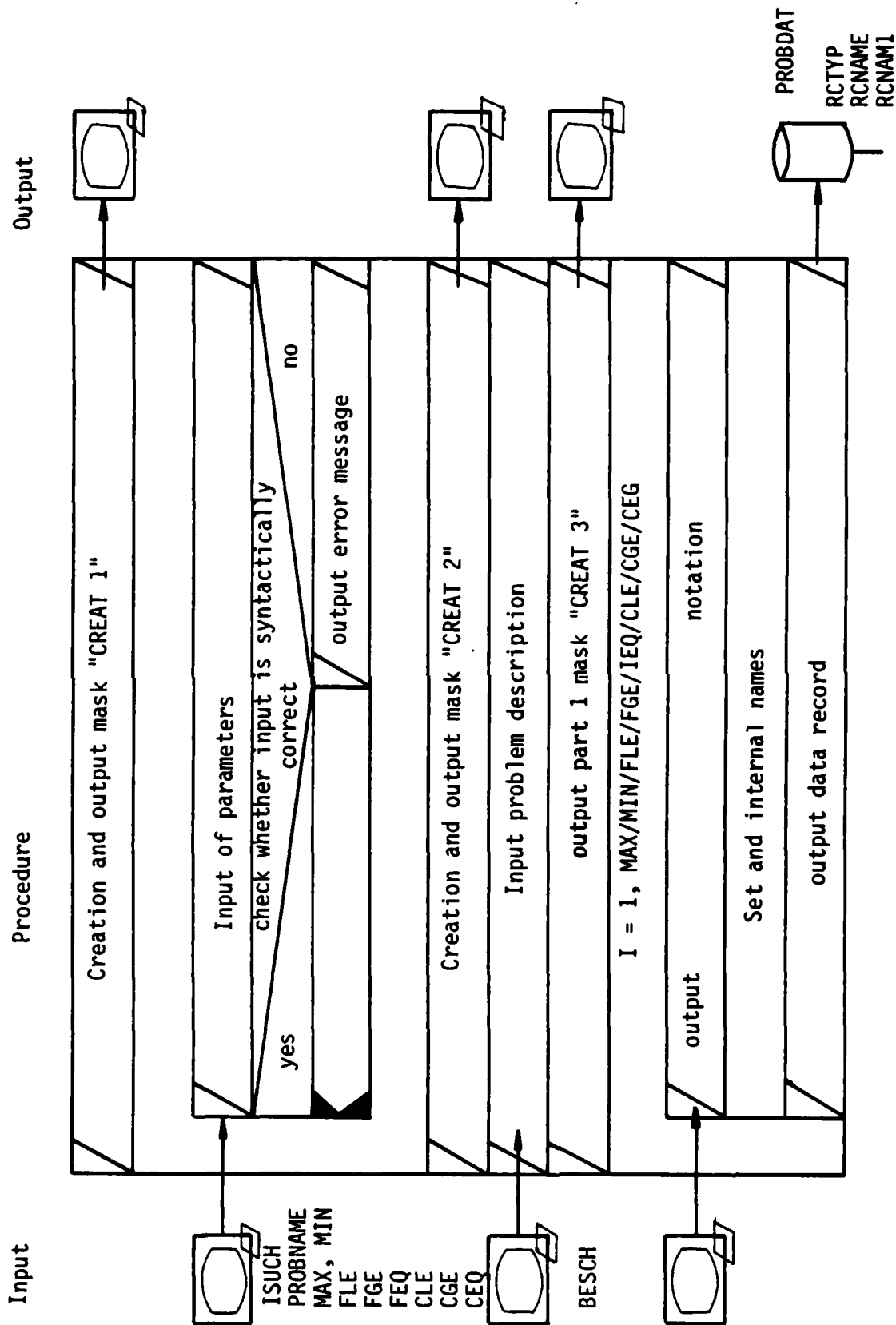
main program

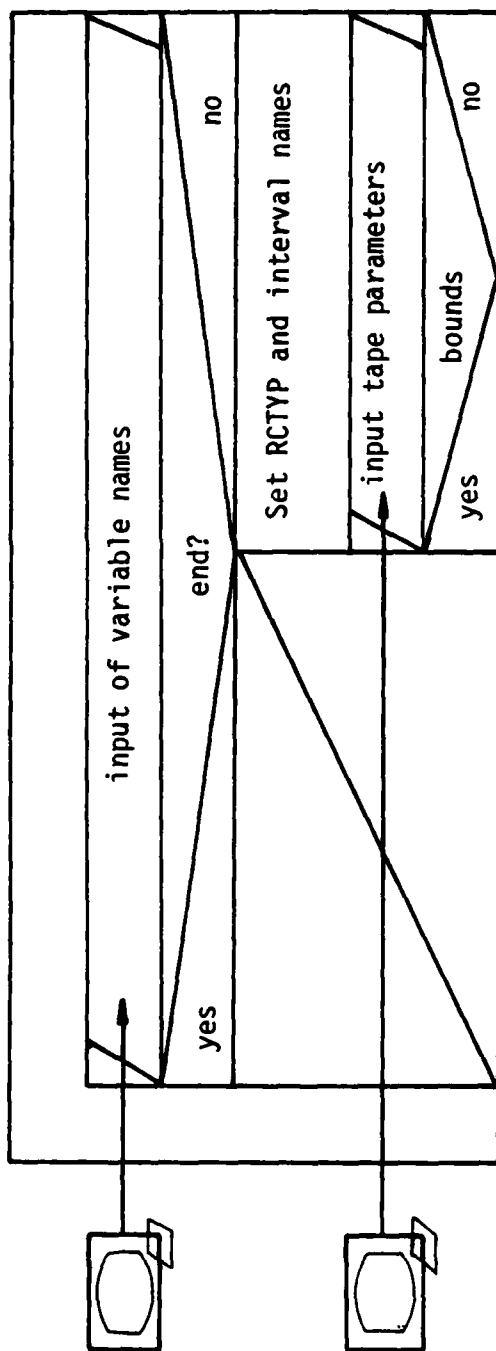
subroutine

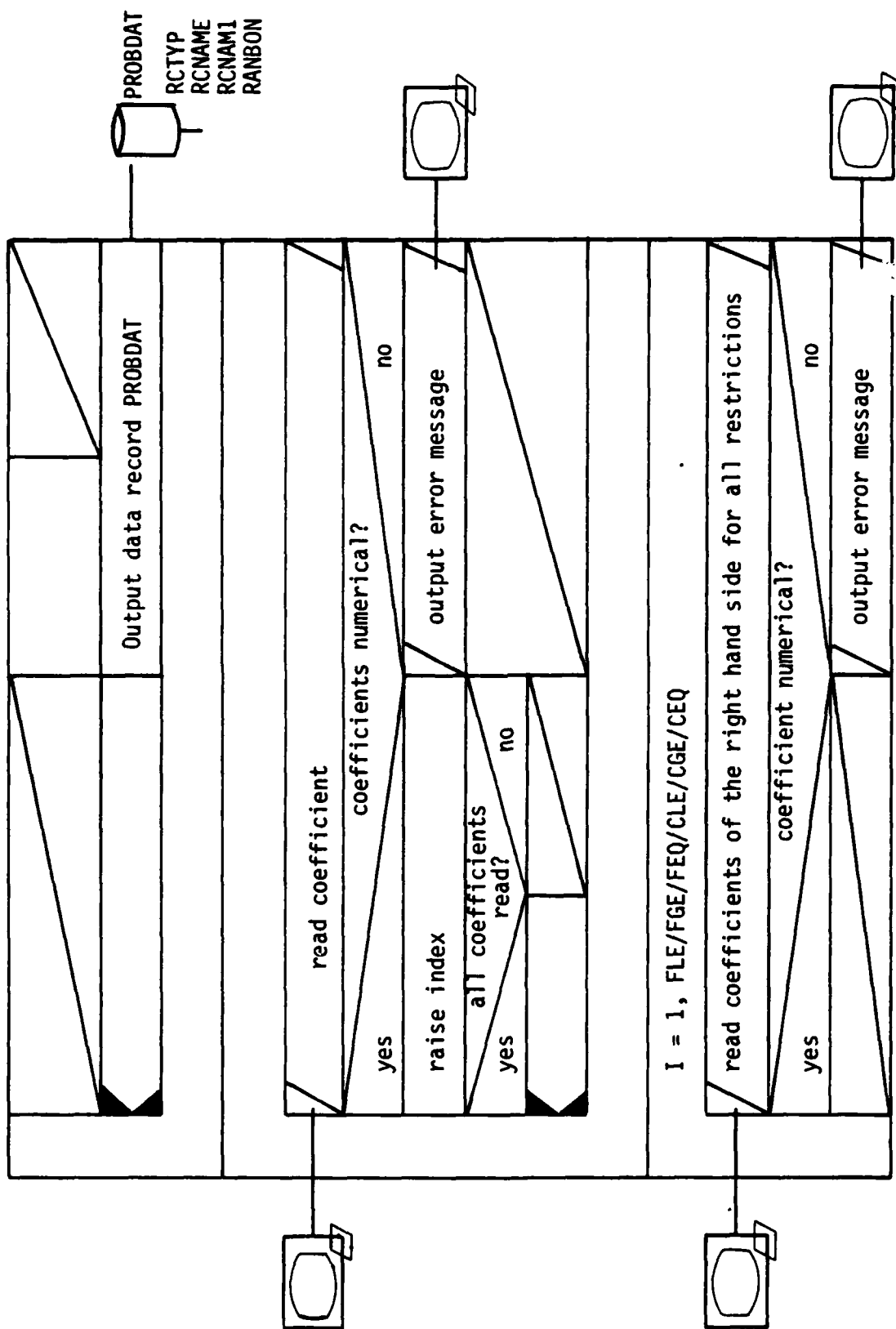
- mode: dialog

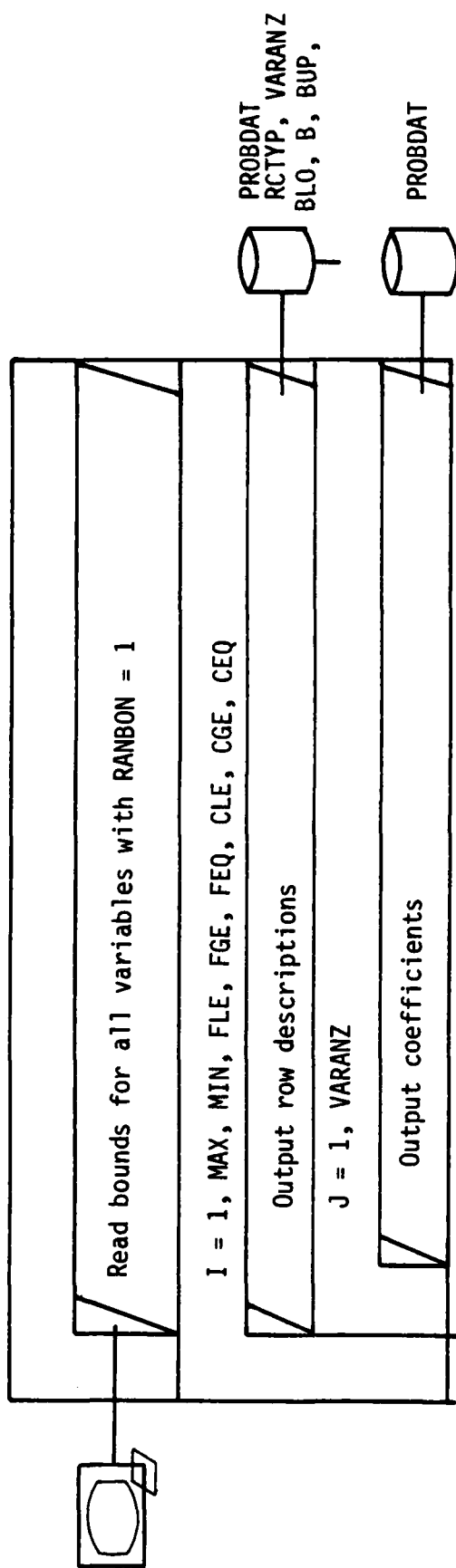
Data

files: PROBDAT, PROBBES









IV.3.3 DELET

Name: DELET

Task: delete all data of a problem both in the file of description
and of problem, reorganisation of these data files

Language: FORTRAN

Status: - calling programs: MAINTEN 1

- called programs: --

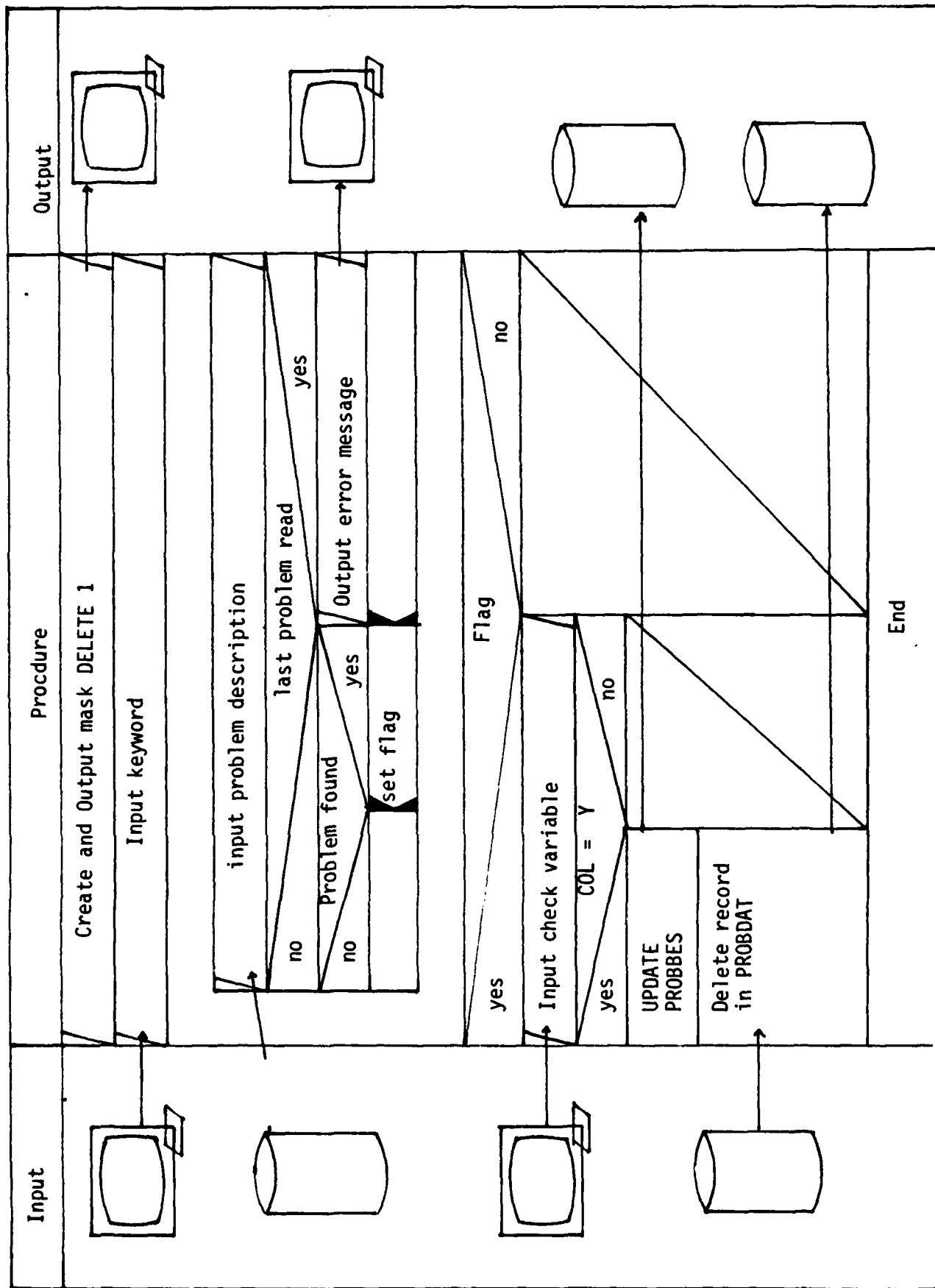
control procedure

main program

soubroutine

- mode: dialog

Data files: PROBDAT, PROBBES



IV.3.4 DESCR

Name: DESCR

Task: This program enables the decision maker to page in the data file of problem description and to search for a particular problem

Language: FORTRAN

Status: - calling programs: MAINTEN 1

- called programs: --

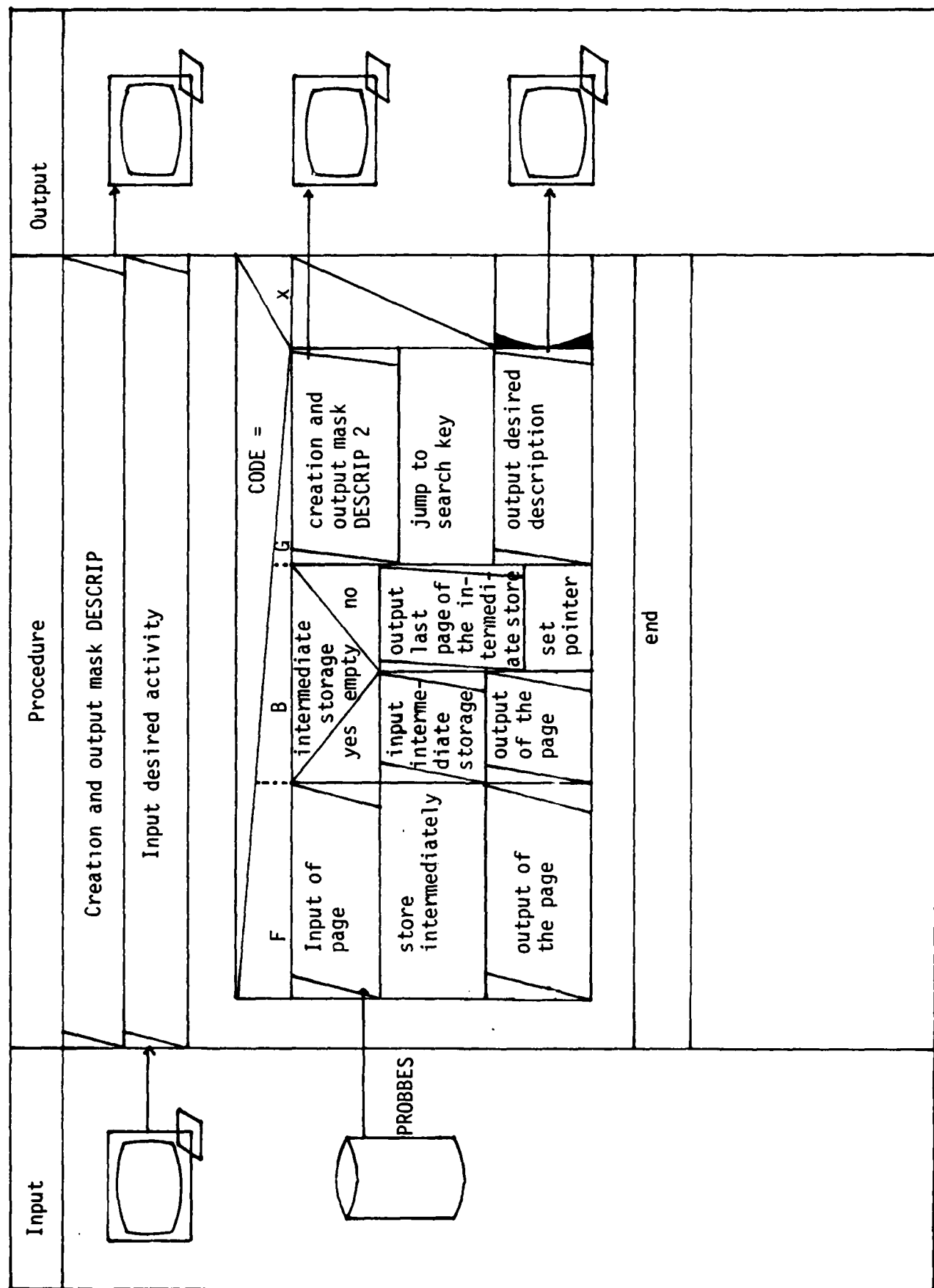
control procedure

main program

subroutine

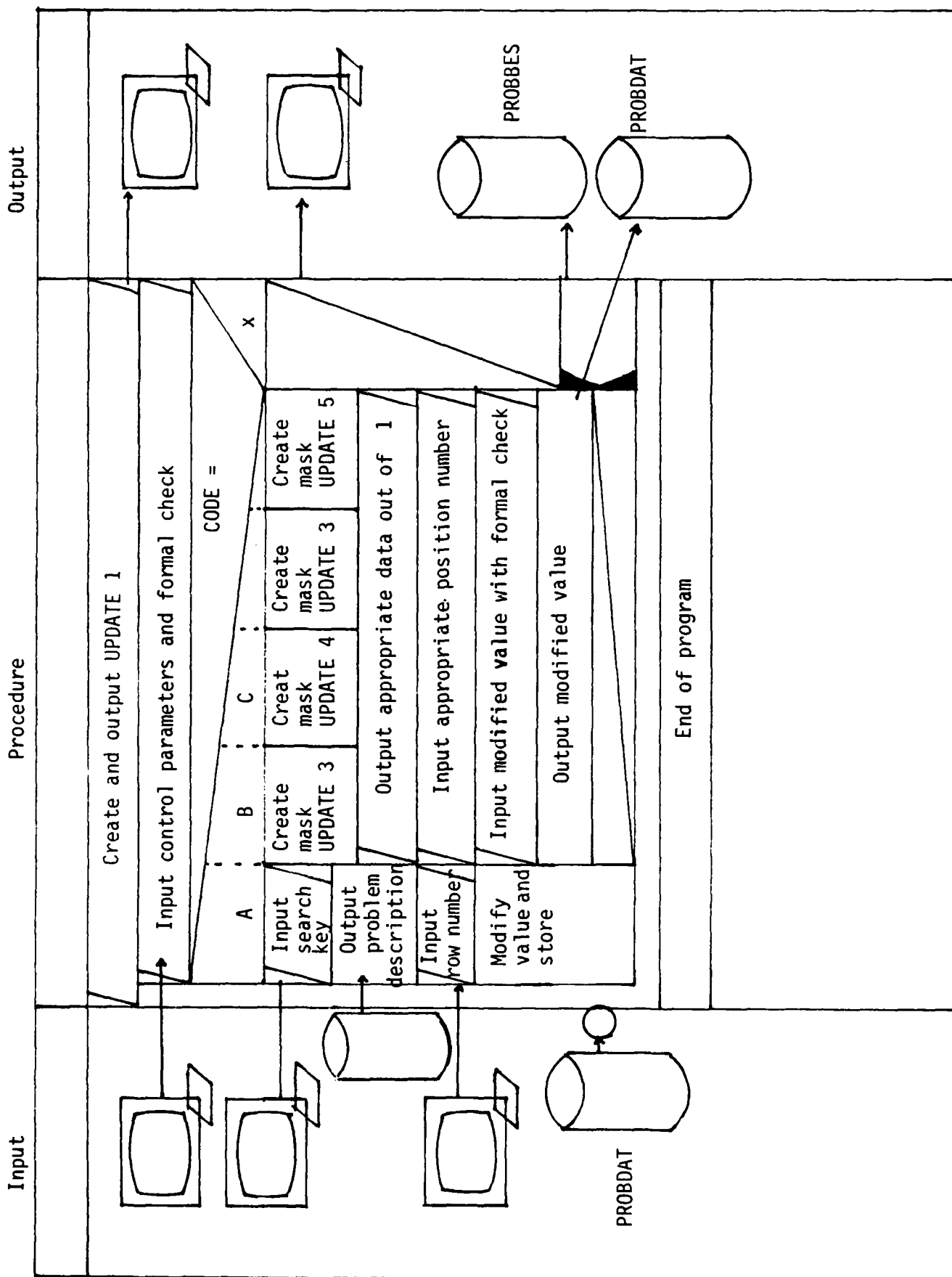
- mode: dialog

Data files: PROBDAT, PROBBES



IV.3.5 UPDTE

Name: UPDTE
Task: change single data of a problem in the data files PROBDAT and
PROBBES
Language: FORTRAN
Status: - calling programs: MAINTEN 1
- called programs: --
control procedure
main program
subroutine
- mode: dialog
Data files: PROBDAT, PROBBES



IV.3.6 EXT

Name: EXT

Task: according to the program activities desired in MAINTEN 1 create a job control file which now controls the system "DSS" and which returns to the main menu after termination

Language: FORTRAN

Status: - calling programs: MAINTEN 1
 - called programs: --
 control procedure
 main program
 subroutine

- mode: dialog

Data files: PROBDAT, PROBBES

IV.3.7 PROBSOL

Name: PROBSOL

Task: extract a data record of the library data file PROBDAT and create an index sequential data file PROBLEM for further processing

Language: PASCAL

Status: - calling programs: MAINCCL
 - called programs: --
 control procedure
 main program
 subroutine

- mode: Batch

Data files: PROBDAT, PROBLEM

IV.3.8 SINGLP

Name: SINGLP

Task: create the individual LP's for determination of \underline{C} and \bar{C}

Language: PASCAL

Status: - calling programs: MAINCCL

- called programs: --

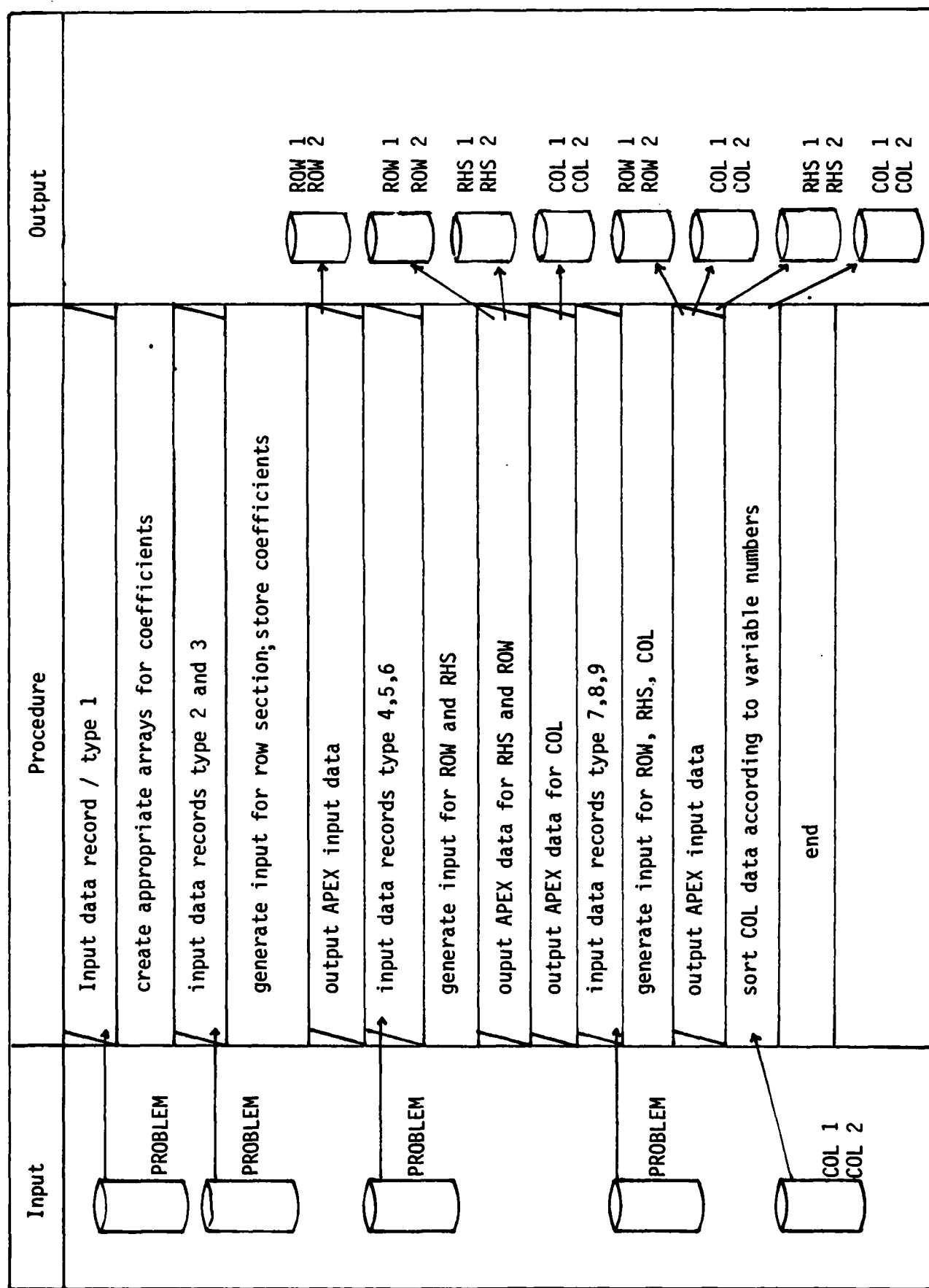
control procedure

main program

subroutine

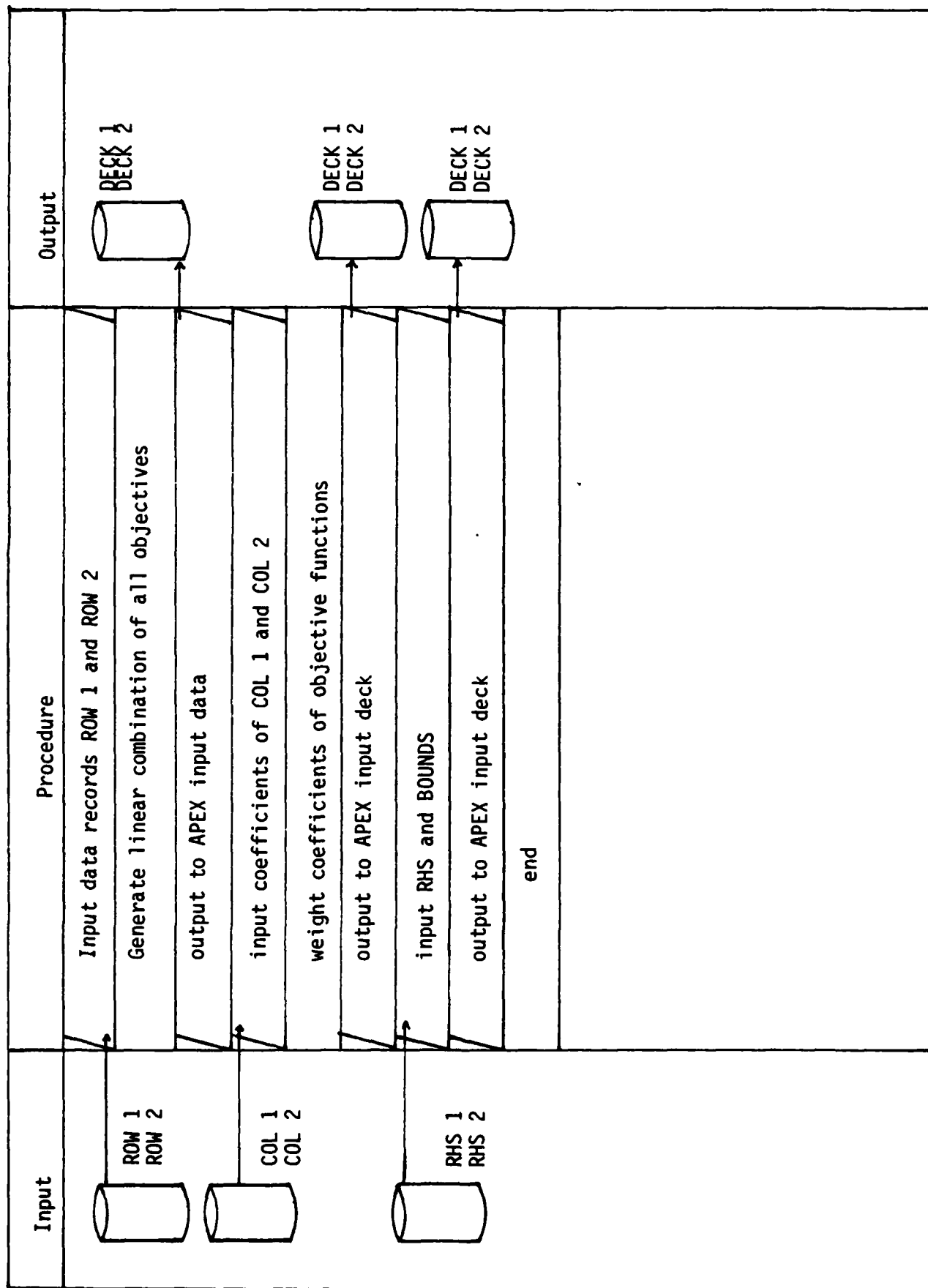
- mode: Batch

Data files: PROBLEM, ROW 1/ ROW 2, COL 1/COL 2, RHS 1/RHS 2



IV.3.9 INDVLP

Name: INDVLP
Task: take over the weighted objective functions to the individual LP's
Language: PASCAL
Status: - calling programs: MAINCCL
 - called programs: --
 control procedure
 main program
 subroutine
 - mode: Batch
Data files: ROW 1/ROW 2, COL 1/COL 2, RHS 1/RHS 2, DECK 1/ DECK 2



IV.3.10. COMPLP

Name: COMPLP

Task: take over the results of the individual LP's; compute the coefficients of the compromise LP; create data structure of APEX

Language: FORTRAN

Status: - calling programs: MAINCCL

- called programs: --

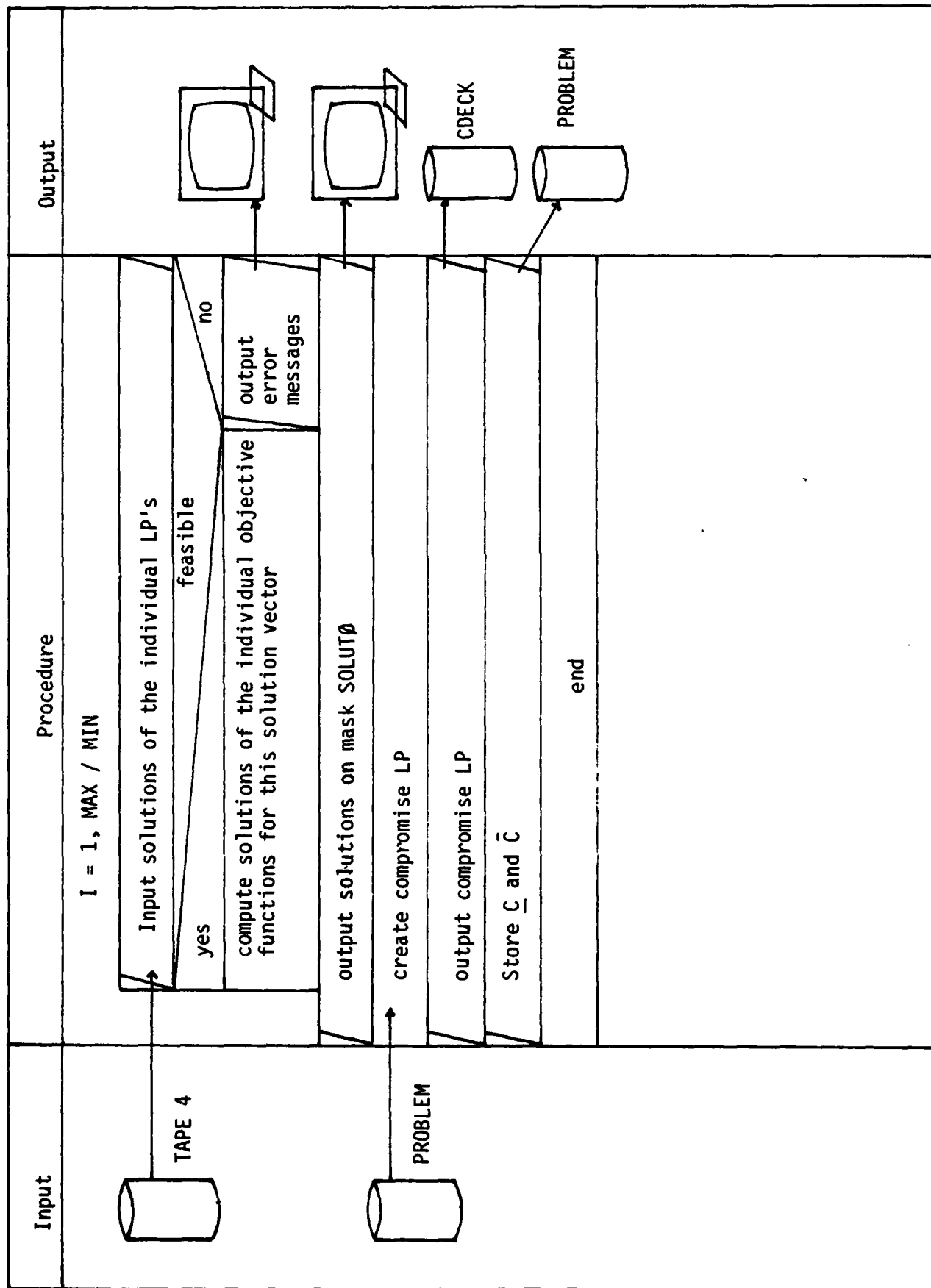
control procedure

main program

subroutine

- mode: Batch

Data
files: TAPE 4, CDECK



IV.3.11 SOLUT

Name: SOLUT

Task: take over the results of a compromise LP; processing and output of the solutions in dialog; modify the coefficients of the compromise LP's, if desired by the decision maker; create the modified data structure for APEX

Language: FORTRAN

Status: - calling programs: MAINCCL

- called programs: --

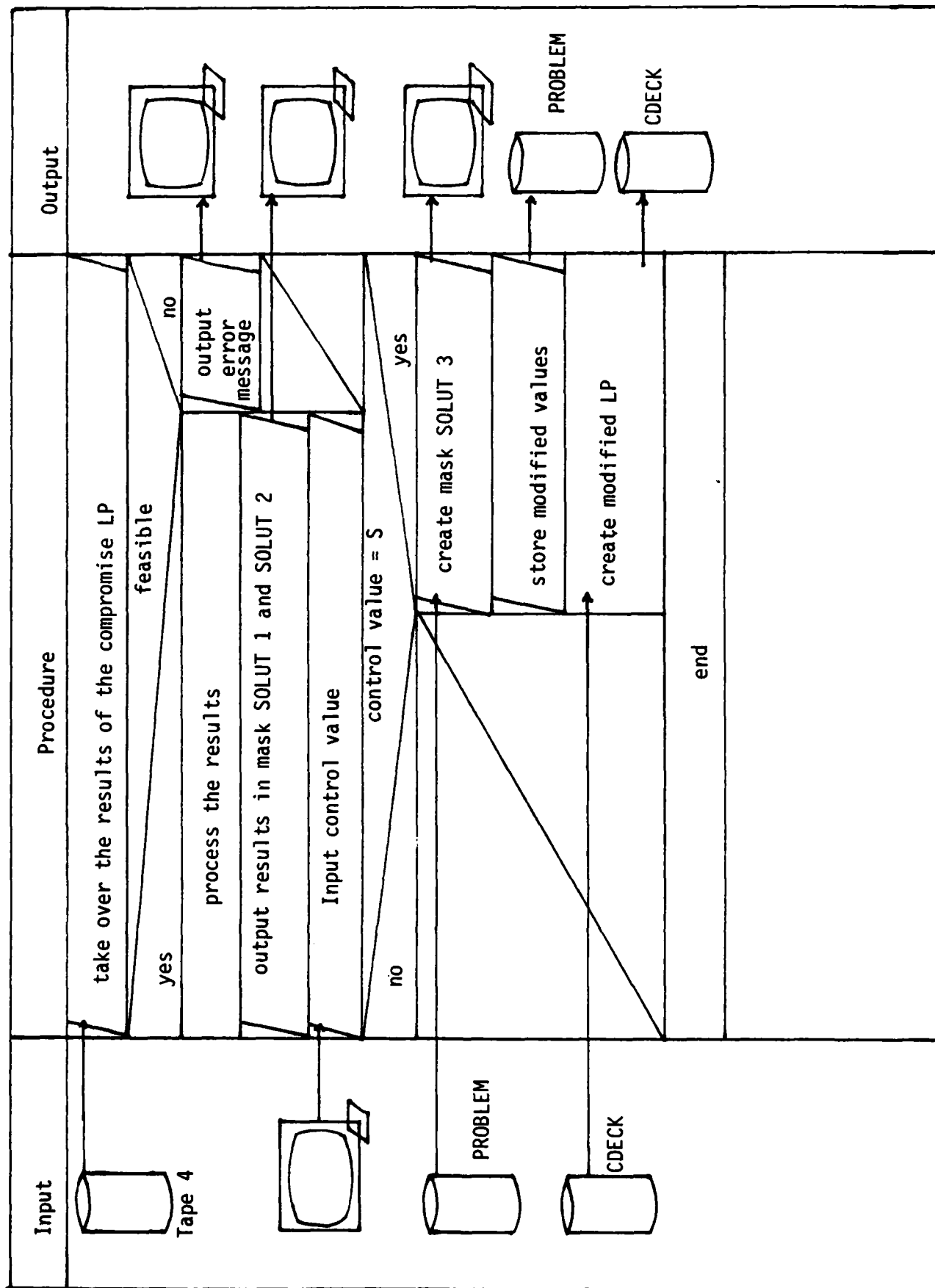
control procedure

main program

subroutine

- mode: dialog

Data files: CDECK, TAPE 4, PROBLEM



IV.3.12 MAINCCL

Name: MAINCCL

Task: MAINCCL represents a local file, on which the job control commands still to be processed are stored. MAINCCL selects the individual programs and is changed by these programs according to the wishes of the decision maker. Examples of the contents of MAINCCL are given in the chapter on the structure of the system

Language: NOS 1.4 - CCL

Status: - calling programs: ---

- called programs: MAINTEN 1, PROBSOL, SINGLP, INDVLP, COMPLP,
SOLUT

control procedure

main program

subroutine

- mode: Batch

Data files: ---

Error message	Program interrupt	Expected activity of men	Origin
Please enter correct code (A,B,C,D,X)	no	revise input	MAINTEN 1
Please enter numerical value	no	revise input	CREAT, UPDTE, COMPLP, SOLUT
The following signs are not allowed in the keyword ' , ' , ' , ' , '	no	revise input	CREAT
Problem 'xxx' is not feasible	no	modify coefficients	COMPLP, SOLUT
Record type 'xxx' in PROBLEM missing	yes	revise file	SINGLP, SOLUT
Incorrect record type in PROBLEM	yes	revise file	SINGLP, SOLUT
Incorrect file structure 'xxx'	yes	revise file	SINGLP, INDVLP, COMPLP, SOLUT

IV.5 Masks for dialog

The input of data principally takes place in the last available row in all masks because of the difficulties described in the Sixth Periodic report, page 5. Normally this is row 21.

Rows 23 and 24 serve for the output of error messages and hints.

Remind that the implemented masks are partially processed during the dialog. Thus in some instances the mask will be presented as created after some steps of dialog.

DECISION SUPPORT SYSTEM

EFFICIENT ALGORITHM FOR FUZZY LINEAR
PROGRAMMING WITH MULTIPLE OBJECTIVES

	CODE
PROBLEM MAINTENANCE	A
PROBLEM SOLVING	B
EXIT	X

ENTER THE DESIRED CODE

?

PROBLEM MAINTENANCE

PROBLEM CREATION

PROBLEM UPDATE

PROBLEM DELETION

PROBLEM DESCRIPTION

EXIT

	CODE
	A
	B
	C
	D
	X

ENTER THE DESIRED CODE

?

PROBLEM CREATION 2

PLEASE ENTER THE PROBLEM DESCRIPTION

?

PROBLEM CREATION 3

PLEASE ENTER THE NAMES OF THE CRISP LE-RESTRICTIONS

PLEASE ENTER THE NAMES OF THE CRISP GE-RESTRICTIONS

PLEASE ENTER THE NAMES OF THE CRISP EQ-RESTRICTIONS

PLEASE ENTER NAME AND TYPE OF VARIABLES

?

PROBLEM CREATION 1

KEYWORD XXX

PROBLEMNAME XXXXXXXXXXXXXXXXXXXXXXXX

NUMBER OF MAXIMIZING GOALS 99

NUMBER OF MINIMIZING GOALS 99

NUMBER OF FUZZY LE-RESTRICTIONS 99

NUMBER OF FUZZY GE-RESTRICTIONS 99

NUMBER OF FUZZY EQ-RESTRICTIONS 99

NUMBER OF CRISP LE-RESTRICTIONS 99

NUMBER OF CRISP GE-RESTRICTIONS 99

NUMBER OF CRISP EQ-RESTRICTIONS 99

?

PROBLEM CREATION 3

PLEASE ENTER THE NAMES OF THE MAXIMIZING GOALS

PLEASE ENTER THE NAMES OF THE MINIMIZING GOALS

PLEASE ENTER THE NAMES OF THE FUZZY LE-RESTRICTIONS

PLEASE ENTER THE NAMES OF THE FUZZY GE-RESTRICTIONS

PLEASE ENTER THE NAMES OF THE FUZZY EQ-RESTRICTIONS

?

PROBLEM CREATION 5		
ROWNAME	LOWER BOUND	UPPER BOUND

PLEASE ENTER BOUND VALUES (RETURN IS ZERO)

?

PROBLEM CREATION 4

ROWS	/ COLUMNS
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____
_____	_____

ENTER VALUES (RETURN IS ZERO)

?

PROBLEM CREATION 6	
VARIABLE	LOWER BOUND UPPER BOUND

PLEASE ENTER BOUND VALUES (RETURN IS ZERO)
?

PROBLEM UPDATE 2

ENTER KEYWORD

PROBLEM DESCRIPTION

1 KEYWORD

2 PROBLEMNAME

3 NUMBER OF MAXIMIZING GOALS

4 NUMBER OF MINIMIZING GOALS

5 NUMBER OF FUZZY LE-RESTRICTIONS

6 NUMBER OF FUZZY GE-RESTRICTIONS

7 NUMBER OF FUZZY EQ-RESTRICTIONS

8 NUMBER OF CRISP LE-RESTRICTIONS

9 NUMBER OF CRISP GE-RESTRICTIONS

0 NUMBER OF CRISP EQ-RESTRICTIONS

ENTER NUMBER OF LINE TO CHANGE

?

ENTER VALUE

?

PROBLEM UPDATE 4

VARIABLE	LOWER BOUND	UPPER BOUND
1	2	3
4	5	6
7	8	9
10	11	12
13	14	15
16	17	18
19	20	21
22	23	24
25	26	27
28	29	30

ENTER THE NUMBER OF VALUE TO CHANGE/ ENTER VALUE

?

PROBLEM UPDATE 1

CHANGE DESCRIPTION	CODE
CHANGE ROWS	A
CHANGE COLUMNS	B
CHANGE RHS	C
CHANGE COEFFICIENTS	D
EXIT	E
	X

ENTER THE DESIRED CODE

?

PROBLEM UPDATE 3

ROWNAME	LOWER BOUND	BOUND	UPPER BOUND
1	2	3	4
5	6	7	8
9	10	11	12
13	14	15	16
17	18	19	20
21	22	23	24
25	26	27	28
29	30	31	32
33	34	35	36
37	38	39	40

ENTER THE NUMBER OF VALUE TO CHANGE/ ENTER VALUE

?

PROBLEM DESCRIPTION 1

FORWARD F BACKWARD B SEARCH S EXIT X
?

PROBLEM DELETION

ENTER THE KEYWORD OF THE PROBLEM TO BE DELETED

PROBLEMDISCUSSION

ARE YOU SURE (Y/N)
?

PROBLEM UPDATE 5
/ COLUMNS

ROWS	1	2	3	4	5	6	7
8	9	10	11	12	13	14	
15	16	17	18	19	20	21	
22	23	24	25	26	27	28	
29	30	31	32	33	34	35	
36	37	38	39	40	41	42	
43	44	45	46	47	48	49	
50	51	52	53	54	55	56	
57	58	59	60	61	62	63	
64	65	66	67	68	69	70	

ENTER THE NUMBER OF VALUE TO CHANGE/ ENTER VALUE
?

PROBLEM DESCRIPTION 2

ENTER KEYWORD

PROBLEM DESCRIPTION
KEYWORD
PROBLEMNAME
NUMBER OF MAXIMIZING GOALS
NUMBER OF MINIMIZING GOALS
NUMBER OF FUZZY LE-RESTRICTIONS
NUMBER OF FUZZY GE-RESTRICTIONS
NUMBER OF CRISP EQ-RESTRICTIONS
NUMBER OF CRISP LE-RESTRICTIONS
NUMBER OF CRISP GE-RESTRICTIONS

PROBLEM SOLUTION ϕ

/ GOALS

SOLUTION _____

UPPER LIMIT

LOWER LIMIT

PROBLEM SOLUTION 2

FUZZY RESTRICTIONS

UPPER LIMIT _____

COMPR SOLUT _____

LOWER LIMIT _____

UPPER LIMIT _____

COMPR SOLUT _____

LOWER LIMIT _____

FOREWARD F BACKWARD B NEW SOLUTION S EXIT X

?

PROBLEM SOLVING 1

ENTER KEYWORD _____

PROBLEM DESCRIPTION

IS IT CORRECT (Y/N)

?

PROBLEM SOLUTION 1

GOALS

UPPER LIMIT _____

COMPR SOLUT _____

LOWER LIMIT _____

UPPER LIMIT _____

COMPR SOLUT _____

LOWER LIMIT _____

FOREWARD F BACKWARD B NEW SOLUTION S EXIT X

?

PROBLEM SOLUTION 3	
GOALS / FUZZY RESTRICTIONS	
UPPER LIMIT 1	2 3 4 5
LOWER LIMIT 6	7 8 9 10
UPPER LIMIT 11	12 13 14 15
LOWER LIMIT 16	17 18 19 20

ENTER THE NUMBER OF VALUE TO CHANGE
?
ENTER VALUE
?

Appendix

Exemplarily the listing of 2 programs is shown in the appendix.


```

PROGRAM SINGEL(INPUT, OUTPUT, DATEN1, DATEN2);
CONST BLANK1)='';
N=1000;
EPSI=1.0E-04;
RJWTP1='GJALMAX';
RJWTP2='GJALMIN';
RJWTP3='FRESTLE';
RJWTP4='FRESTGE';
RJWTP5='FRESTE';
RJWTP6='CRESTLE';
RJWTP7='CRESTGE';
RJWTP8='CRESTE';
COLTYP1='VARIABLE';
R4STYP1='R4,FRES';
R4STYP2='R4,SCRES';
TYPE DEFCDEFCHAR=RECORD SPALIND:INTEGER;
                                COEFWERT:REAL      END (*OF COLUMN GEFUNDEN*);
DEFCDEFCHF=ARRAY[1..N] OF DEFCDEFCHAR;
DEFSATZTYP = 1..9;
CHARAR=PACKED ARRAY[1..7] OF CHAR;
CHARFI=FILE OF CHAR;
DATSTRUK1=RECORD
    SATZTYP:DEFSATZTYP;
    SATZLAENGE:INTEGER;
    CASE STYP:DEFSATZTYP OF
        1:(MAXFZ,MINFZ,FRLE,FRGE,FRQ,CRLE,CRGE,CREQ:INTEGER);
        2:(MAXCOEF:DEFCDEFCHF);
        3:(MINCOEF:DEFCDEFCHF);
        4:(FRLEBOQ,FRLEBOQ:REAL;FRLECOEF:DEFCDEFCHF);
        5:(FRGEBOQ,FRGEBOQ:REAL;FRGECOEF:DEFCDEFCHF);
        6:(FREBOQ,FREBOQ:REAL;FRECOEF:DEFCDEFCHF);
        7:(CRLEB:REAL;CRLECOEF:DEFCDEFCHF);
        8:(CRGEB:REAL;CRGECOEF:DEFCDEFCHF);
        9:(CREB:REAL;CRECOEF:DEFCDEFCHF)
    END;
DATSATZ=FILE OF DATSTRUK1;
VAR I,MAXFZ,IMINFZ,IFRLE,IFRGE,IFREQ,ICRLE,ICRGE,ICREQ,LSE,I,J,ERRCODE,RECCODE,
    RECLGE,K:INTEGER;
    RJWW,PROEF3:CHAR;
    ZWI,ZWI2:PACKED ARRAY[1..5] OF CHAR;
    ZWI3:PACKED ARRAY[1..2] OF CHAR;
    PROEF1,PROEF2:CHAR;
    SCHL,KK,SCHLV,LFAR,TYP:INTEGER;
    WERT,MULTI:REAL;
    NAME:PACKED ARRAY[1..40] OF CHAR;
VAP DATEN1:CHARFI;
    DATEN2:CHARFI;

```

Copy available to DTIC does not
 permit fully legible reproduction

```

BEGIN (*OF MAIN PR.*)
(* EINLESEN DER STEUERUNGSPARAMETER *)
RESLT(DATEN1);
READLN; READ(K, LFN, TYP);
(* BERECHNUNG STEUERUNGSWERTE *)
MULTI:=1-(K-1)*EPSI;
SCHL:=ABS(LFN-333*TYP);
IF TYP=2
  THEN RJWW:=RJW1TYP1
  ELSE RJWW:=RJW2TYP2;
(* VERARBEITUNG DATENSATZE *)
WHILE NOT EOF(DATEN1) DO
  BEGIN (*OF READER*)
    FOR I:=1 TO 40 DO NAME[I]:= ' ';
    READ(DATEN1, PRUEF1, PRUEF2);
    (* ABFRAGE, OB ZIELFKT. GUEF *)
    IF (PRUEF1 <> ' ') OR ((PRUEF1=' ') AND ((PRUEF2='X') OR (PRUEF2='D'))))
      THEN BEGIN (* OF JEBERNAME *)
        I:=1;
        IF (PRUEF1=' ') THEN PRUEF1:=' ';
        IF (PRUEF2='X') THEN PRUEF2:=' ';
        WHILE NOT EOF(DATEN1) DO
          BEGIN (*OF ZEICHENEINLES*)
            READ(DATEN1, NAME[I]);
            I:=I+1;
          END (*OF ZEICHENEINLES*);
          READLN(DATEN1);
        WRITE(DATEN2, PRUEF1, PRUEF2);
        FOR J:=1 TO (I-1) DO WRITE(DATEN2, NAME[J]);
        WRITELN(DATEN2, NAME[I]);
        END (*OF JEBERNAME*);
      ELSE BEGIN (*OF JEBERPRUEFUNG*)
        (* ABFRAGE, OB RJW SEKTOR *)
        IF (PRUEF2='E')
          THEN BEGIN (*OF ZIEL GEFUNDEN*)
            READ(DATEN1, ZW13[1], ZW13[2]);
            FOR KK:=1 TO 7 DO READ(DATEN1, PRUEF3[KK]);
            READLN(DATEN1, SCHLV);
            PRUEF1:=' ';
            WRITELN(DATEN2, PRUEF1, PRUEF2, ZW13[2], PRUEF3[7], SCHLV[3]);
          END (*OF ZIEL GEFUNDEN*);
        ELSE BEGIN (*OF COLUMN GEFUNDEN*)
          FOR KK:=1 TO 6 DO READ(DATEN1, ZW12[KK]);
          FOR KK:=1 TO 6 DO READ(DATEN1, ZW12[KK]);
          FOR KK:=1 TO 7 DO READ(DATEN1, PRUEF3[KK]);
          READLN(DATEN1, SCHLV, WERT);
          IF (PRUEF3=RJWW) AND (SCHLV=SCHL)
            THEN BEGIN (*OF HAUPTZIEL*)
              WERT:=WERT*MULTI;
              PRUEF1:=' ';
            END (*OF HAUPTZIEL*);
          ELSE BEGIN (*OF NEBENZIEL*)
              WERT:=WERT*EPSI;
              PRUEF1:=' ';
            END (*OF NEBENZIEL*);
          WRITELN(DATEN2, PRUEF1, PRUEF2, ZW1[5], ZW12[6], PRUEF3[7], SCHLV[3],
            WERT[12:4]);
        END;
      END (*OF JEBERPRUEFUNG*);
    END (*OF READER*);
  END (*OF MAIN PR.*);

```

```

PROGRAM INDVLP(DATENINPUT,OUTPUT,DATENROW1,DATENROW2,DATENCOL1,DATENCOL2,
              DATENRHS1,DATENRHS2);
CONST BLANK1:=#           #;
      N=1000;
      ROWTYP1:=#JALMAX#;
      ROWTYP2:=#JALMIN#;
      ROWTYP3:=#RESTLEE#;
      ROWTYP4:=#RESTGE#;
      ROWTYP5:=#RESTEJ#;
      ROWTYP6:=#CRESTLEE#;
      ROWTYP7:=#CRESTGE#;
      ROWTYP8:=#CRESTEJ#;
      COLTYP1:=#VARIABLE#;
      RASTYP1:=#RHSFRES#;
TYPE DEFCOEFCHAR=RECORD SPALIND:INTEGER;
                        COEFWERT:REAL      END;
DEFCOEFCHF=ARRAY[1..N] OF DEFCOEFCHAR;
DEFSATZTYP = 1..9;
CHARAR=PACKED ARRAY[1..7] OF CHAR;
CHARFI=FILE OF CHAR;
DATSTRUK1=RECORD
      SATZTYP:DEFSATZTYP;
      SATZLAENGE:INTEGER;
      CASE STYP:DEFSATZTYP OF
        1:(MAXFZ,MINFZ,FRLE,FRGE,FREQ,CRLE,CRGE,CREQ:INTEGER);
        2:(MAXCOEF:DEFCOEFCHF);
        3:(MINCOEF:DEFCOEFCHF);
        4:(FRLEBUQ,FRLEBJJ:REAL;FRLECOEF:DEFCOEFCHF);
        5:(FRGEBUQ,FRGEBJJ:REAL;FRGECOEF:DEFCOEFCHF);
        6:(FREGBUQ,FREGB,FREGBBQ:REAL;FREGCCOEF:DEFCOEFCHF);
        7:(CRLEB:REAL;CRLECOEF:DEFCOEFCHF);
        8:(CRGEB:REAL;CRGECOEF:DEFCOEFCHF);
        9:(CREGB:REAL;CREGCCOEF:DEFCOEFCHF)
      END;
DATSATZ=FILE OF DATSTRUK1;
VAR IMAXFZ,IMINFZ,IFRLE,IFRGE,IFREQ,ICKLE,ICRGE,ICREB,LGE,I,J,ERRCODE,RECCODE,
    RECLGE,MJE,K:INTEGER;
VAR DATENINPUT:DATSATZ;
    DATENROW1:CHARFI;
    DATENROW2:CHARFI;
    DATENCOL1:CHARFI;
    DATENCOL2:CHARFI;
    DATENRHS1:CHARFI;
    DATENRHS2:CHARFI;
PROCEDURE DATLES(VAR DATREC:DATSATZ;VAR RECTYP,SATZLGE,ERRTYP:INTEGER);
(* EINLESEN EINES BELIEBIGEN SATZES DER PROBLEMDATEI *)
BEGIN
  GET(DATREC);
  (* UEBERPRUEFUNG, OB DATEI LEER *)
  IF EOF(DATREC)
    THEN BEGIN
      WRITELN(***ERROR 4 : RECORD TYPE #,RECTYP:1,# MISSING ***);
      ERRTYP := 1
      END
    (* UEBERPRUEFUNG, OB SATZTYP KORREKT *)
    ELSE IF RECTYP <> DATREC.SATZTYP
      THEN BEGIN
        WRITELN(***ERROR 5 : INCORRECT RECD TYPE ***);
        ERRTYP := 2
        END
      ELSE SATZLGE := DATREC.SATZLAENGE;
    END (* IF PROCEDURE DATLES *);
PROCEDURE ZIELFKT(VAR DATREC:DATSATZ;VAR ROW1,ROW2,COL1,COL2:CHARFI;
                  VAR LGE,LFNR,TYP:INTEGER);
VAR ZIEL,J,SCHL:INTEGER;WERT:REAL;ROWW:CHARAR;
(* VERARBEITUNG DER LFNR-TEN ZIELFUNKTION *)
(* SCHRITT 1 : EINTRAG IN ROW DATEIEN *)
(* UEBERPRUEFUNG, OB MAX-ZIELFUNKTION *)

```

```

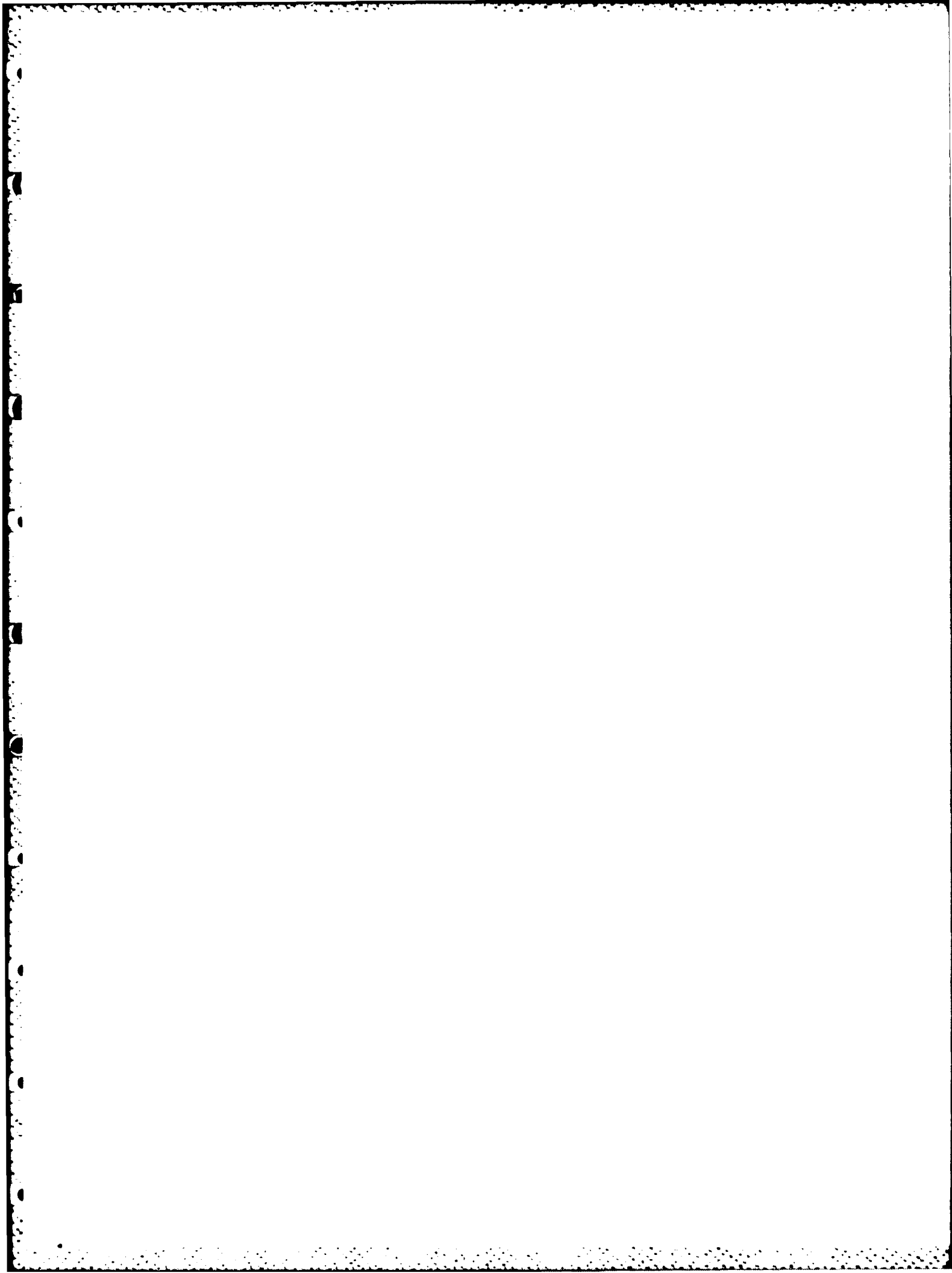
BEGIN
  ZIEL := ABS(LFNR - 533 * TYP);
  IF TYP = 2
    THEN ROW4 := ROWTYP1
    ELSE ROW4 := ROWTYP2;
  WRITELN(ROW1, #N #, ROW4:7, ZIEL:3);
  WRITELN(ROW2, #N #, ROW4:7, ZIEL:3);
(* SCHRITT2 : EINTRAG IN COL DATEIEN*)
  FOR J := 1 TO LGE CJ
    BEGIN
      SCHL := ABS(DATRECT * MAXCOEFFCJ, SPALTIND - 999);
      IF TYP = 3
        THEN WERT := -DATRECT * MAXCOEFFCJ, CDEFWERT
        ELSE WERT := DATRECT * MAXCOEFFCJ, CDEFWERT;
      WRITELN(CJL1, # #, COLTYP1:7, SCHL:3, ROW4:7, ZIEL:3, WERT:12:4);
      WRITELN(CJL2, # #, COLTYP1:7, SCHL:3, ROW4:7, ZIEL:3, WERT:12:4);
    END;
END (* OF PROCEDURE ZIELFKT *);
PROCEDURE FREST(VAR DATRECT: DATSATZ; VAR ROW1, ROW2, COL1, CJL2, RHS1, RHS2:
  CHARFI; LGE, LFNR, TYP: INTEGER);
  VAR ZIEL, HILF, J, SCHL: INIEGER; WERT: REAL; ROW4: CHARAK;
(* VERARBEITUNG DER LFNR-TEN FUZZY RESTRIKTION*)
(* SCHRITT1 : EINTRAG IN ROW DATEIEN*)
  BEGIN
    ZIEL := ABS(LFNR - 999);
    HILF := 111;
    CASE TYP OF 4: BEGIN
      WRITELN(ROW1, # L #, ROWTYP3:7, ZIEL:3);
      WRITELN(ROW2, # L #, ROWTYP3:7, ZIEL:3);
      ROW4 := ROWTYP3;
    END;
    5: BEGIN
      WRITELN(ROW1, # G #, ROWTYP4:7, ZIEL:3);
      WRITELN(ROW2, # G #, ROWTYP4:7, ZIEL:3);
      ROW4 := ROWTYP4;
    END;
    6: BEGIN
      WRITELN(ROW1, # E #, ROWTYP5:7, ZIEL:3);
      WRITELN(ROW2, # L #, ROWTYP3:6, #L#, ZIEL:3);
      WRITELN(ROW2, # G #, ROWTYP4:6, #G#, ZIEL:3);
    END;
  END;
(* SCHRITT2 : EINTRAG IN RHS DATEIEN*)
  CASE TYP OF 4: BEGIN
    WRITELN(RHS1, # #, RHSTYP1:7, HILF:3, ROWTYP3:7, ZIEL:3,
      DATRECT * FRLEBUQ:12:4);
    WRITELN(RHS2, # #, RHSTYP1:7, HILF:3, ROWTYP3:7, ZIEL:3,
      DATRECT * FRLEBUQ:12:4);
  END;
  5: BEGIN
    WRITELN(RHS1, # #, RHSTYP1:7, HILF:3, ROWTYP4:7, ZIEL:3,
      DATRECT * FRLEBUQ:12:4);
    WRITELN(RHS2, # #, RHSTYP1:7, HILF:3, ROWTYP4:7, ZIEL:3,
      DATRECT * FRLEBUQ:12:4);
  END;
  6: BEGIN
    WRITELN(RHS1, # #, RHSTYP1:7, HILF:3, ROWTYP5:7, ZIEL:3,
      DATRECT * FREQB:12:4);
    WRITELN(RHS2, # #, RHSTYP1:7, HILF:3, ROWTYP3:6, #L#,
      ZIEL:3, DATRECT * FREQB:12:4);
    WRITELN(RHS2, # #, RHSTYP1:7, HILF:3, ROWTYP4:6, #G#,
      ZIEL:3, DATRECT * FREQB:12:4);
  END;
END;
(* SCHRITT3 : EINTRAG IN CJL DATEIEN*)
  FOR J := 1 TO LGE CJ
    BEGIN

```

```

IF TYP = 6
THEN BEGIN
    SCHL := ABS(DATRECT.FREQCOEF[J].SPALTIND - 9);
    WERT := DATRECT.FREQCOEF[J].COEFWERT
    END
    ELSE BEGIN
    SCHL := ABS(DATRECT.FREQCOEF[J].SPALTIND - 999);
    WERT := DATRECT.FREQCOEF[J].COEFWERT
    END;
CASE TYP OF 4: BEGIN
    WRITELN(COL1,=      =,COLTYP1:7,SCHL:3,RJW4:7,ZIEL:3,WERT:12:4);
    WRITELN(COL2,=      =,COLTYP1:7,SCHL:3,RJW4:7,ZIEL:3,WERT:12:4)
    END;
5: BEGIN
    WRITELN(COL1,=      =,COLTYP1:7,SCHL:3,RJW4:7,ZIEL:3,WERT:12:4);
    WRITELN(COL2,=      =,COLTYP1:7,SCHL:3,RJW4:7,ZIEL:3,WERT:12:4)
    END;
6: BEGIN
    WRITELN(COL1,=      =,COLTYP1:7,SCHL:3,RJWTP5:7,ZIEL:3,WERT:12:4);
    WRITELN(COL2,=      =,COLTYP1:7,SCHL:3,RJWTP3:6,=L=,ZIEL:3,WERT:12:4);
    WRITELN(COL2,=      =,COLTYP1:7,SCHL:3,RJWTP4:6,=G=,ZIEL:3,WERT:12:4);
    END;
END;
END;
END (* JF PROCEDURE FREST *);
PROCEDURE CREST(VAR DATRECT:DATSATZ;VAR ROW1,ROW2,COL1,COL2,RHS1,RHS2:
    CHARFI;VAR _GE,LFNR,TYP:INTEGER);
VAR ZIEL,HILF,J,SCHL:INTEGER;WERT:REAL;ROWW:CHARAR;
(* VERARBEITUNG DER LFNR-TEN CRISP RESTRIKTION*)
(* SCHRITT1 : EINTRAG IN ROW DATEIEN*)
BEGIN
    ZIEL := ABS(LFNR - 999);
    HILF:=111;
    CASE TYP OF 7: BEGIN
        WRITELN(ROW1,= L      =,ROWTYP6:7,ZIEL:3);
        WRITELN(ROW2,= L      =,ROWTYP6:7,ZIEL:3);
        RJW4 := ROWTYP6;
        END;
8: BEGIN
        WRITELN(ROW1,= G      =,ROWTYP7:7,ZIEL:3);
        WRITELN(ROW2,= G      =,ROWTYP7:7,ZIEL:3);
        RJW4 := RJWTP7
        END;
9: BEGIN
        WRITELN(ROW1,= E      =,ROWTYP8:7,ZIEL:3);
        WRITELN(ROW2,= E      =,ROWTYP8:7,ZIEL:3);
        RJW4 := RJWTP8
        END;
END;
END;
END (* SCHRITT2 : EINTRAG IN RHS DATEIEN*)
CASE TYP OF 7: BEGIN
    WRITELN(RHS1,=      =,RHSTYP1:7,HILF:3,RJWTP6:7,ZIEL:3,
        DATRECT.CRLEB:12:4);
    WRITELN(RHS2,=      =,RHSTYP1:7,HILF:3,RJWTP6:7,ZIEL:3,
        DATRECT.CRLEB:12:4);
    END;
8: BEGIN
    WRITELN(RHS1,=      =,RHSTYP1:7,HILF:3,RJWTP7:7,ZIEL:3,
        DATRECT.CRGE8:12:4);
    WRITELN(RHS2,=      =,RHSTYP1:7,HILF:3,RJWTP7:7,ZIEL:3,
        DATRECT.CRGE8:12:4);
    END;
9: BEGIN
    WRITELN(RHS1,=      =,RHSTYP1:7,HILF:3,RJWTP8:7,ZIEL:3,
        DATRECT.CREQ8:12:4);
    WRITELN(RHS2,=      =,RHSTYP1:7,HILF:3,RJWTP8:7,
        ZIEL:3,DATRECT.CREQ8:12:4);
    END;
END;

```



```

END;
(* SCHRITT 3 : EINTRAG IN COI DATEIEN*)
FOR J := 1 TO LGE DO
  BEGIN
    SCHL := ABS(DATREC*.CRLECOEFF(J).SPALTIND - 999);
    WERT := DATREC*.CRLECOEFF(J).COEFWERT;
    CASE TYP OF 7: BEGIN
      WRITELN(COI1,=      =,COLTYP1:7,SCHL:3,ROWW:7,ZIEL:3,WERT:12:4);
      WRITELN(COI2,=      =,COLTYP1:7,SCHL:3,ROWW:7,ZIEL:3,WERT:12:4);
    END;
    8: BEGIN
      WRITELN(COI1,=      =,COLTYP1:7,SCHL:3,ROWW:7,ZIEL:3,WERT:12:4);
      WRITELN(COI2,=      =,COLTYP1:7,SCHL:3,ROWW:7,ZIEL:3,WERT:12:4);
    END;
    9: BEGIN
      WRITELN(COI1,=      =,COLTYP1:7,SCHL:3,ROWW:7,ZIEL:3,WERT:12:4);
      WRITELN(COI2,=      =,COLTYP1:7,SCHL:3,ROWW:7,ZIEL:3,WERT:12:4);
    END;
  END;
END;
END (* OF PROCEDURE CREST *);
BEGIN
  (* VORBESETZUNG VON VARIABLEN*)
  ERRCODE := 0;
  (* EINLESEN DES ERSTEN DATENSATZES DER PROBLEMDATEI *)
  RESET(DATENINPUT);
  (* UEBERPRUEFUNG, OB DATEI LEER *)
  IF EOF(DATENINPUT)
    THEN WRITELN(***ERROR 1 : NO SOURCE DECK ***);
  ELSE BEGIN
    (* UEBERPRUEFUNG, OB SATZTYP 1 VORHANDEN *)
    IF DATENINPUT*.SATZTYP <> 1
      THEN WRITELN(***ERROR 2 : INCORRECT FILE STRUCTURE ***);
    ELSE BEGIN
      (* UEBERPRUEFUNG, OB SATZTYP 1 KORREKT *)
      IF DATENINPUT*.SATZLAENGE <> 10
        THEN WRITELN(***ERROR 3 : INCORRECT RECORD =,
          =STRUCTURE ***);
      ELSE BEGIN
        (* UEBERNAHME PROBLEMCHARACTERISIERUNG *)
        IMAXFZ:=DATENINPUT*.MAXFZ;
        IMINFZ:=DATENINPUT*.MINFZ;
        IFRLE:=DATENINPUT*.FRLE;
        IFRGE:=DATENINPUT*.FRGE;
        IFRJ1:=DATENINPUT*.FRJ1;
        ICRLE:=DATENINPUT*.CRLE;
        ICRGE:=DATENINPUT*.CRGE;
        ICRJ1:=DATENINPUT*.CRJ1;
        (*INITIALISIERUNG DER ROW DATEIEN*)
        WRITELN(DATENROW1,=NAME=,BLANK10:10,=MINRESTRIK=);
        WRITELN(DATENROW1,=RJWS=);
        WRITELN(DATENROW2,=NAME=,BLANK10:10,=MAXRESTRIK=);
        WRITELN(DATENROW2,=RJWS=);
        (*ERZEUGUNG DER LINEARKOMBINATION*)
        WRITE(DATENROW1,=*DN =);
        WRITE(DATENROW2,=*DN =);
        FOR I := 1 TO IMAXFZ DO BEGIN
          J:=ABS(I-333*2);
          WRITE(DATENROW1,=GJALKOMBINE,ROWTYP1:7,J:3,=1.0=);
          WRITELN(DATENROW1);
          WRITE(DATENROW1,=*X =);
          WRITE(DATENROW2,=GJALKOMBINE,ROWTYP1:7,J:3,=1.0=);
          WRITELN(DATENROW2);
          WRITE(DATENROW2,=*X =);
        END;
        FOR I := 1 TO IMINFZ DO BEGIN
          J:=ABS(I-333*3);

```



```

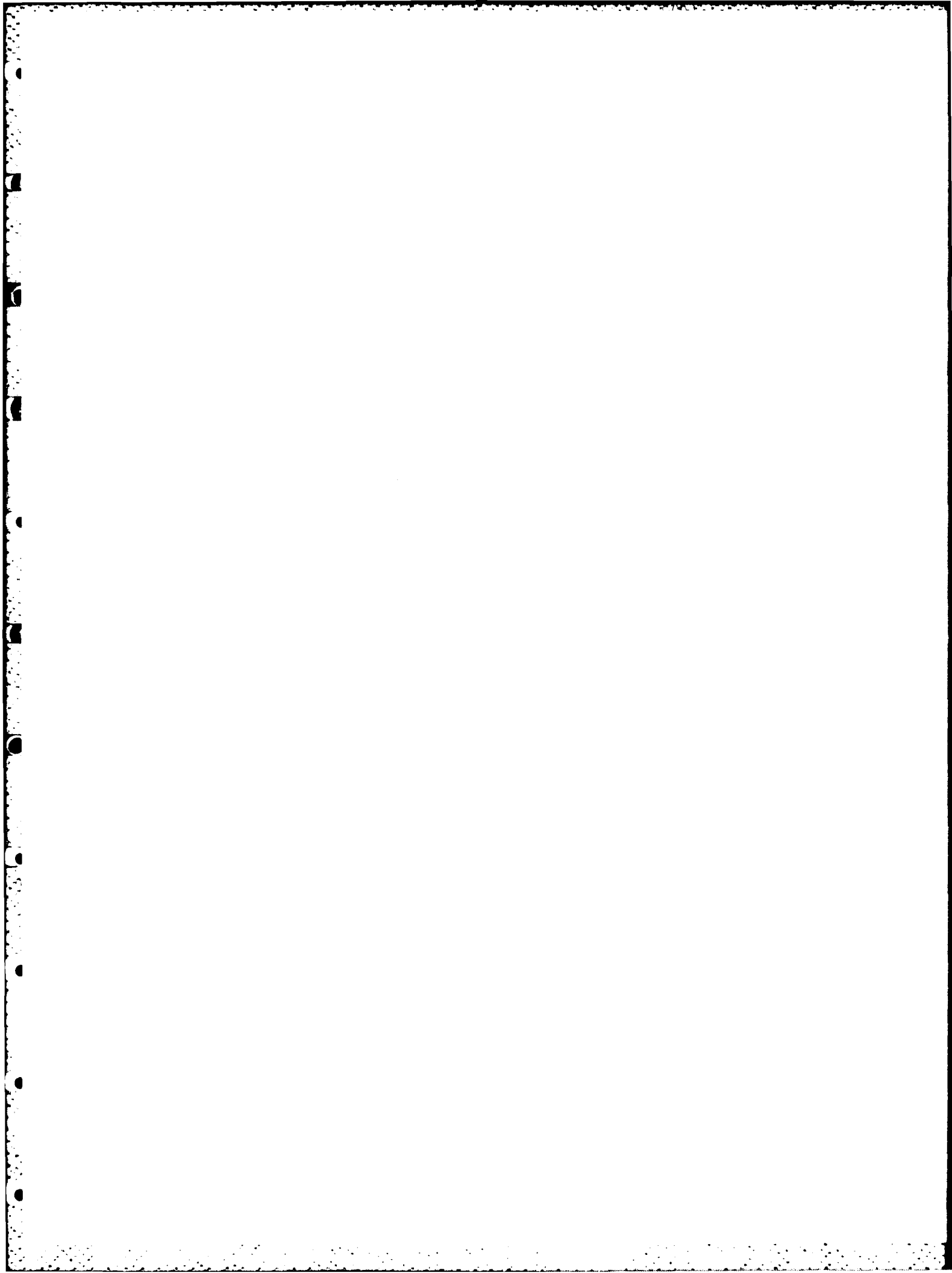
(*EINLESEN DATENSATZ*)
IF ERRCODE = 0
  THEN BEGIN
    DATLES(DATENINPUT,RECCODE,RECLGE,ERRCODE);
    (*ABFRAGE, OB DATEI FEHLERFREI GELESEN*)
    IF ERRCODE = 0
      THEN BEGIN
        K:=DATENINPUT+.SATZLAENGE;
        PREST(DATENINPUT,DATENROW1,DATENROW2,
              DATENCOL1,DATENCOL2,DATENRHS1,DATENRHS2,
              <I,RECCODE);
        END;
      END;
    END;
  END;
END;

(*VERARBEITUNG PROBLEMDATEI-SAETZE TYP 6 *)
RECCODE:=6;
FOR I:=1 TO IFREI DO
  BEGIN
    (*EINLESEN DATENSATZ*)
    IF ERRCODE = 0
      THEN BEGIN
        DATLES(DATENINPUT,RECCODE,RECLGE,ERRCODE);
        (*ABFRAGE, OB DATEI FEHLERFREI GELESEN*)
        IF ERRCODE = 0
          THEN BEGIN
            K:=DATENINPUT+.SATZLAENGE;
            PREST(DATENINPUT,DATENROW1,DATENROW2,
                  DATENCOL1,DATENCOL2,DATENRHS1,DATENRHS2,
                  <I,RECCODE);
            END;
          END;
        END;
      END;
    END;
  END;
END;

(*VERARBEITUNG PROBLEMDATEI-SAETZE TYP 7 *)
RECCODE:=7;
FOR I:=1 TO ICRLE DO
  BEGIN
    (*EINLESEN DATENSATZ*)
    IF ERRCODE = 0
      THEN BEGIN
        DATLES(DATENINPUT,RECCODE,RECLGE,ERRCODE);
        (*ABFRAGE, OB DATEI FEHLERFREI GELESEN*)
        IF ERRCODE = 0
          THEN BEGIN
            K:=DATENINPUT+.SATZLAENGE;
            PREST(DATENINPUT,DATENROW1,DATENROW2,
                  DATENCOL1,DATENCOL2,DATENRHS1,DATENRHS2,
                  <I,RECCODE);
            END;
          END;
        END;
      END;
    END;
  END;
END;

(*VERARBEITUNG PROBLEMDATEI-SAETZE TYP 8 *)
RECCODE:=8;
FOR I:=1 TO ICRGE DO
  BEGIN
    (*EINLESEN DATENSATZ*)
    IF ERRCODE = 0
      THEN BEGIN
        DATLES(DATENINPUT,RECCODE,RECLGE,ERRCODE);
        (*ABFRAGE, OB DATEI FEHLERFREI GELESEN*)
        IF ERRCODE = 0
          THEN BEGIN
            K:=DATENINPUT+.SATZLAENGE;
            PREST(DATENINPUT,DATENROW1,DATENROW2,
                  DATENCOL1,DATENCOL2,DATENRHS1,DATENRHS2,
                  <I,RECCODE);
            END;
          END;
        END;
      END;
    END;
  END;
END;

```



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      END;
END;
(*VERARBEITUNG PROBLEM)DATEI-SAETZE TYP 9 *)
RECCODE:=9;
FOR I:=1 TO (CRE) DO
  BEGIN
    (*EINLESEN DATENSATZ*)
    IF ERRCODE = 0
      THEN BEGIN
        DATLES(DATENINPUT,RECCODE,RECLGE,ERRCODE);
        (*ABFRAGE, OB DATEI FEHLERFREI GELESEN*)
        IF ERRCODE = 0
          THEN BEGIN
            K:=DATENINPUT*.SATZLAENGE;
            CREST(DATENINPUT,DATENROW1,DATENROW2,
              DATENCOL1,DATENCOL2,DATENRHS1,DATENRHS2,
              <,I,RECCODE);
          END;
        END;
      END;
    END;
  END;
  (* ABSCHLUSS DER DATEIEN *)
  WRITELN(DATENROW1,=COLUMNS);
  WRITELN(DATENROW2,=COLUMNS);
  WRITELN(DATENKHS1,=ENDATA);
  WRITELN(DATENRHS2,=ENDATA);
  END;
END;
END (* JF PROGRAM EINZELLP*);

```

END

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